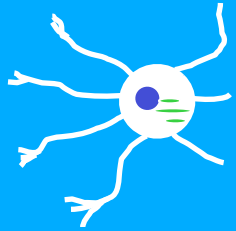
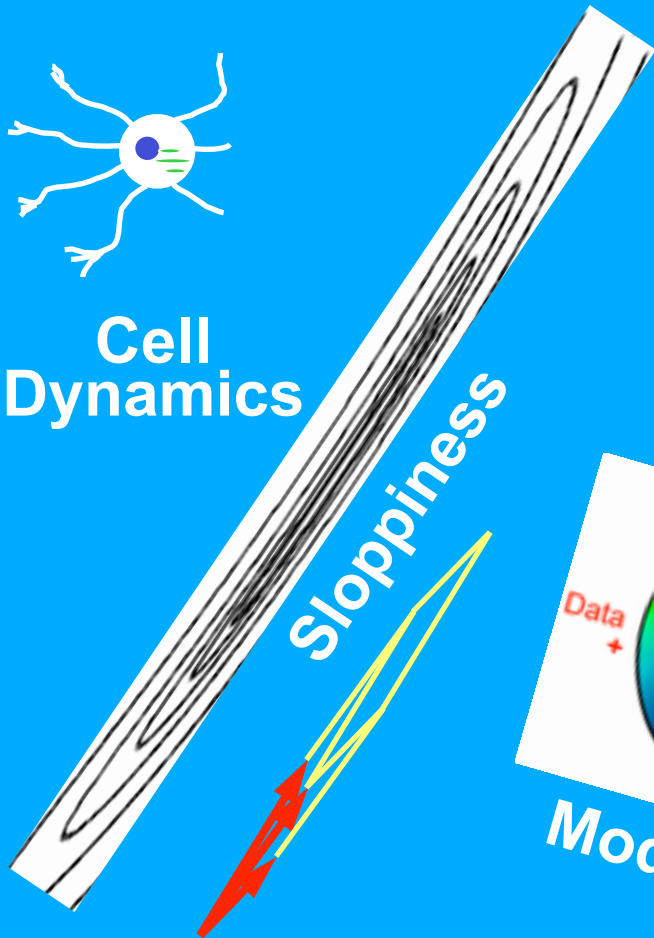


# 'Sloppy Model' Nonlinear Fits: Signal Transduction to Differential Geometry

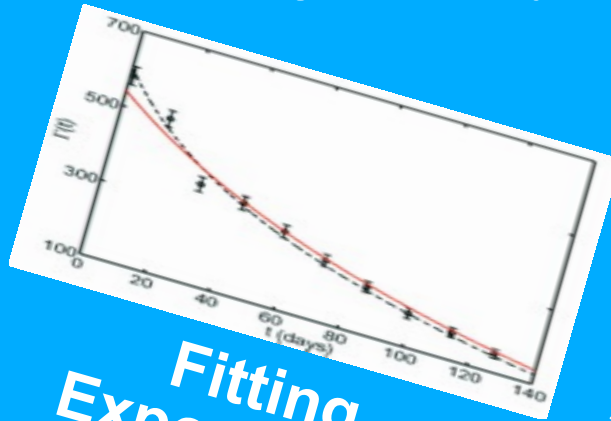
JPS, Mark Transtrum, Ben Machta, Ricky Chachra, Lorien Hayden, Alex Alemi, Isabel Kloumann, Colin Clement, Kevin Brown, Ryan Gutenkunst, Josh Waterfall, Paul Ginsparg, Chris Myers, ...



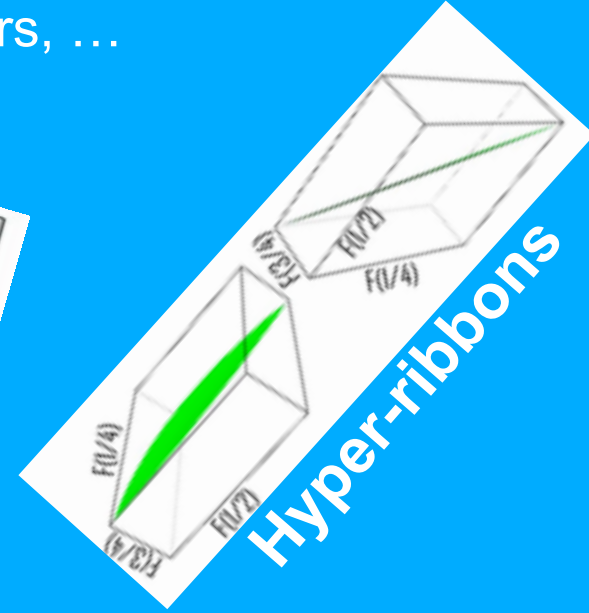
Cell Dynamics



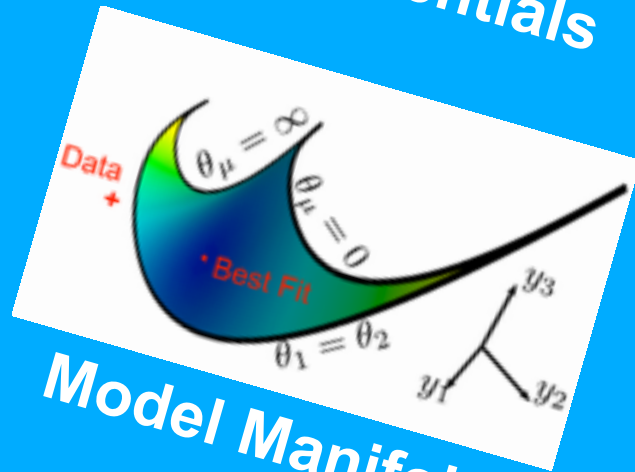
Sloppiness



Fitting Exponentials

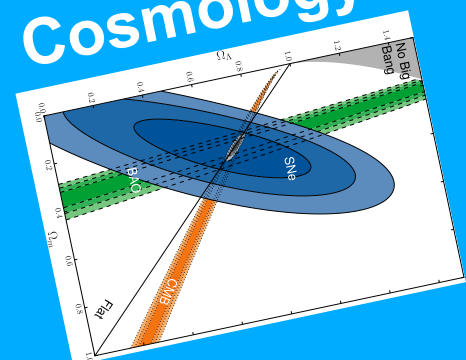


Hyper-ribbons



Model Manifold

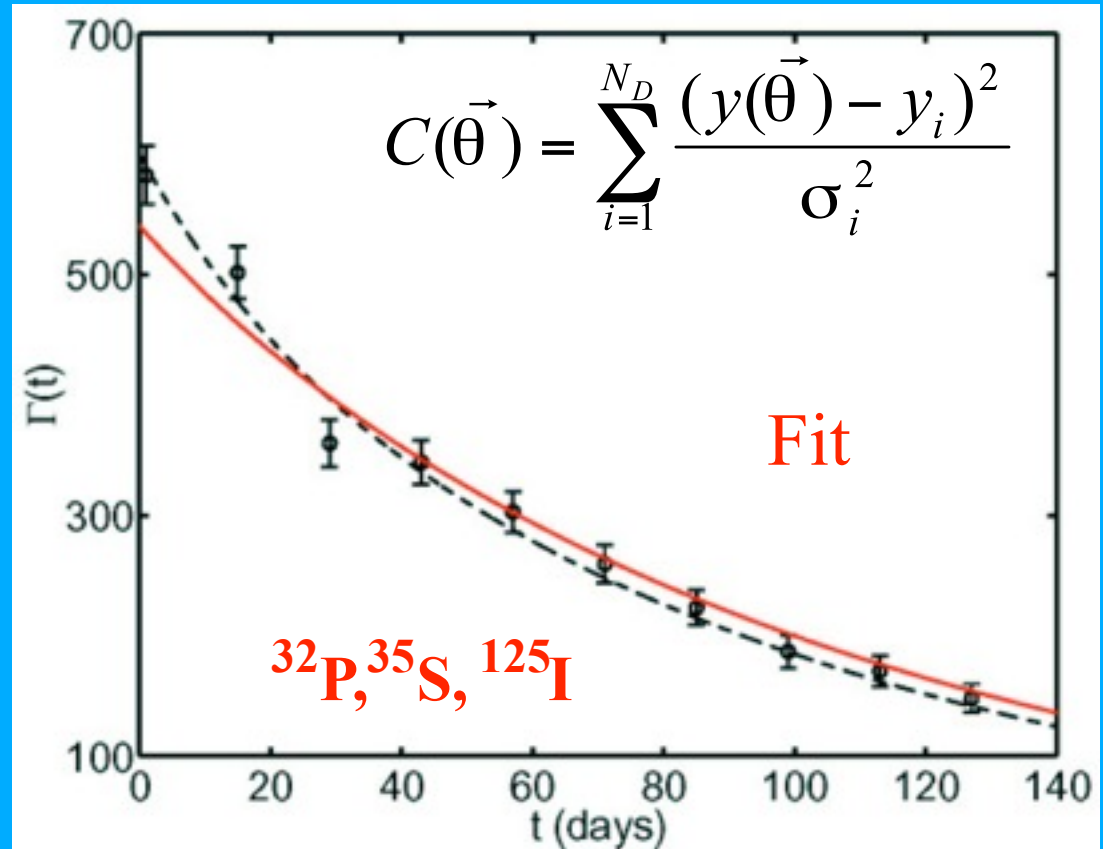
Cosmology



# Fitting Decaying Exponentials

Classic ill-posed  
inverse problem

Given Geiger counter  
measurements from a  
radioactive pile, can we  
recover the identity of  
the elements and/or  
predict future  
radioactivity? Good fits  
with bad decay rates!



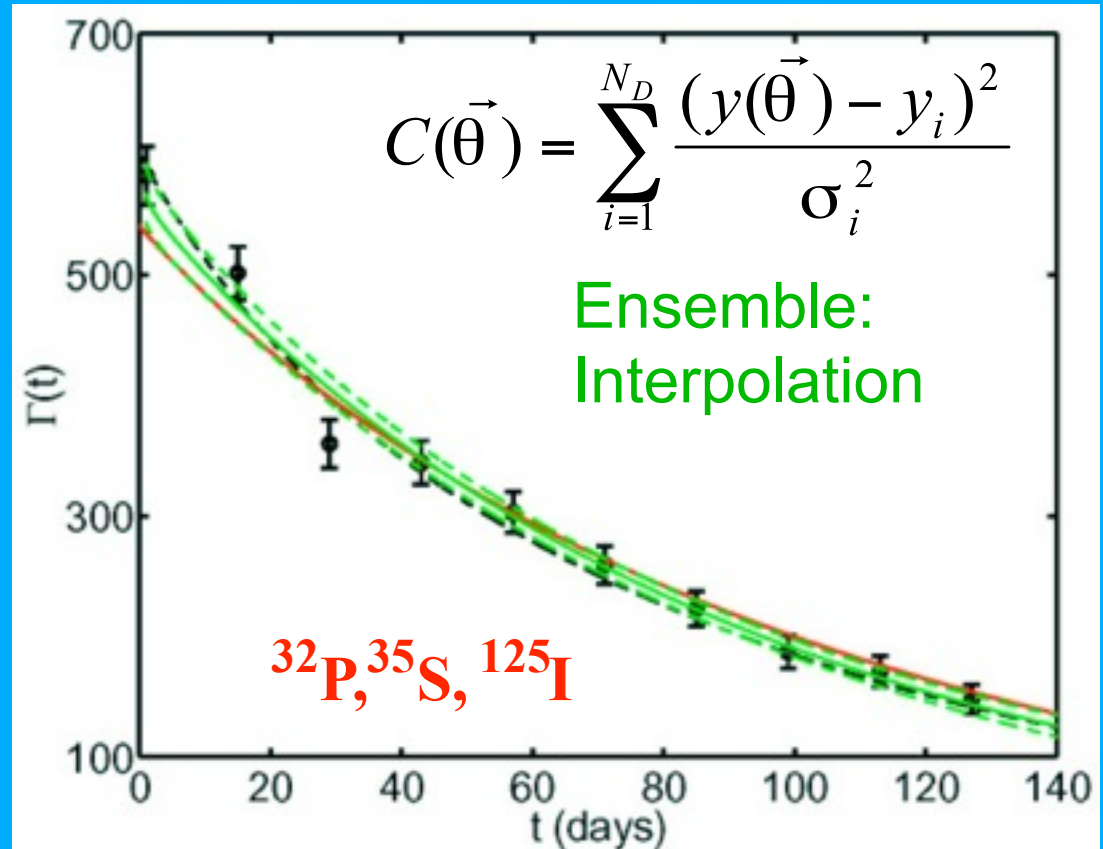
$$y(\mathbf{A}, \boldsymbol{\gamma}, t) = A_1 e^{-\gamma_1 t} + A_2 e^{-\gamma_2 t} + A_3 e^{-\gamma_3 t}$$

