

# Pattern Formations with a Zooplankton:

Experiment and Theory

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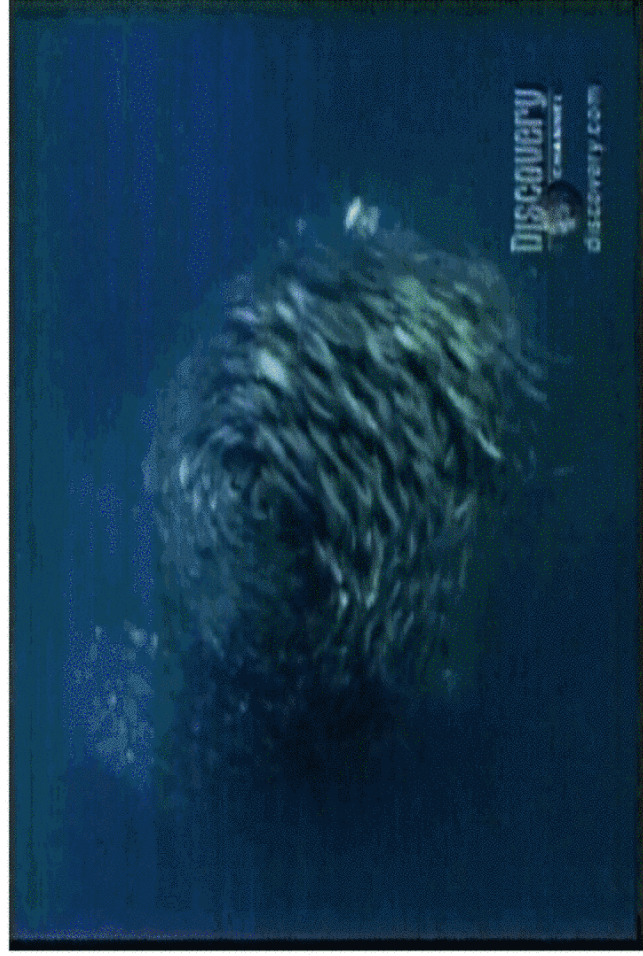
Support:

US Office of Naval Research

Alexander von Humboldt Foundation

Motivation:

Vortex-swarming of 'self-propelled' animals



## Outline

- ❖ The Active Brownian Particle (ABP) Theory – Erdmann, Ebeling, Schweitzer – Humboldt University Berlin
- ❖ Single (few) Particle Motions & Bifurcations
- ❖ About *Daphnia* – the experiment
- ❖ Random Walk Theory - Measures and Results
- ❖ Symmetry Breaking – Vortex motion
- ❖ Simulation using RWT
- ❖ Summary

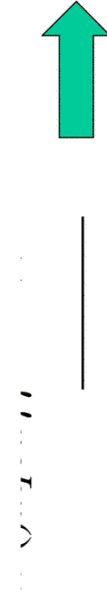
Active Brownian Particle (ABP) with internal energy depot  
 [Schweitzer et al., PRL **80**, 5044 (1998)]

$$\dot{e} = -\gamma_0 e + q - d_2 \nabla^2 e$$

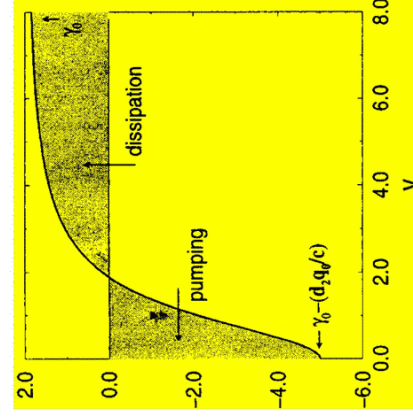
Energy depot: space-dependent take-up  $q(\mathbf{r})$ , internal dissipation  $c e(t)$ , conversion of internal energy into kinetic energy  $d_2 e(t) \nabla^2$

$$\dot{v} = \gamma_0 v + q - d_2 \nabla^2 v$$

(For uniform distr:  $q(\mathbf{r}) = q_0$ )