6 Parameter Fit

# Fitting Decaying Exponentials

Classic ill-posed  
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measurements from a  
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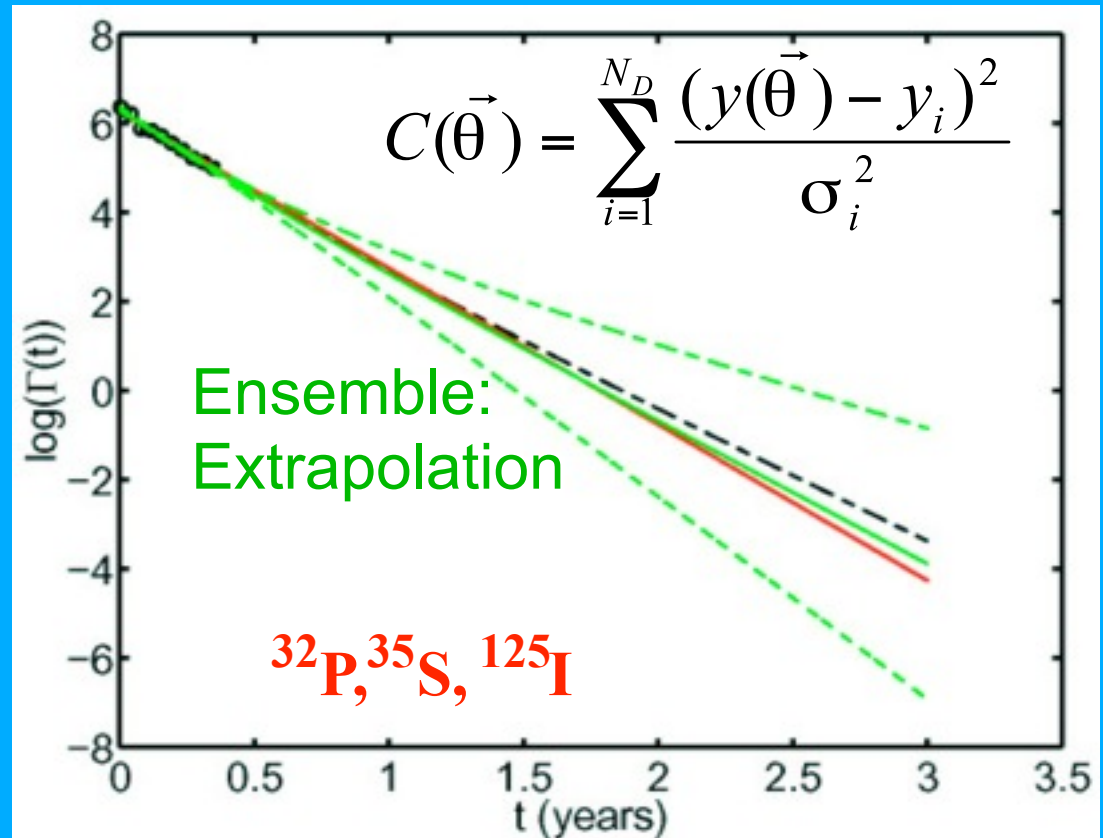
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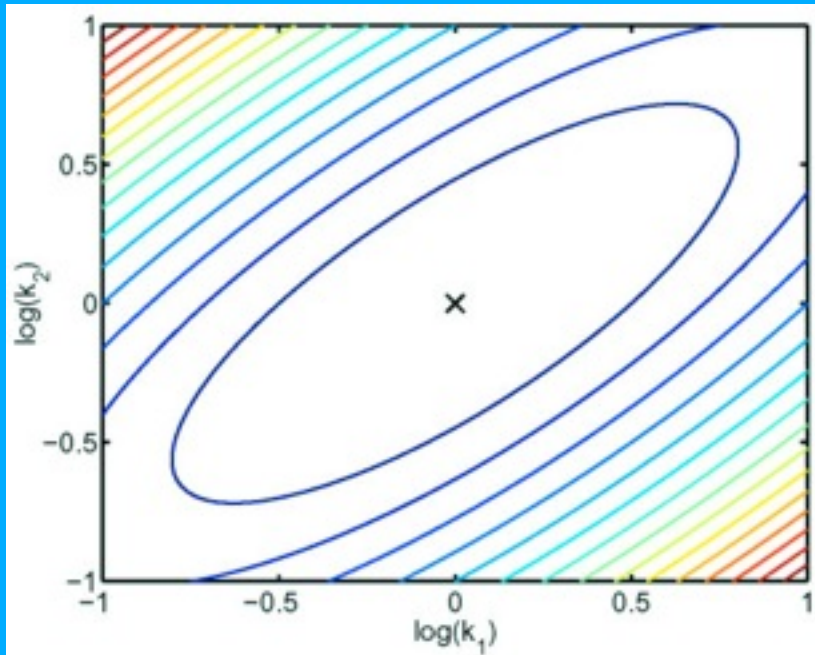
6 Parameter Fit

# Ensemble of Models

Kevin Brown

We want to consider not just minimum cost fits, but all parameter sets consistent with the available data. New level of abstraction: *statistical mechanics in model space*.

*Don't trust predictions that vary*



Cost is least-squares fit

$$C(\vec{\theta}) = \frac{1}{2} \sum_{i=1}^{N_D} \frac{(y(\vec{\theta}) - y_i)^2}{\sigma_i^2}$$

Boltzmann weights  $\exp(-C/T)$



$$H_{ij} = \partial^2 C / \partial \theta_i \partial \theta_j$$

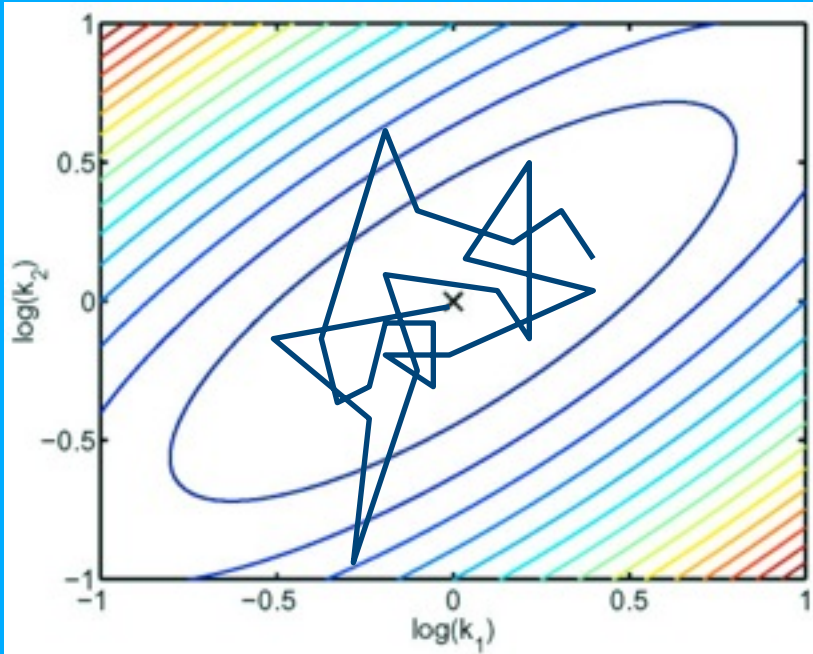
O is chemical concentration  $y(t_i)$ , or rate constant  $\theta_n \dots$

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$$\langle O \rangle = \frac{1}{N_E} \sum_{i=1}^{N_E} O(\vec{\theta}_i)$$

$$\sigma_O^2 = \langle O^2(\vec{\theta}) \rangle - \langle O(\vec{\theta}) \rangle^2$$

$O$  is chemical concentration  $y(t_i)$ , or rate constant  $\theta_n \dots$

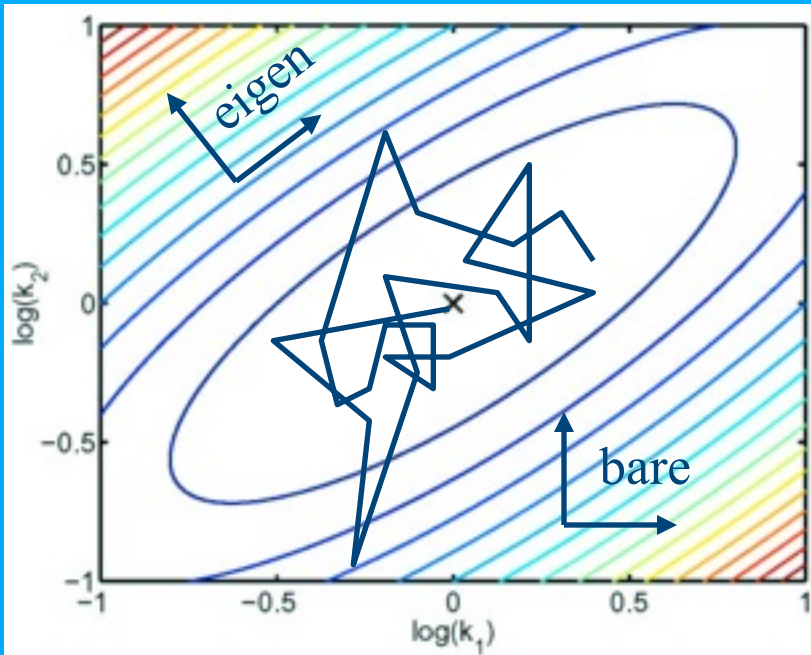
$$H_{ij} = \partial^2 C / \partial \theta_i \partial \theta_j$$

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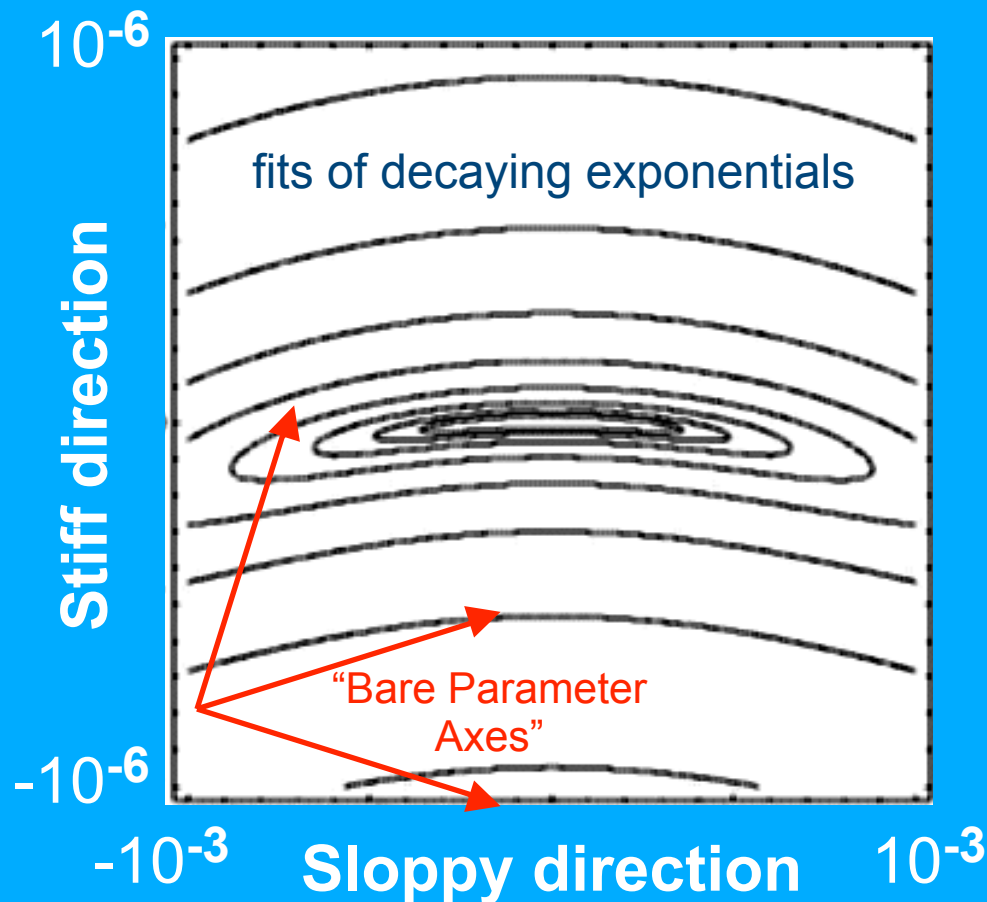
O is chemical concentration  $y(t_i)$ , or rate constant  $\theta_n \dots$

$$H_{ij} = \partial^2 C / \partial \theta_i \partial \theta_j$$

# Parameter Indeterminacy and Sloppiness

Josh Waterfall, Ryan Gutenkunst, Chris Myers

## Cost Contours



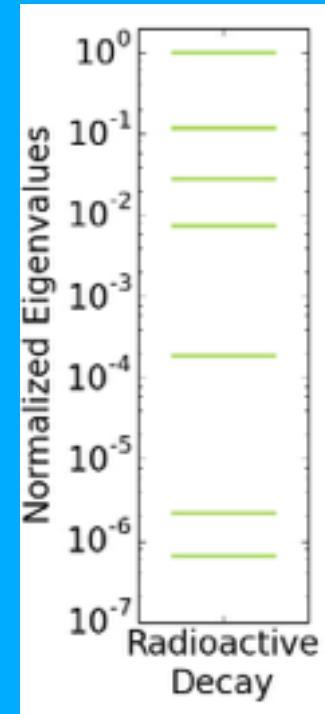
Few stiff, many sloppy directions

Horizontal scale  
shrunk by 1000  
times

Aspect ratio =  
Human hair

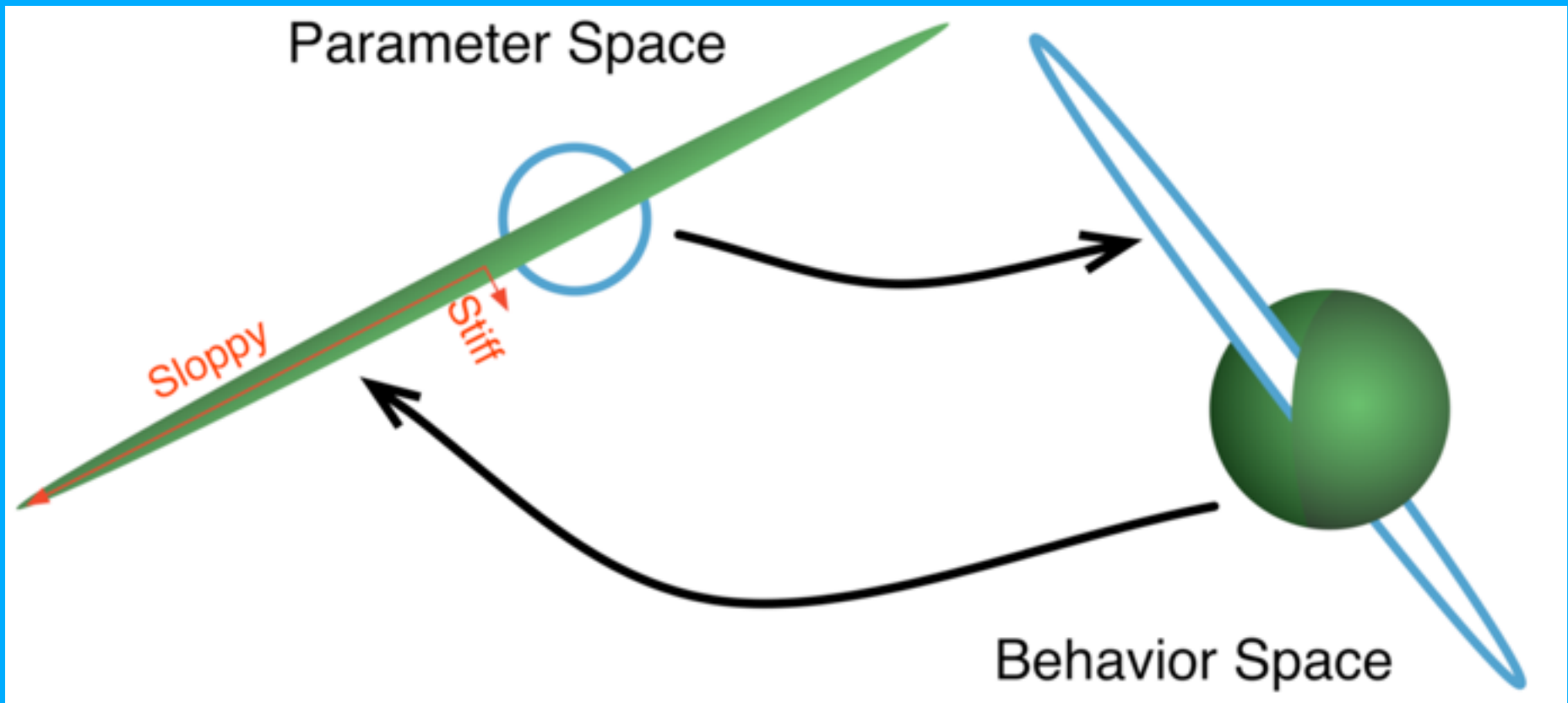
Many parameter  
sets give almost  
equally good fits

A few 'stiff'  
constrained  
directions allow  
model to remain  
predictive



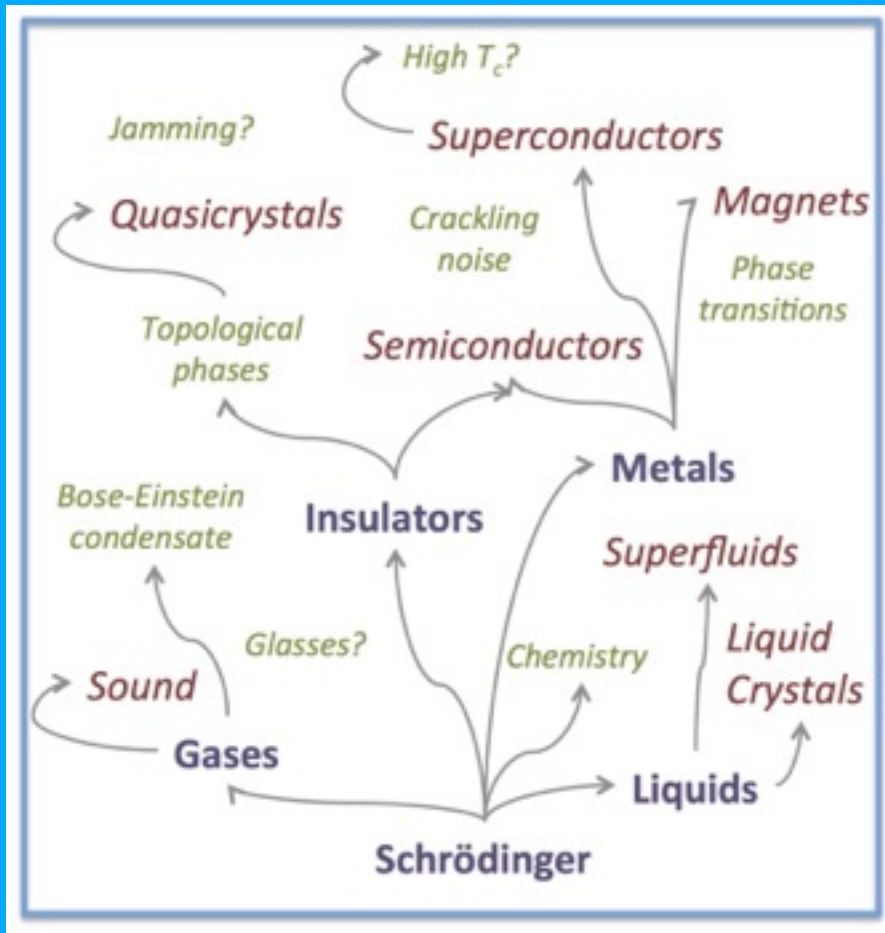


# Models: Predictions about Data



Scientific model: Predictions about behavior depend on physical constants (parameters) in the model.  
Sloppiness: the behavior only depends on a few stiff parameter combinations.

# Emergence: More is Different



## *Condensed Matter*

Microscopic complexity

Simplicity emerges on long length and time scales, low energies

Emergent theory compresses microscopic details into a few governing parameters

# Sloppiness and the Diffusion Equation

Ben Machta, Ricky Chachra, Mark Transtrum

What features of the microscopic hopping laws remain after several hops? Central limit theorem: only mean and variance.

Eigenvalues of parameter identifiability: Stiff = emergent, sloppy = microscopic

## *Diffusion equation*

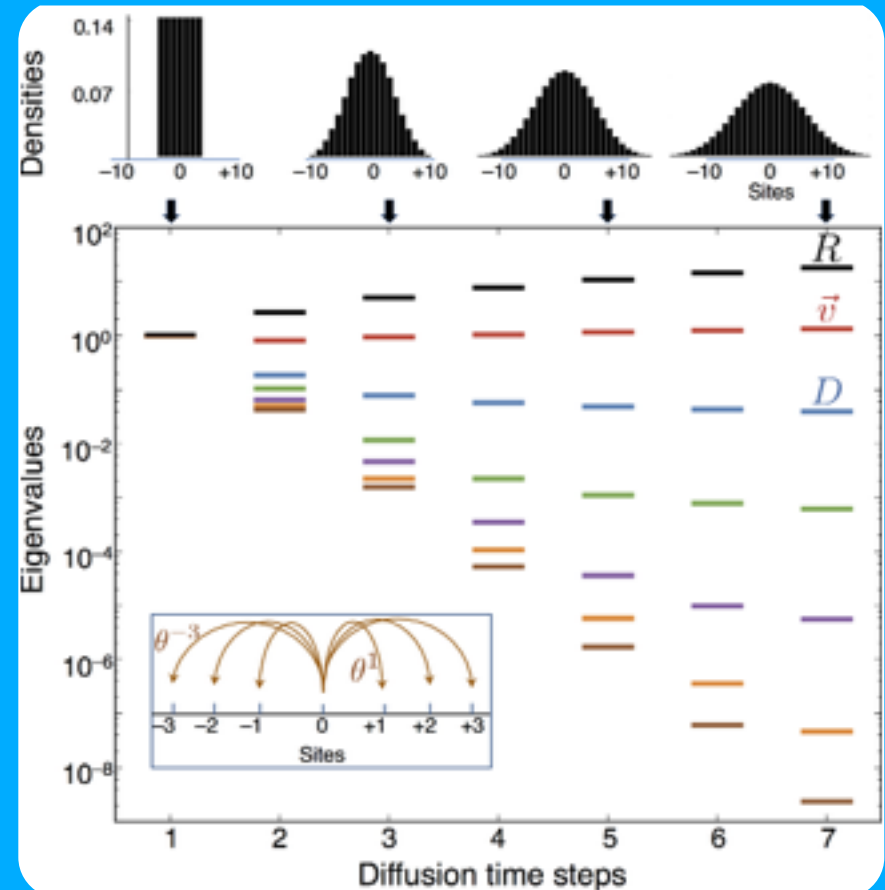
Microscopic long-range hopping model

Continuum limit

$$\partial\rho/\partial t = R\rho - V \partial\rho/\partial x + D \partial^2\rho/\partial x^2$$