A velocity dependent dissipation

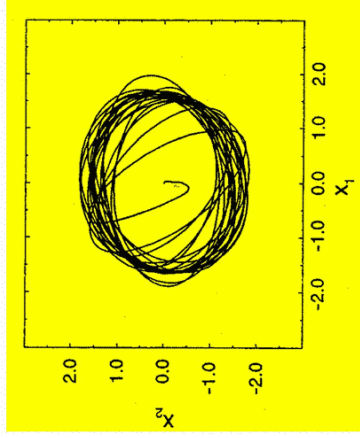
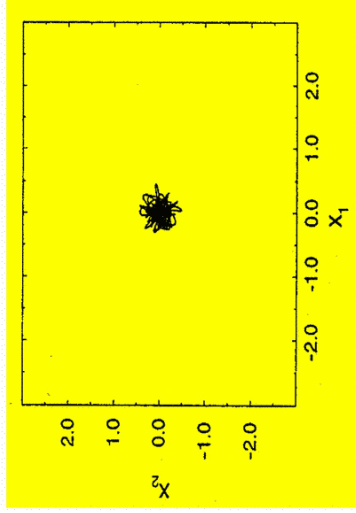


## Hopf bifurcation:

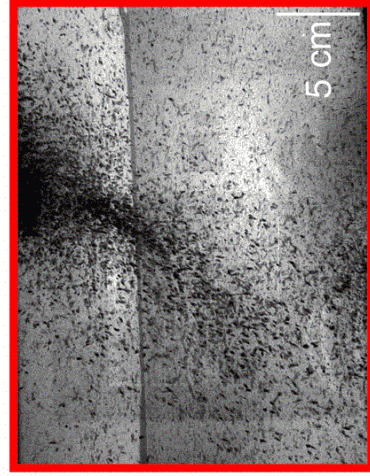
Fixed point  $\rightarrow$  limit cycle pair

.....

Bifurcation parameter: ———

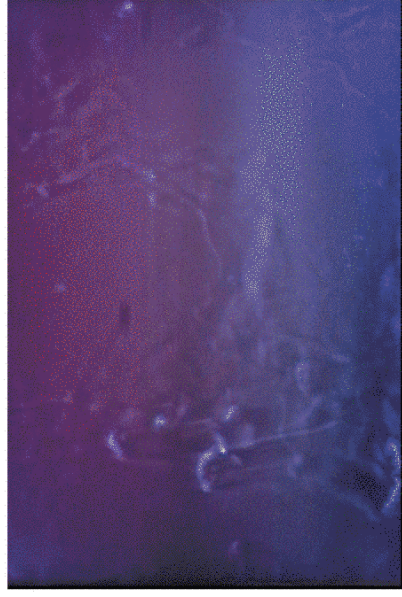


## *Daphnia* make vortices



Side view of vortex-swarming zooplankton *Daphnia* in our lab. Picture by D.F. Russell.  $\uparrow$

Schlieren technique movie of *Daphnia* motion by Ai Nihongi and Rudi Strickler.  $\rightarrow$



## About *Daphnia*

*Daphnia magna*, common “water flea”.

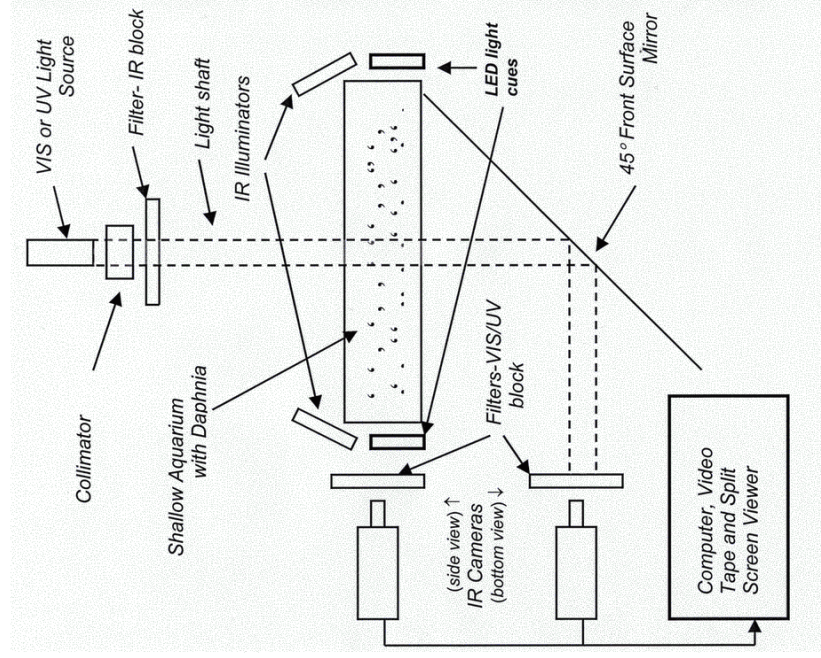
They are:

- ❖ Attracted to visible light (VIS)
- ❖ Repelled by ultra violet (not used here)
- ❖ Blind to infra red (IR)

Record their motions using IR and manipulate motions using VIS

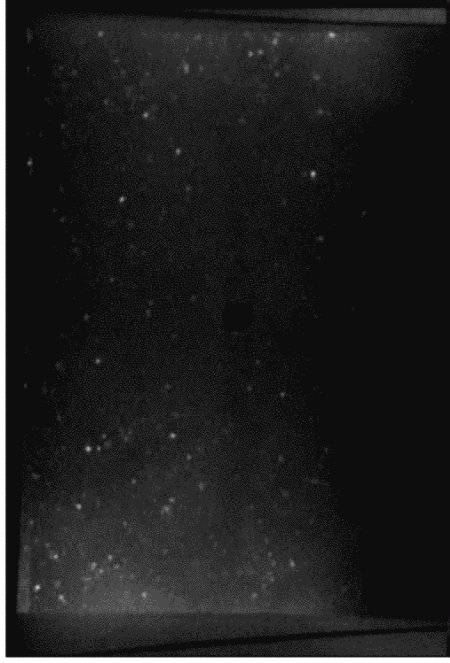
## Apparatus

- ❖ Side and bottom views recorded simultaneously
- ❖ VIS light shaft is the cue
- ❖ Illumination and recording in IR

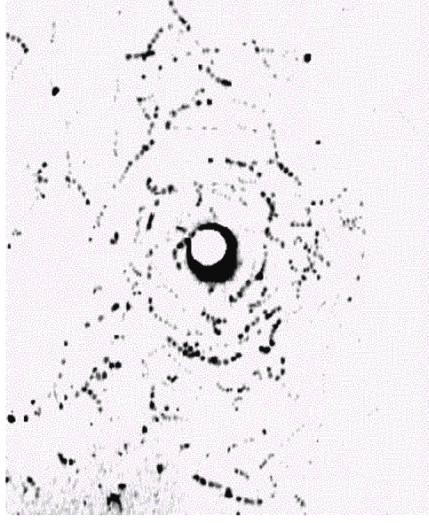


## Example Recordings

About 40 animals, approximately equal numbers circling in opposite directions

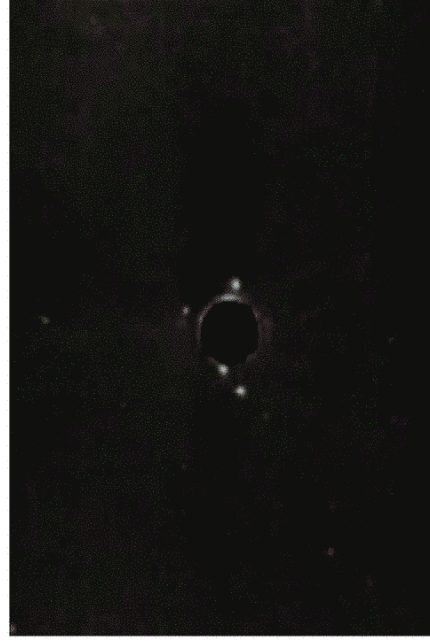


Bottom view of a few *Daphnia* moving around light shaft (radius  $r = 5\text{mm}$ ).  
Movie is speeded up 4 times.