One time step: all  $\theta_h$

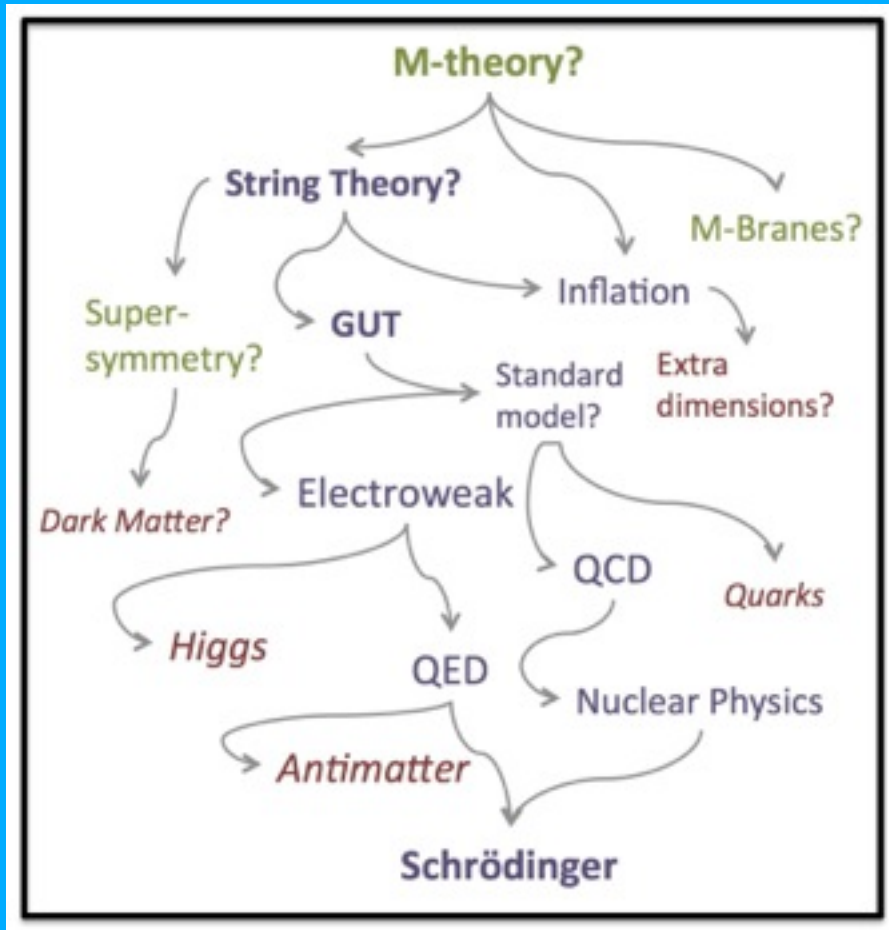
6 time steps: only  $R, V$  and  $D$



Stiff

Sloppy

# Renormalizability: Invisible underpinnings



Renormalization

## *Particle physics*

Renormalizability: Low energy physics independent of cutoff theory

Underlying theory contributes only a few governing parameters

Can't see microscopic details at low energies: need big accelerators

# Sloppiness and the Ising Model

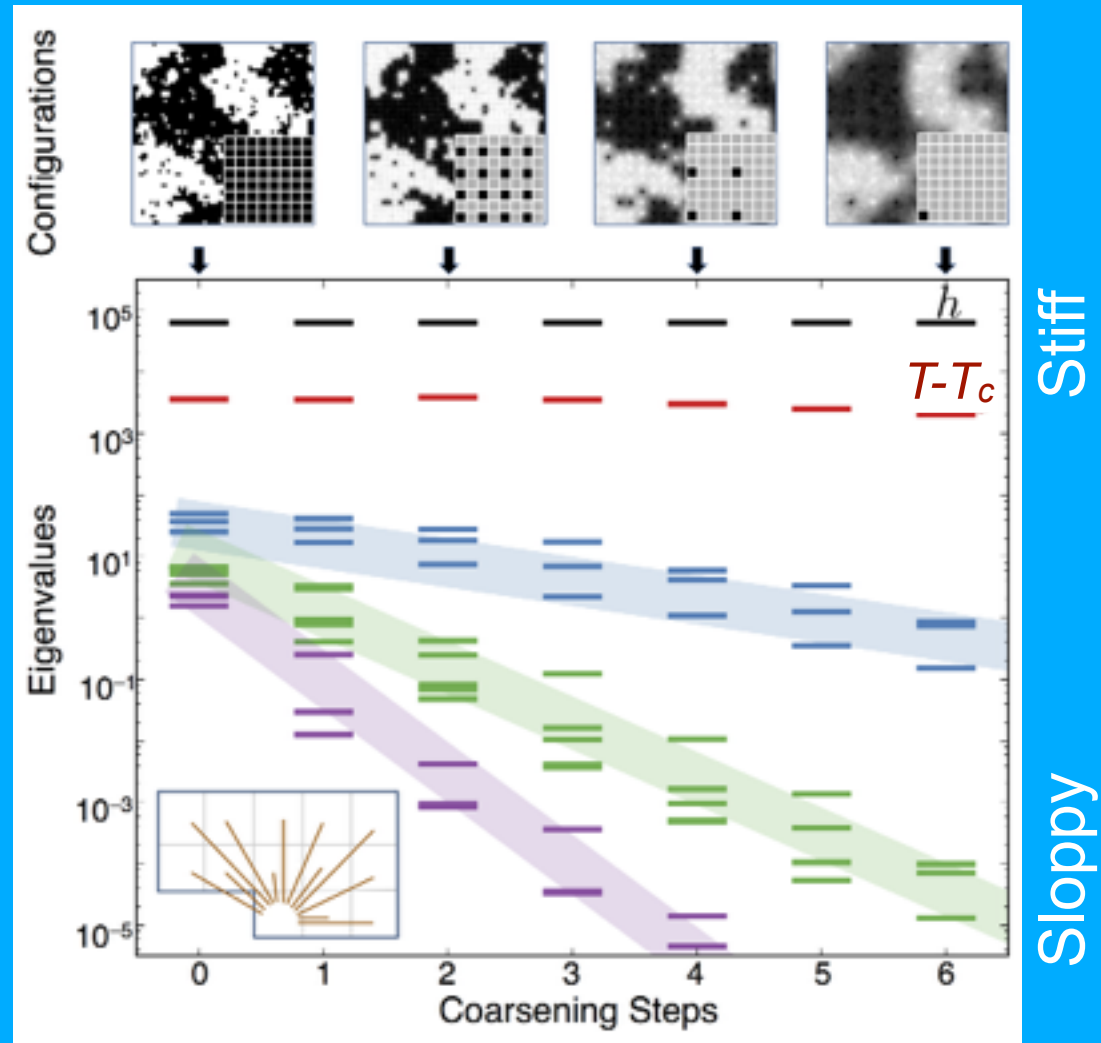
Ben Machta, Ricky Chachra, Mark Transtrum

What features of the microscopic interactions remain after coarse graining?

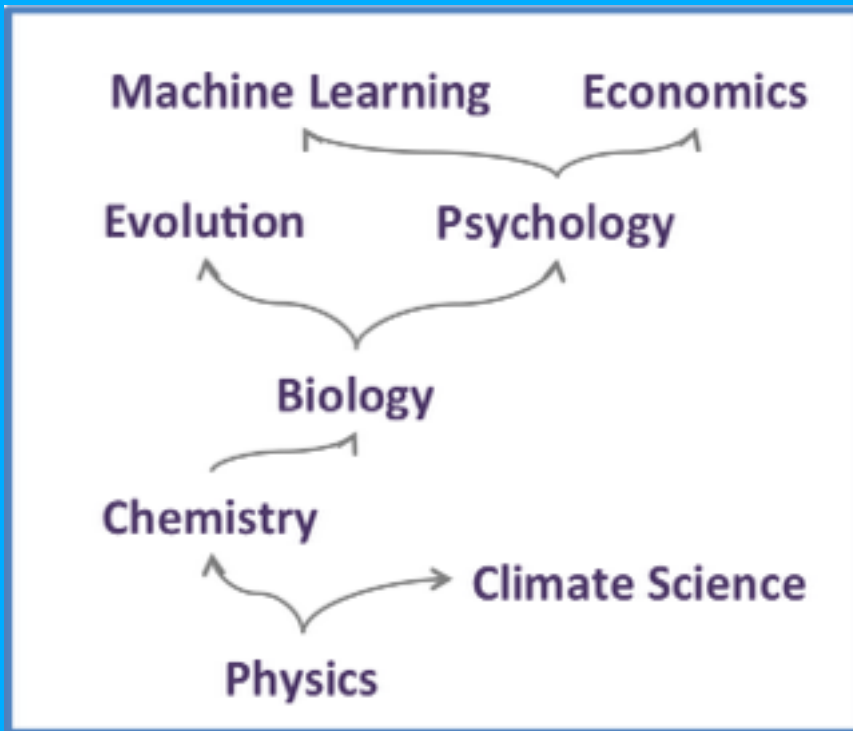
*Renormalization group: only  $h$  and  $T-T_c$*

Eigenvalues of the Fisher Information matrix, Ising with long-range couplings. Only [left] eigenvector of relevant RG operators measurable

Sloppy after coarse graining in space



# Sloppiness and the rest of science

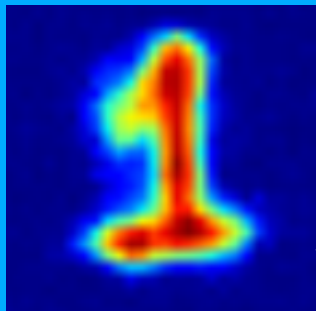
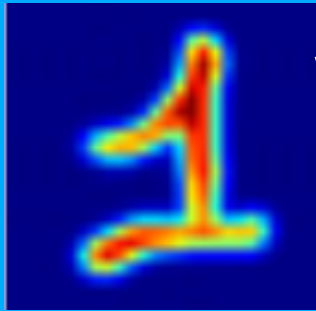


How is science possible,  
without small parameters  
like  $1/L$ ,  $T-T_c$ ?

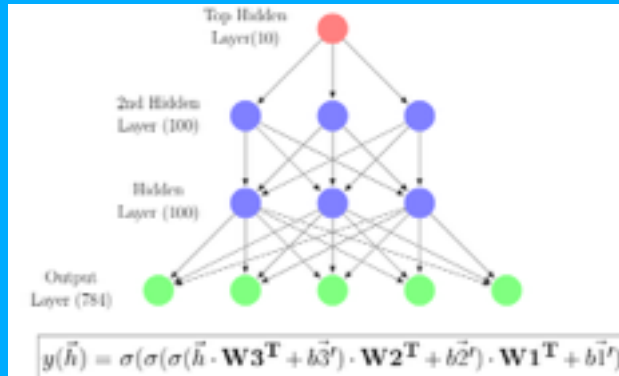
Simple models succeed in  
describing complex  
behavior

# Neural Networks and the Model Manifold

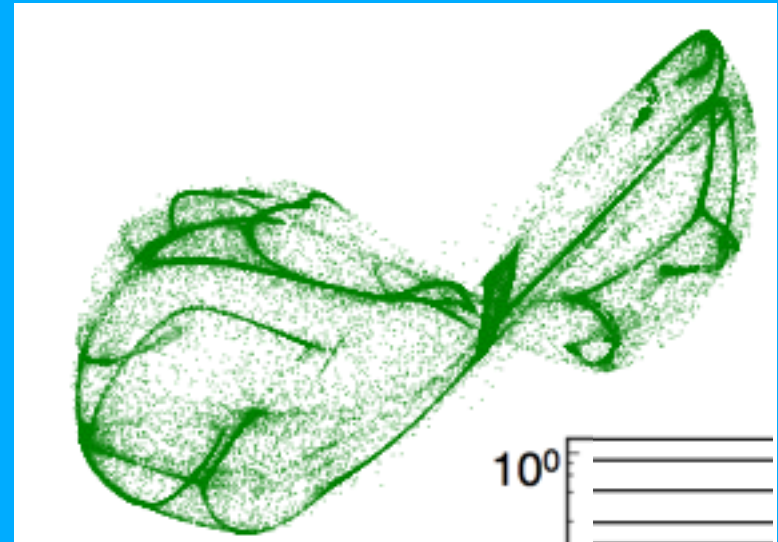
Lorien Hayden, Alex Alemi



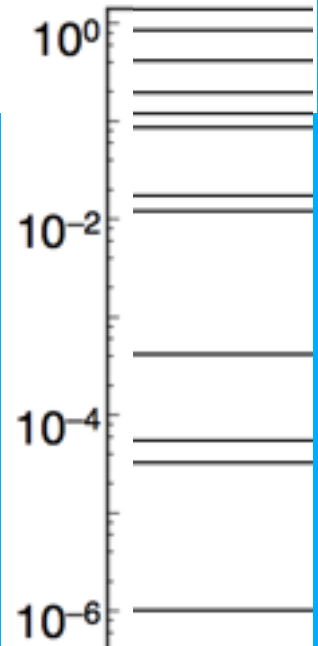
MNIST digits



Stacked Denoising Autoencoder



Geodesic Widths<sup>2</sup>

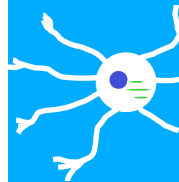
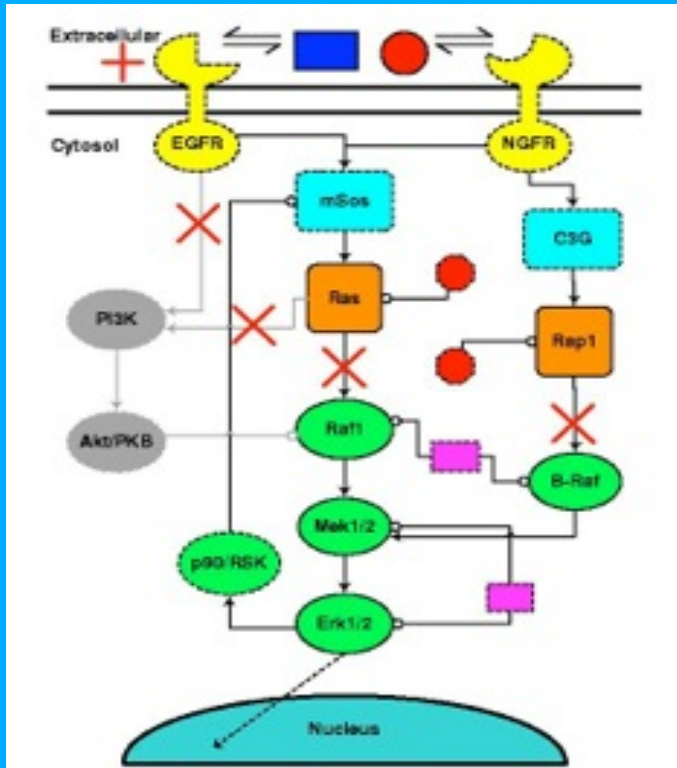






# Systems Biology: Cell Protein Reactions

Kevin Brown, Rick Cerione

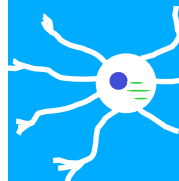
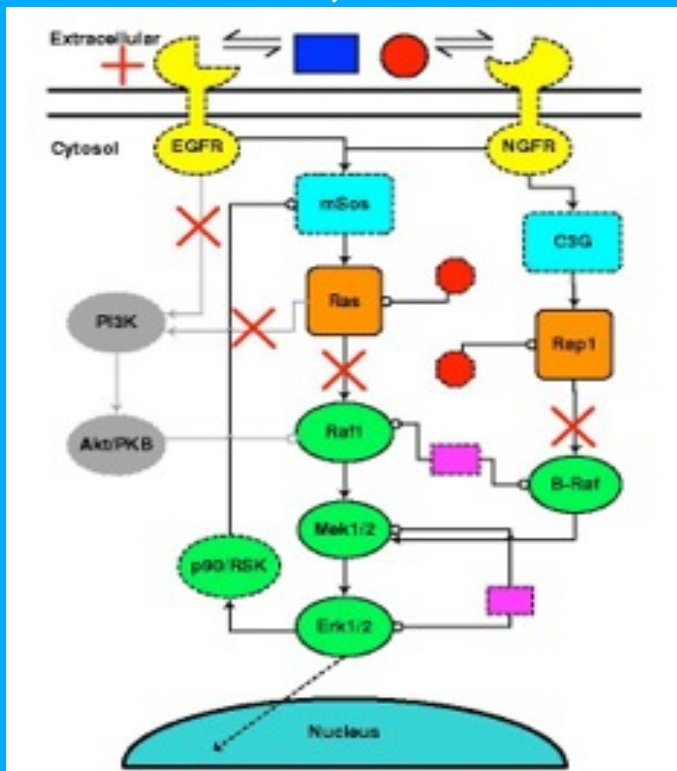


$\frac{d[EGF]}{dt} = -k_{EGF} [EGF] [EGFR_{Total}] + k_{EGF} [EGF] [EGFR_{Active}]$	$\frac{d[Mek1/2]}{dt} = -k_{Mek1/2} [Mek1/2] [Mek1/2_{Total}] + k_{Mek1/2} [Mek1/2_{Active}] [Mek1/2_{Total}]$
$\frac{d[NGF]}{dt} = -k_{NGF} [NGF] [NGFR_{Total}] + k_{NGF} [NGF] [NGFR_{Active}]$	$\frac{d[MakActive]}{dt} = -k_{MakActive} [MakActive] [MakActive] + k_{MakActive} [MakActive] [MakTotal]$
$\frac{d[EGFR_{Total}]}{dt} = k_{EGFR} [EGF] [EGFR_{Total}] - k_{EGFR} [EGFR_{Active}] [EGFR_{Total}]$	$\frac{d[MakTotal]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[EGFR_{Active}]}{dt} = k_{EGFR} [EGF] [EGFR_{Total}] - k_{EGFR} [EGFR_{Active}] [EGFR_{Total}]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[NGFR_{Total}]}{dt} = k_{NGFR} [NGF] [NGFR_{Total}] - k_{NGFR} [NGFR_{Active}] [NGFR_{Total}]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[NGFR_{Active}]}{dt} = k_{NGFR} [NGF] [NGFR_{Total}] - k_{NGFR} [NGFR_{Active}] [NGFR_{Total}]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[Ras]}{dt} = -k_{Ras} [RasActive] [RasActive] + k_{Ras} [RasActive] [RasTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[Raf1]}{dt} = -k_{Raf1} [Raf1Active] [Raf1Active] + k_{Raf1} [Raf1Active] [Raf1Total]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[Mek1/2]}{dt} = -k_{Mek1/2} [Mek1/2Active] [Mek1/2Active] + k_{Mek1/2} [Mek1/2Active] [Mek1/2Total]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[Erk1/2]}{dt} = -k_{Erk1/2} [Erk1/2Active] [Erk1/2Active] + k_{Erk1/2} [Erk1/2Active] [Erk1/2Total]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[PI3K]}{dt} = -k_{PI3K} [PI3KActive] [PI3KActive] + k_{PI3K} [PI3KActive] [PI3KTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[Akt/PKB]}{dt} = -k_{Akt/PKB} [Akt/PKBActive] [Akt/PKBActive] + k_{Akt/PKB} [Akt/PKBActive] [Akt/PKBTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[p90RSK]}{dt} = -k_{p90RSK} [p90RSKActive] [p90RSKActive] + k_{p90RSK} [p90RSKActive] [p90RSKTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[TotalRaf]}{dt} = -k_{TotalRaf} [TotalRafActive] [TotalRafActive] + k_{TotalRaf} [TotalRafActive] [TotalRafTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[RafActive]}{dt} = k_{Raf} [RafTotal] - k_{Raf} [RafActive] [RafTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[RafTotal]}{dt} = k_{Raf} [RafTotal] - k_{Raf} [RafActive] [RafTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[RafByAkt]}{dt} = -k_{RafByAkt} [RafByAktActive] [RafByAktActive] + k_{RafByAkt} [RafByAktActive] [RafByAktTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[RafByAktTotal]}{dt} = k_{RafByAkt} [RafByAktTotal] - k_{RafByAkt} [RafByAktActive] [RafByAktTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[RafByAktActive]}{dt} = k_{RafByAkt} [RafByAktTotal] - k_{RafByAkt} [RafByAktActive] [RafByAktTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[RafByAktTotal]}{dt} = k_{RafByAkt} [RafByAktTotal] - k_{RafByAkt} [RafByAktActive] [RafByAktTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[RafByAktActive]}{dt} = k_{RafByAkt} [RafByAktTotal] - k_{RafByAkt} [RafByAktActive] [RafByAktTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$
$\frac{d[RafByAktActive]}{dt} = k_{RafByAkt} [RafByAktTotal] - k_{RafByAkt} [RafByAktActive] [RafByAktTotal]$	$\frac{d[MakInact]}{dt} = -k_{Mak} [MakActive] [MakActive] + k_{Mak} [MakActive] [MakTotal]$

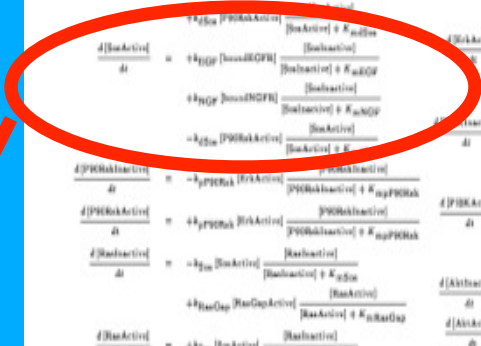
## 48 Parameter Fit!

# Systems Biology: Cell Protein Reactions

Kevin Brown, Rick Cerione



$\frac{d[EGF]}{dt} = -k_{EGF}[EGF][\text{boundEGFR}] + k_{EGF}[EGF][\text{freeEGFR}]$	$\frac{d[\text{boundEGFR}]}{dt} = +k_{EGF}[EGF][\text{freeEGFR}] - k_{EGF}[EGF][\text{boundEGFR}]$	$\frac{d[\text{boundNGFR}]}{dt} = +k_{NGF}[NGF][\text{freeNGFR}] - k_{NGF}[NGF][\text{boundNGFR}]$	$\frac{d[\text{boundNGFR}]}{dt} = +k_{NGF}[NGF][\text{freeNGFR}] - k_{NGF}[NGF][\text{boundNGFR}]$
$\frac{d[mSos]}{dt} = +k_{EGF}[EGF][\text{boundEGFR}] - k_{EGF}[EGF][\text{boundEGFR}] - k_{dSos}[P90RskActive] \frac{[mSos]}{[mSos] + K_{mdSos}}$	$\frac{d[Ras]}{dt} = +k_{EGF}[EGF][\text{boundEGFR}] - k_{EGF}[EGF][\text{boundEGFR}] - k_{dRas}[RasActive] \frac{[Ras]}{[Ras] + K_{dRas}}$	$\frac{d[CSG]}{dt} = +k_{NGF}[NGF][\text{boundNGFR}] - k_{dCSG}[CSGActive] \frac{[CSG]}{[CSG] + K_{dCSG}}$	$\frac{d[Rep1]}{dt} = +k_{NGF}[NGF][\text{boundNGFR}] - k_{dRep1}[Rep1Active] \frac{[Rep1]}{[Rep1] + K_{dRep1}}$
$\frac{d[Raf1]}{dt} = +k_{Ras}[RasActive] \frac{[Raf1]}{[Raf1] + K_{dRaf1}} - k_{dRaf1}[Raf1Active] \frac{[Raf1]}{[Raf1] + K_{dRaf1}}$	$\frac{d[Mek1/2]}{dt} = +k_{Raf1}[Raf1Active] \frac{[Mek1/2]}{[Mek1/2] + K_{dMek1/2}} - k_{dMek1/2}[Mek1/2Active] \frac{[Mek1/2]}{[Mek1/2] + K_{dMek1/2}}$	$\frac{d[\beta-Raf]}{dt} = +k_{Rep1}[Rep1Active] \frac{[\beta-Raf]}{[\beta-Raf] + K_{d\beta-Raf}} - k_{d\beta-Raf}[\beta-RafActive] \frac{[\beta-Raf]}{[\beta-Raf] + K_{d\beta-Raf}}$	$\frac{d[Erk1/2]}{dt} = +k_{Mek1/2}[Mek1/2Active] \frac{[Erk1/2]}{[Erk1/2] + K_{dErk1/2}} - k_{dErk1/2}[Erk1/2Active] \frac{[Erk1/2]}{[Erk1/2] + K_{dErk1/2}}$
$\frac{d[PI3K]}{dt} = +k_{EGF}[EGF][\text{boundEGFR}] - k_{dPI3K}[PI3KActive] \frac{[PI3K]}{[PI3K] + K_{dPI3K}}$	$\frac{d[Akt/PKB]}{dt} = +k_{PI3K}[PI3KActive] \frac{[Akt/PKB]}{[Akt/PKB] + K_{dAkt/PKB}} - k_{dAkt/PKB}[Akt/PKBActive] \frac{[Akt/PKB]}{[Akt/PKB] + K_{dAkt/PKB}}$	$\frac{d[ERKActive]}{dt} = +k_{Erk1/2}[Erk1/2Active] \frac{[ERKActive]}{[ERKActive] + K_{dERKActive}} - k_{dERKActive}[ERKActive] \frac{[ERKActive]}{[ERKActive] + K_{dERKActive}}$	$\frac{d[ERKInactive]}{dt} = +k_{dERKActive}[ERKActive] \frac{[ERKInactive]}{[ERKInactive] + K_{dERKInactive}} - k_{ERKActive}[ERKInactive] \frac{[ERKActive]}{[ERKActive] + K_{dERKActive}}$