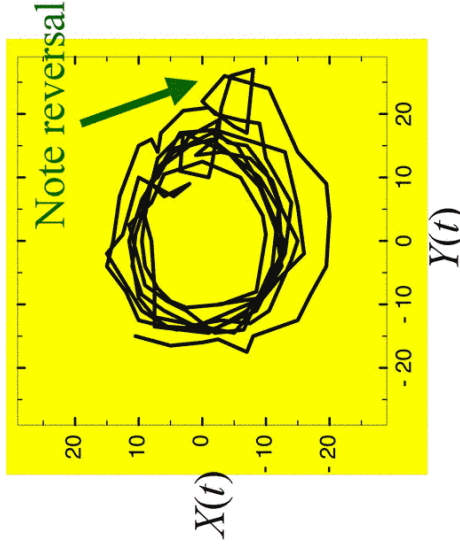


Five successive positions of *Daphnia* taken in intervals of 0.3s (black/white inverted).

## Observation of a single *Daphnia*



Bottom view of individual *Daphnia* moving around light shaft. Movie is speeded up 3 times.

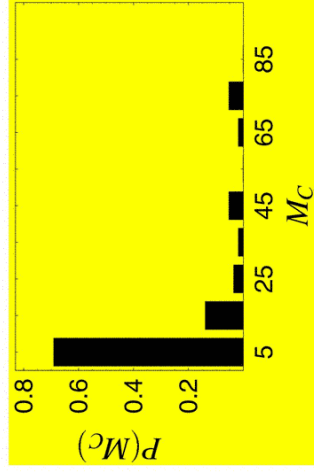
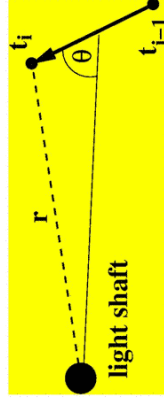
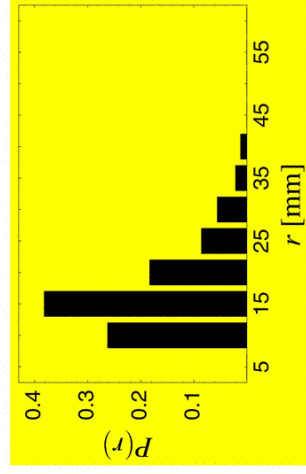
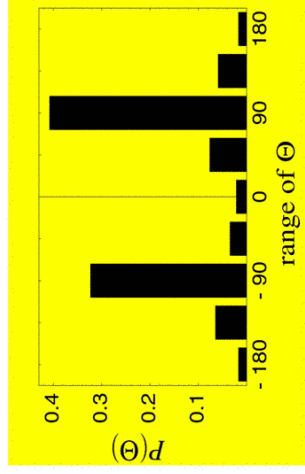


Track of one *Daphnia* individually circling horizontally around light shaft (146s).

**Single *Daphnia* circle individually in both directions around light shaft, frequently changing direction**

## How to characterize observed circular motion?

- $M=624$  moves from 4 different animals
- Average speed  $v_{\text{avg}} = 5.71 \pm 1.35$  mm/s



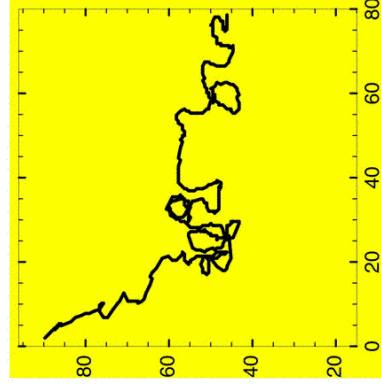
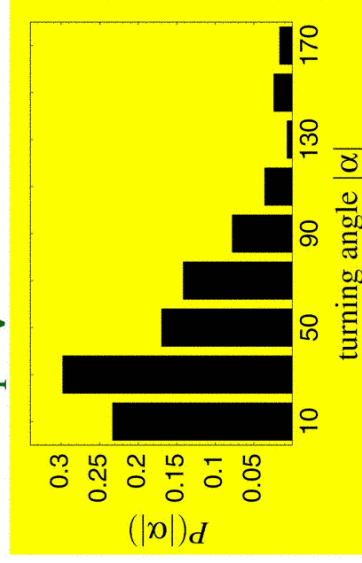
$M_C$  = Number of successive moves before changing direction (CCW vvs CW).  $\langle M_C \rangle = 11.8$

## Random Walk Theory - but need

Motion of single *Daphnia* in the dark.