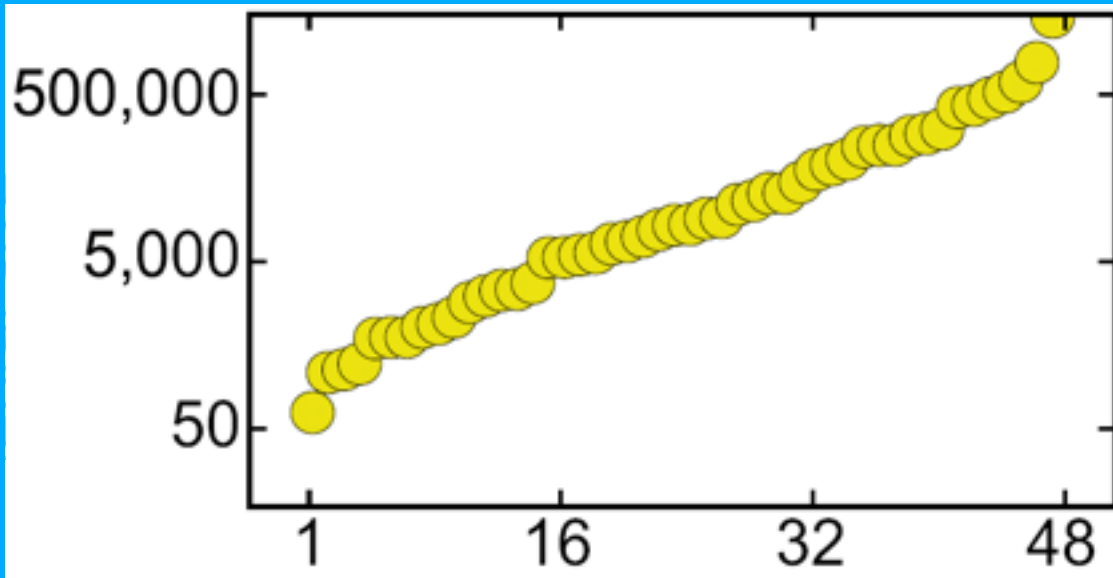


$$\frac{d[\text{SosActive}]}{dt} = +k_{EGF} [\text{boundEGFR}] \frac{[\text{SosInactive}]}{[\text{SosInactive}] + K_{mEGF}} + k_{NGF} [\text{boundNGFR}] \frac{[\text{SosInactive}]}{[\text{SosInactive}] + K_{mNGF}} - k_{dSos} [\text{P90RskActive}] \frac{[\text{SosActive}]}{[\text{SosActive}] + K_{mdSos}}$$

48 Parameter Fit!



Relative parameter fluctuation



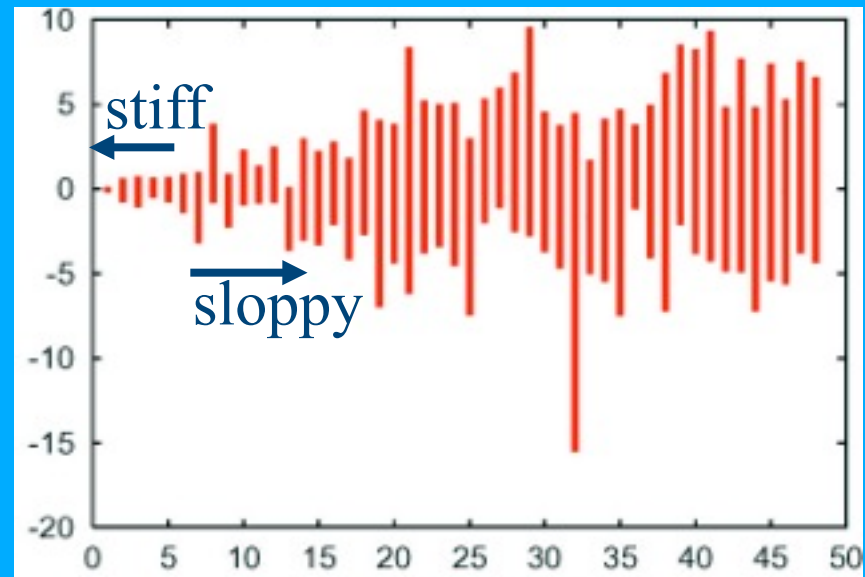
Parameter (sorted)

Parameters  
Fluctuate  
over  
Enormous  
Range

- All parameters vary by minimum factor of 50, some by a million
- Not robust: four or five “stiff” linear combinations of parameters; 44 sloppy

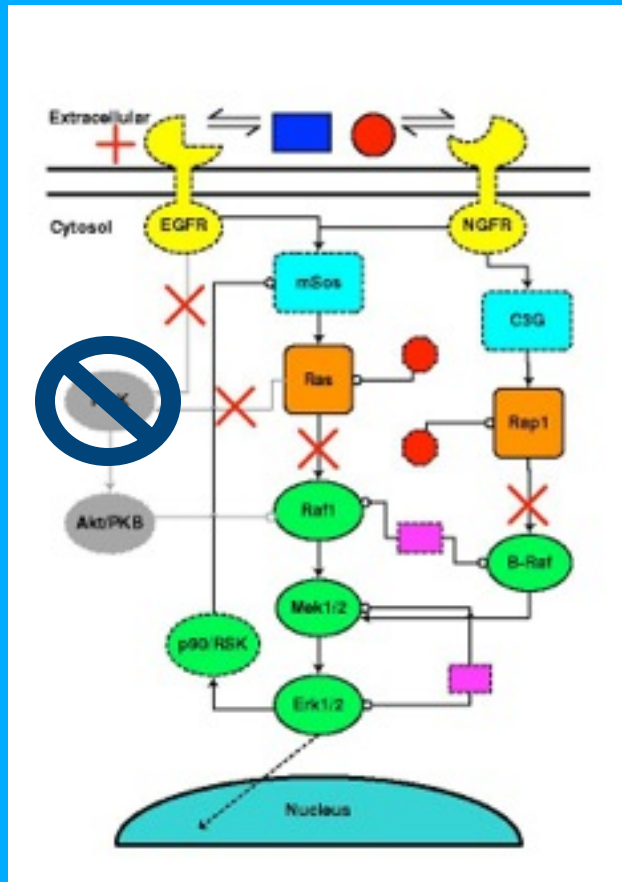
Are predictions possible?

$\log_e$  eigenparameter fluctuation



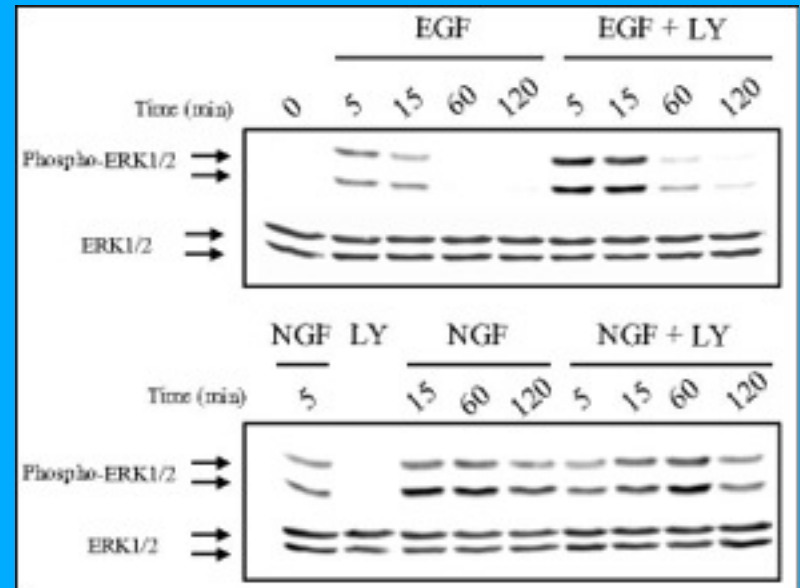
sorted eigenparameter number

# Predictions are Possible

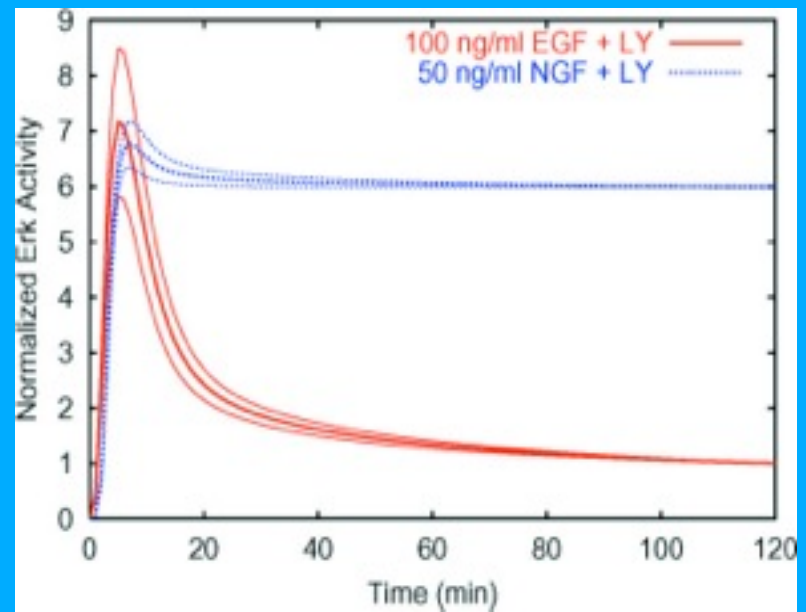


Model predicts that the left branch isn't important

Brown's Experiment



Parameters fluctuate orders of magnitude, but still predictive!

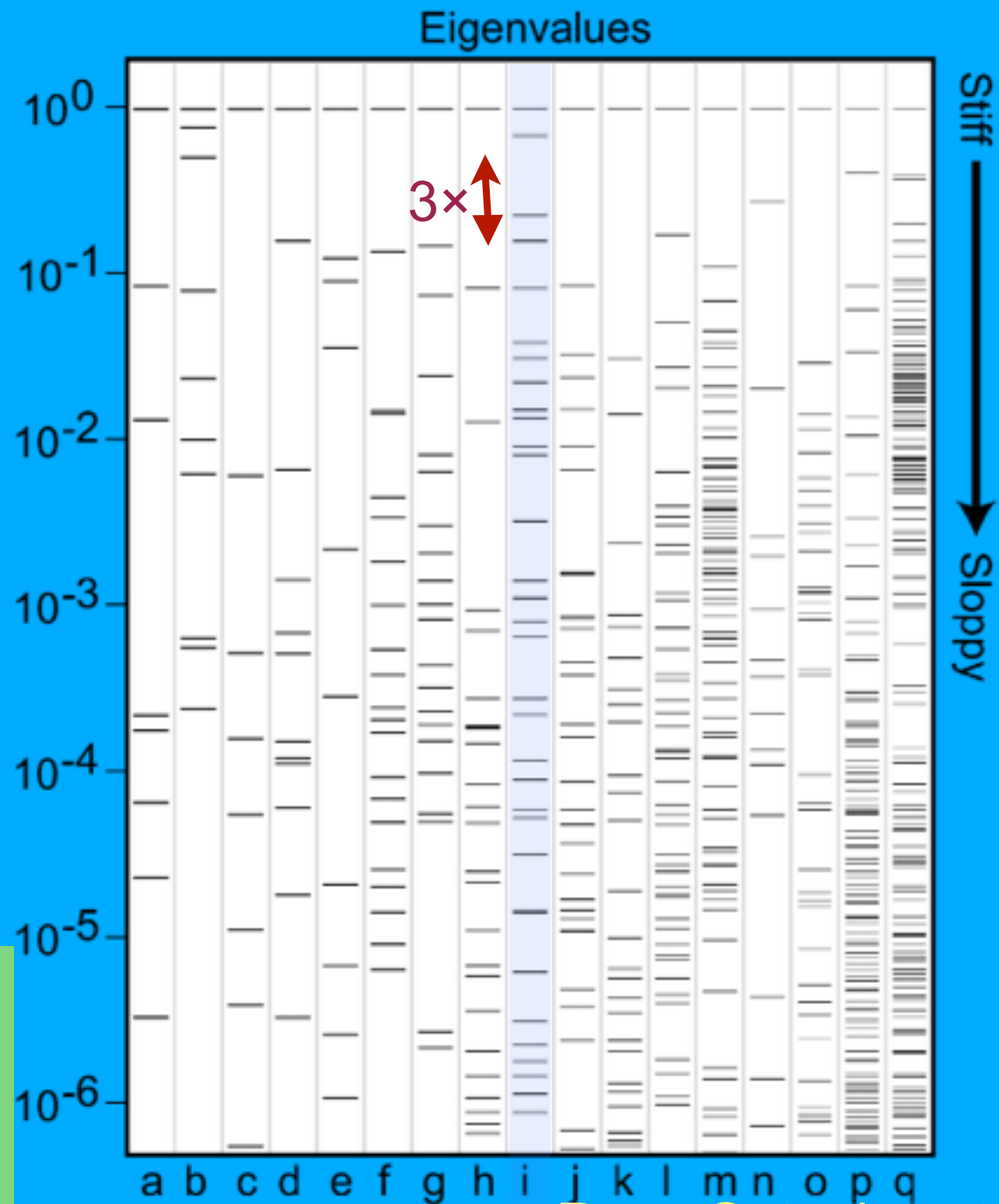


# Systems Biology

## Seventeen models

- (a) eukaryotic cell cycle
- (b) Xenopus egg cell cycle
- (c) eukaryotic mitosis
- (d) generic circadian rhythm
- (e) nicotinic acetylcholine intra-receptor dynamics
- (f) generic kinase cascade
- (g) Xenopus Wnt signaling
- (h) Drosophila circadian rhythm
- (i) rat growth-factor signaling
- (j) Drosophila segment polarity
- (k) Drosophila circadian rhythm
- (l) Arabidopsis circadian rhythm
- (m) in silico regulatory network
- (n) human purine metabolism
- (o) Escherichia coli carbon metabolism
- (p) budding yeast cell cycle
- (q) rat growth-factor signaling

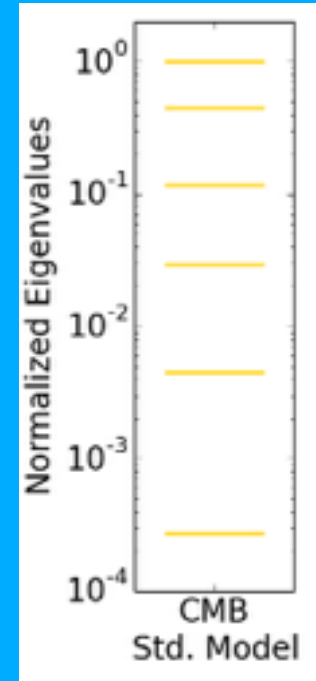
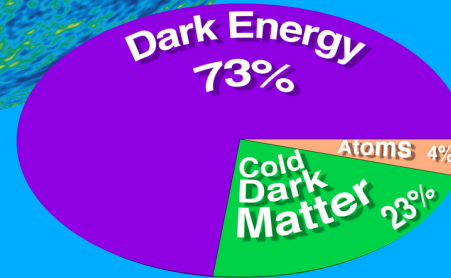
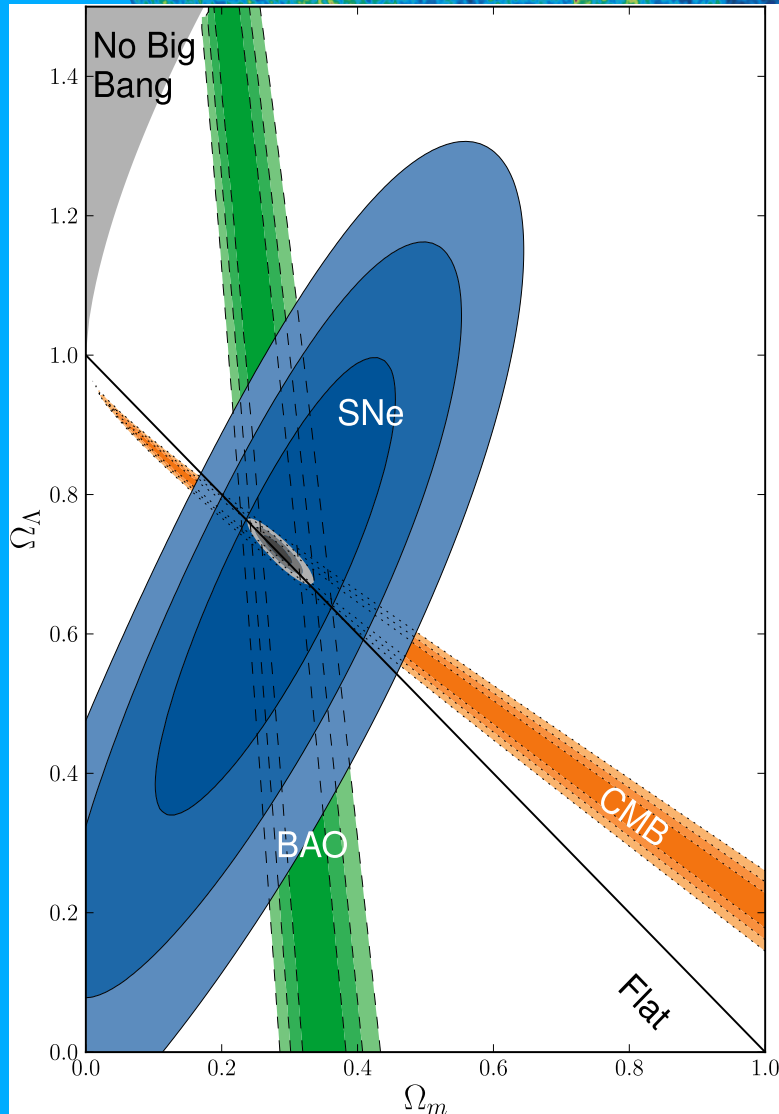
Enormous Ranges of  
Eigenvalues  
( $3^{48}$  is a big number)  
Sloppy Range  $\sim \sqrt{\lambda}$



Ryan Gutenkunst

# The Universe

$\Lambda$ CDM fit for cosmic microwave background radiation



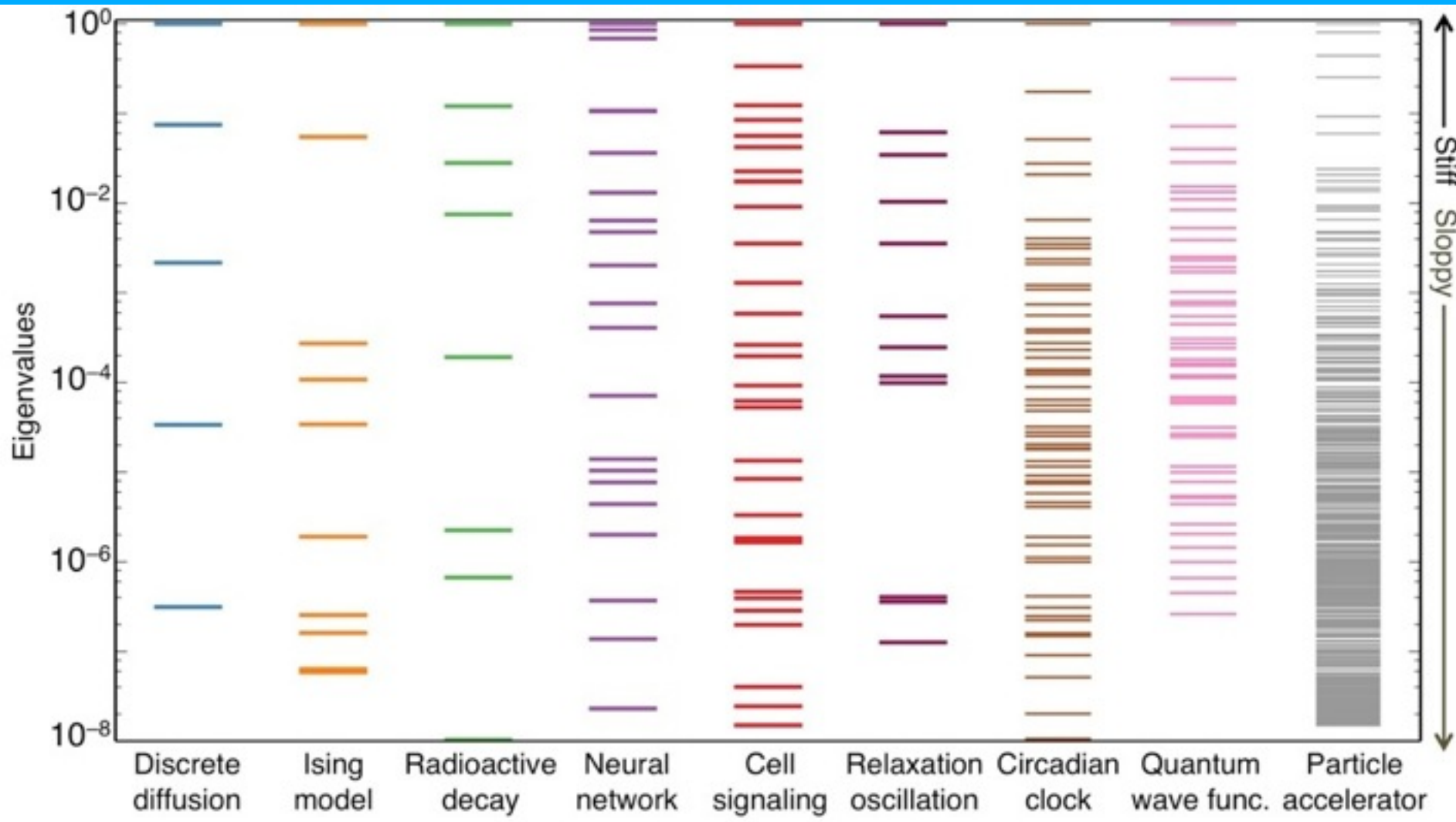
Universe is flat, mostly unknown dark stuff

- Six parameter  $\Lambda$ CDM model is sloppy fit to CMB; SNe and BAO determine
- More general models introduce worse degeneracies

Katherine Quinn, Michael Niemack,  
Francesco De Bernardis

# Sloppy Universality Outside Bio

Waterfall, Gutenkunst, Chachra, Machta, Clement



**Enormous range of eigenvalues; Roughly equal density in log;  
Observed in broad range of systems**



# The Model Manifold

Mark Transtrum, Ben Machta

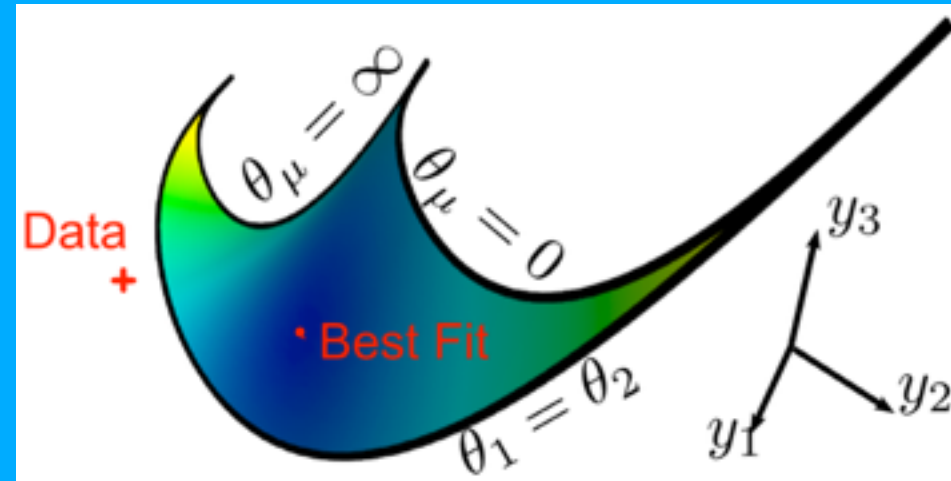
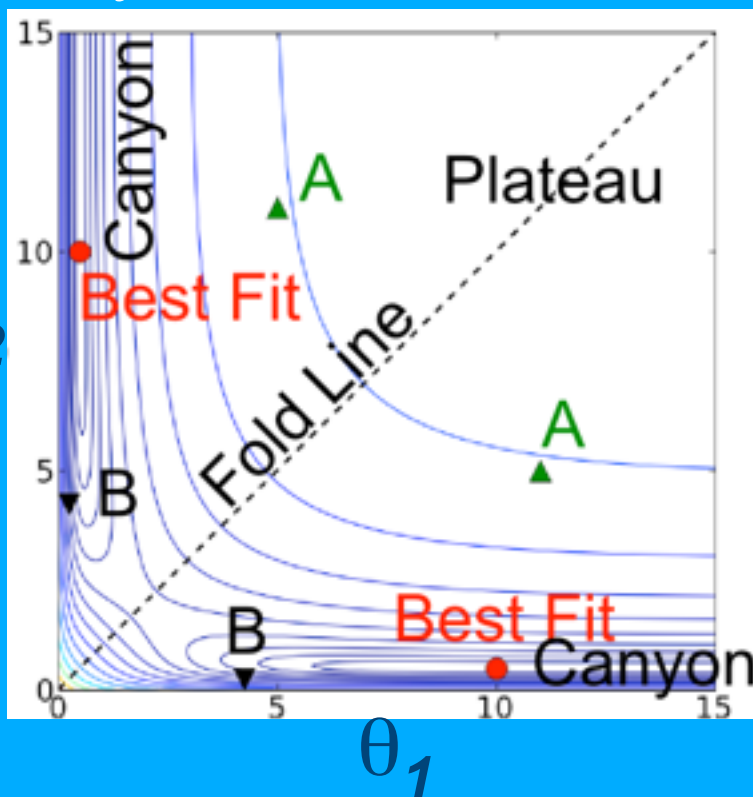
Two exponentials  $\theta_\alpha$  fit to three data points  $y_n$ ,