1599 moves from 8 different animals  
 Example track, 200 hops  $\rightarrow$

Distribution of turning angles,  
 $\alpha$  = directional change after each hop  $\downarrow$



X

Y

$P(\alpha)$  symmetric about  $0^\circ$ .  $\langle |\alpha| \rangle \approx 35^\circ$

(Similar to oceanic copepods)

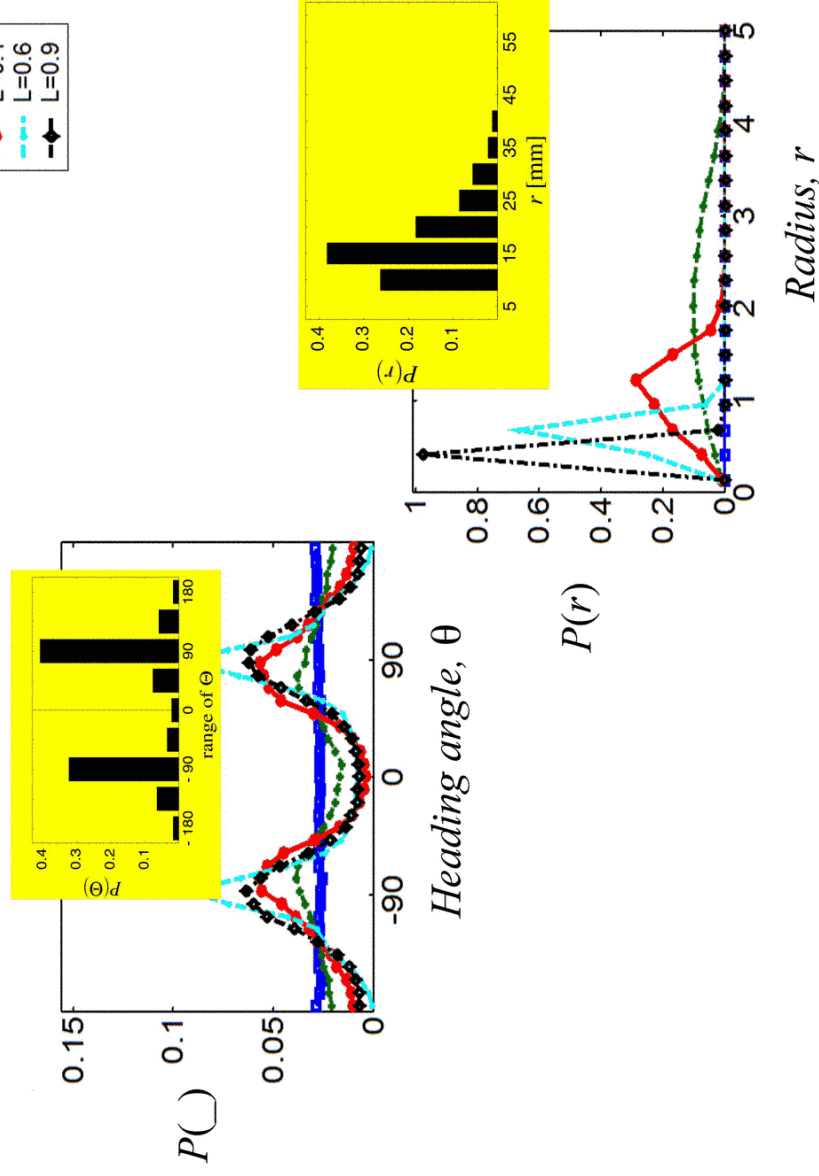
## Random Walk Theory

- \* Short range temporal correlation
- \* Attraction to light

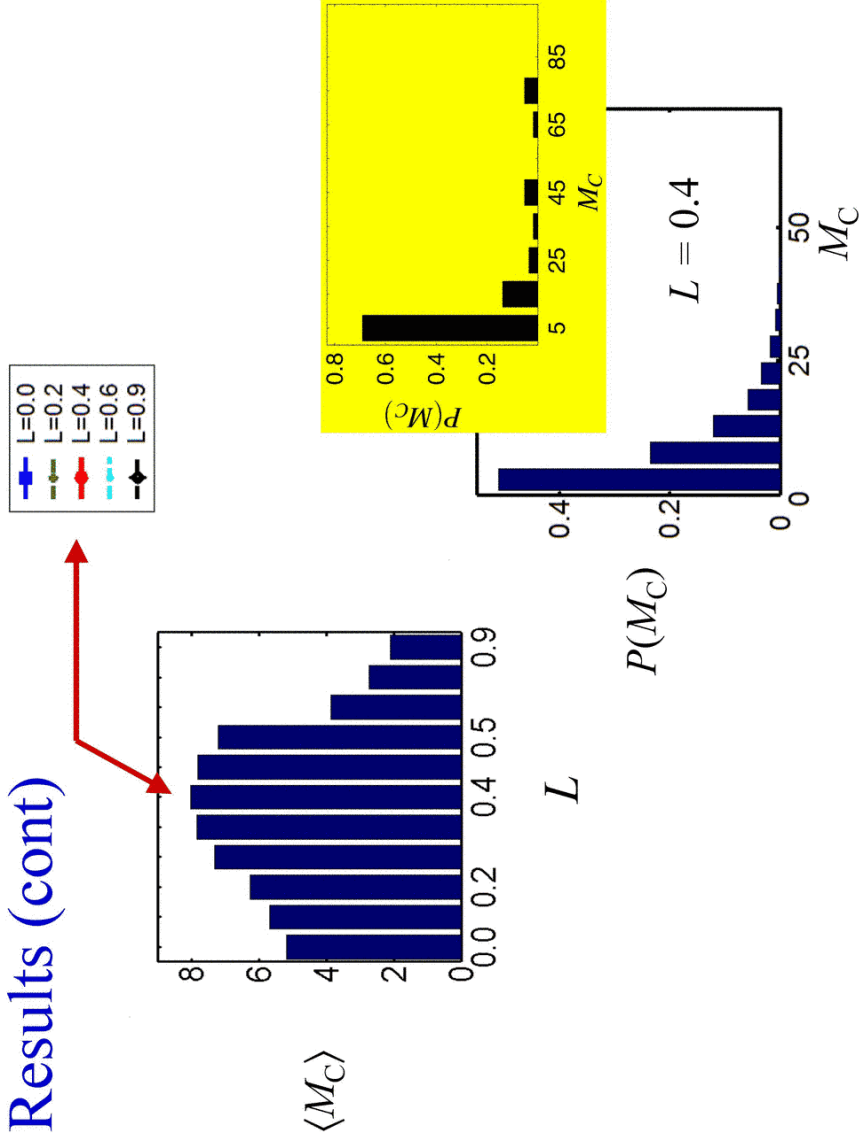
❖ *Daphnia* in darkness: At the end of each step, the direction of next time step at  $t_{i+1}$  is randomly chosen from observed distribution of turning angle (DTA)

❖ *Daphnia* in light field: At the end of each time step, the direction is again chosen from the DTA, but an additional kick of strength  $r * L / (L - 1)$  towards the light (parabolic potential) is added and the final heading is rescaled to unit length. [ $0 \leq L < 1$ ]

## Results of the Simulation for various $L$ :

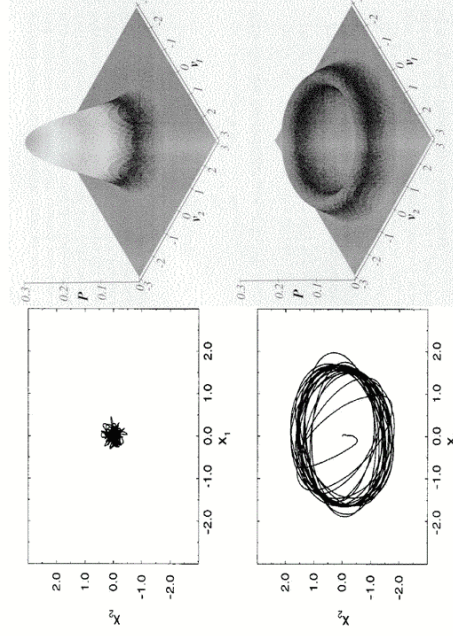


## Results (cont)



## Many Particle Generalizations - ABP (Humboldt)

Particle-Particle attractive interaction  $\rightarrow$   
 Mean field potential (ABP) and probability densities of the limit cycle motions.  
 Symmetric pair of limit cycles.

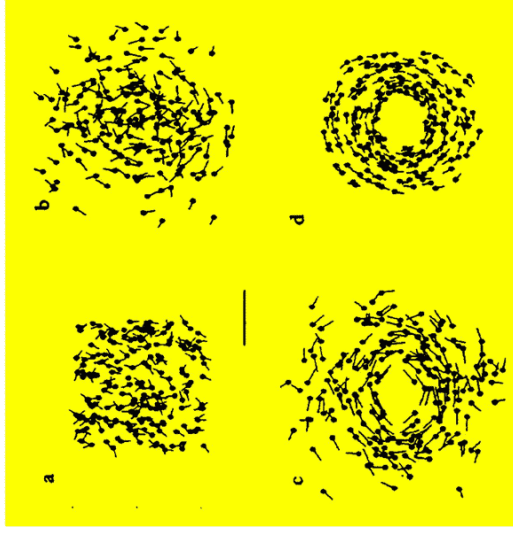


Interacting Active Brownian Particles [Schweitzer *et al.*, PRE **64**, 021110 (2001); Ebeling and Schweitzer, Theory Biosci. **120**, 20 (2001); Erdmann *et al.*, PRE **65**, 061106 (2002)]



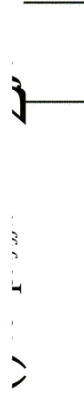
## Many Particle Generalizations – Levine $\Rightarrow$

Short range repulsion and long range attraction added to the model of Self-Propelled Interacting Particles [Levine *et al.*, PRE **63**, 017101 (2001)]



Self propelling force,  $v$   
(no alignment)

Self propelling force, (with alignment – range  $l_c$ )



## Transition to Vortex Motion by a

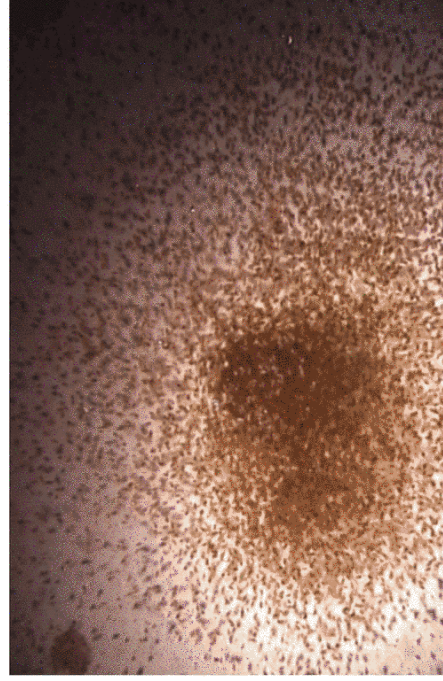
### *Daphnia* Swarm

**Models:** Symmetry of limit cycles must be broken.

Velocity alignment; Avoidance

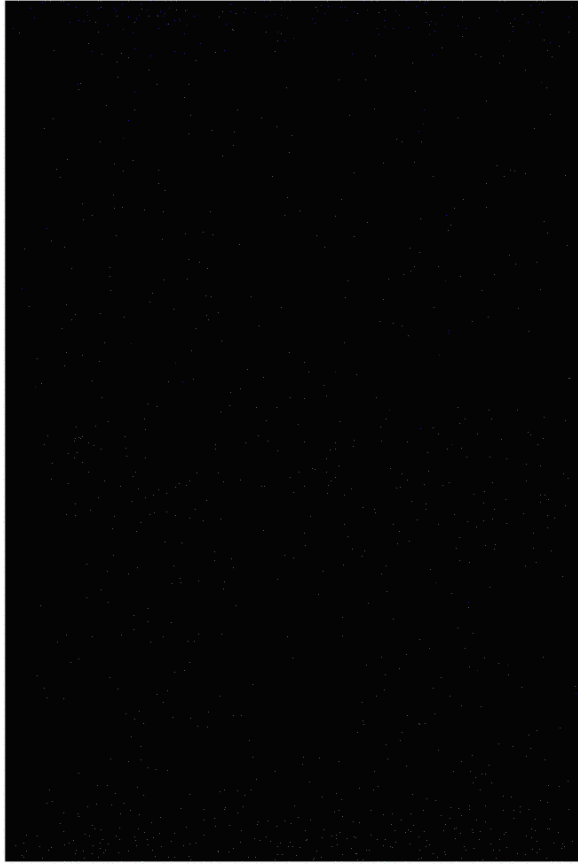
***Daphnia* experiment:** hydrodynamic coupling likely

(for birds and fish the alignment is visual with neighbors)



CCW Motion  
and spiral arms

## Another example



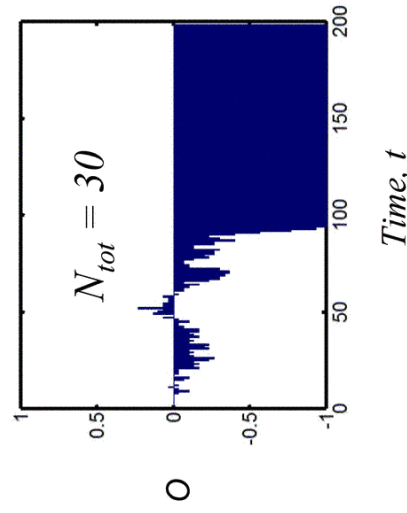
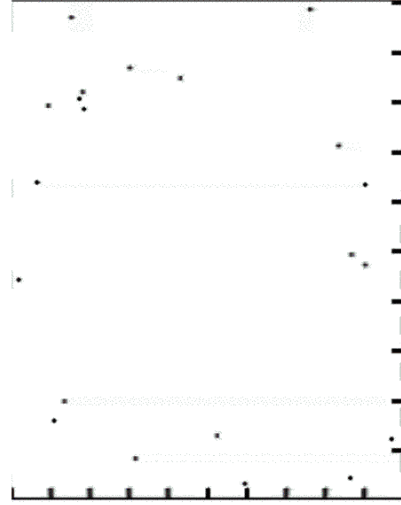
CW Motion  
(after a time  
delay)

## RWT Simulation of the transition:

### Interacting RW with DTA

- Simple model for (vortex-) swarming *Daphnia*  
Indirect inter-agent interactions via water drag are incorporated by adding 'alignment' or 'water drag' kick proportional to:

A local order parameter:



Global order parameter:

$$O = (N_{CW} - N_{CCW})/N_{tot}$$

## Conclusions

Theory predicts four motions:

- ❖ Noisy fixed point
- ❖ Symmetric pair of limit cycles
- ❖ Swarming
- ❖ Transition to vortex

All four motions can be observed in experiments with *Daphnia*

## Discussion

What are the minimum ingredients that lead to these motions?

A. Few animal (low density) experiments:

- ❖ Self-propelled particles (finite non-zero velocity)
- ❖ Assigned preference to move in 'forward' direction
- ❖ Confinement, arising from Attraction (either as mean field potential from interagent interactions or as external attractive potential)

B. Large animal density experiments:

- ❖ In addition to the above – a symmetry breaking (velocity alignment) mechanism.