$$y_n = \exp(-\theta_1 t_n) + \exp(-\theta_2 t_n)$$

## Parameter space

Stiff and sloppy directions

Canyons, Plateaus



## Data space

Manifold of model predictions

Parameters as coordinates

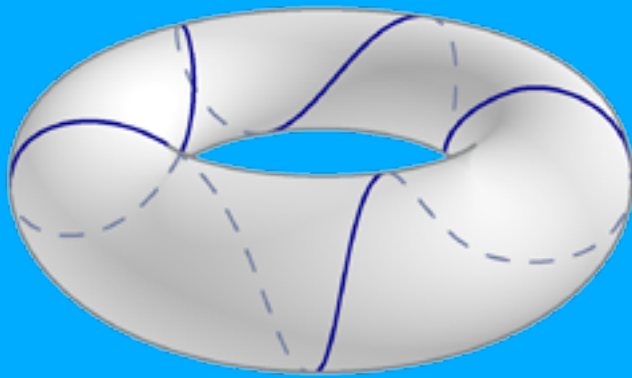
Model boundaries  $\theta_n = \infty$ ,  $\theta_m$

cause Plateaus

Metric  $g_{\mu\nu}$  from distance to data

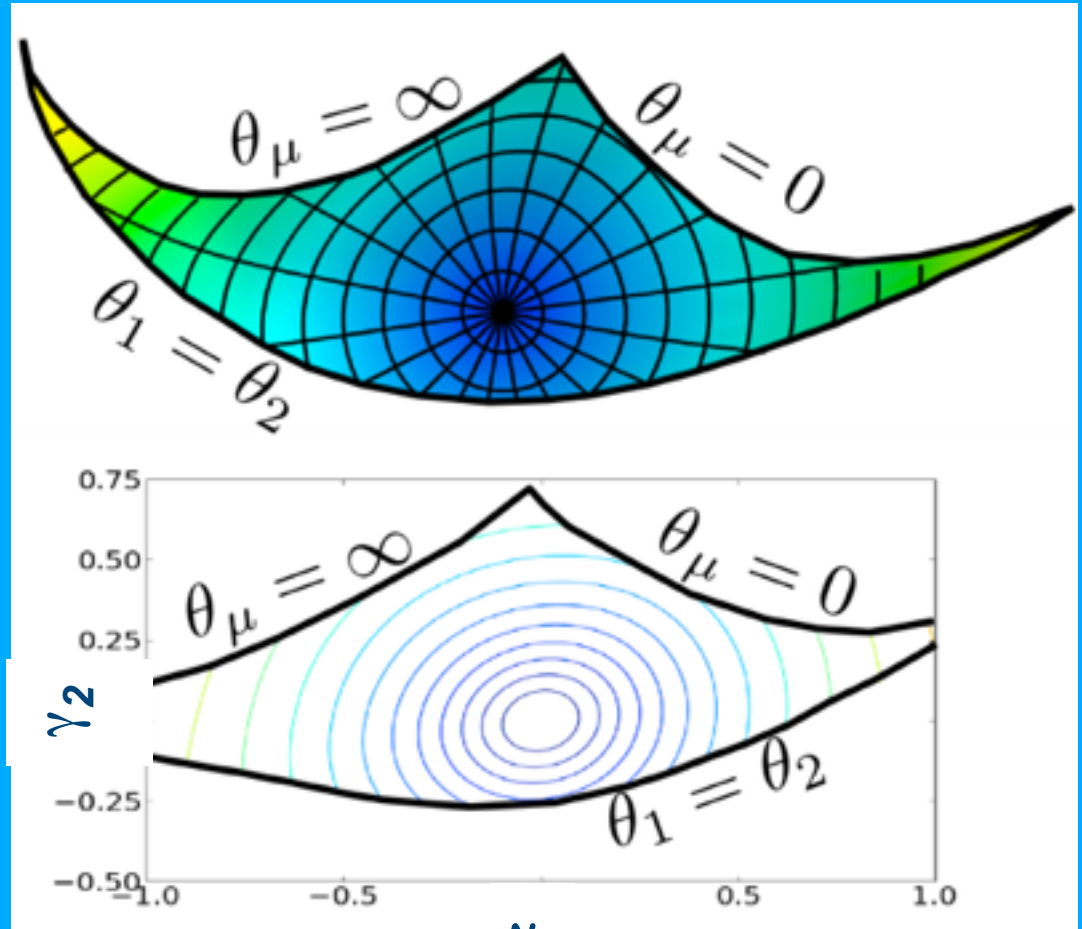
# Geodesics

“Straight line” in curved space  
Shortest path between points



Easy to find cost minimum using polar geodesic coordinates

$\gamma_1, \gamma_2$



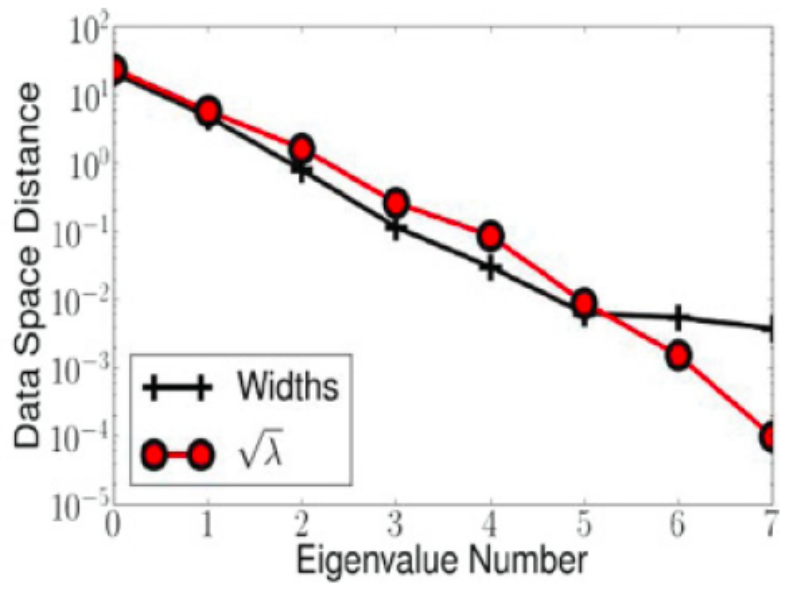
$\gamma_1$

Cost contours in geodesic coordinates  
nearly concentric circles!  
Use this for algorithms...

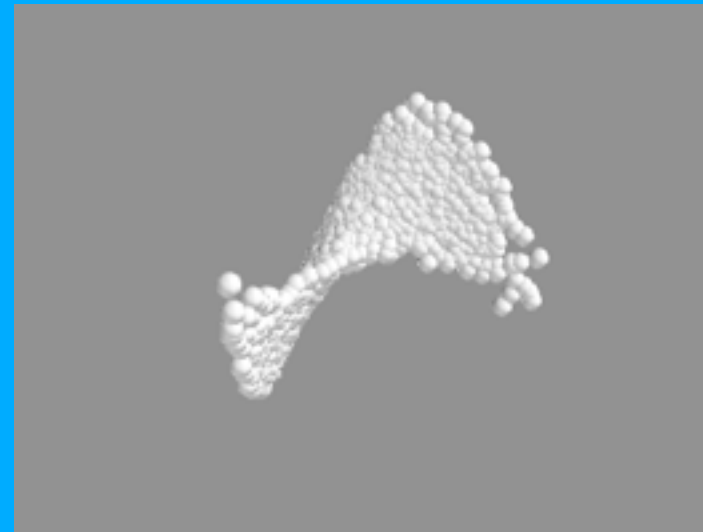
# The Model Manifold is a *Hyper-Ribbon*

- Hyper-ribbon: object that is longer than wide, wider than thick, thicker than ...
- Thick directions traversed by stiff eigenparameters, thin as sloppy directions varied.

Sum of many exponentials,  
fit to  
 $y(0), y(1)$   
data  
predictions at  
 $y(1/4), y(1/2),$   
 $y(3/4)$



Widths along geodesics track eigenvalues almost perfectly!

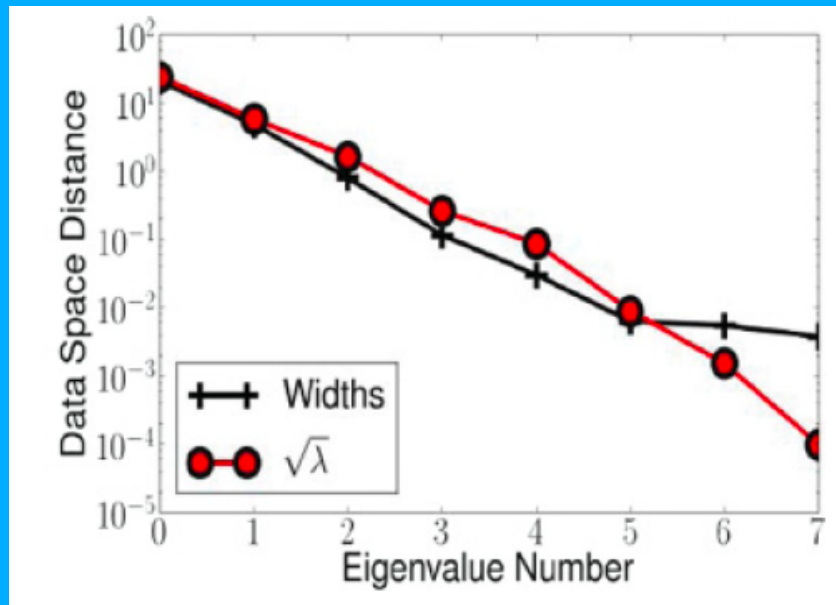


Diffusion equation after three time steps

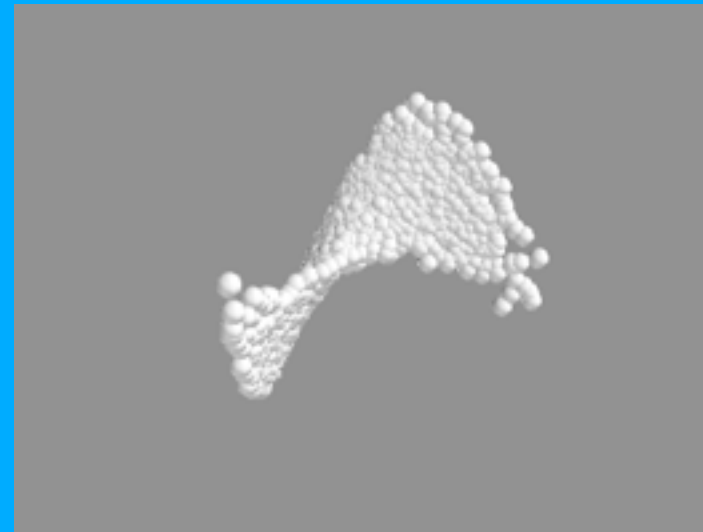
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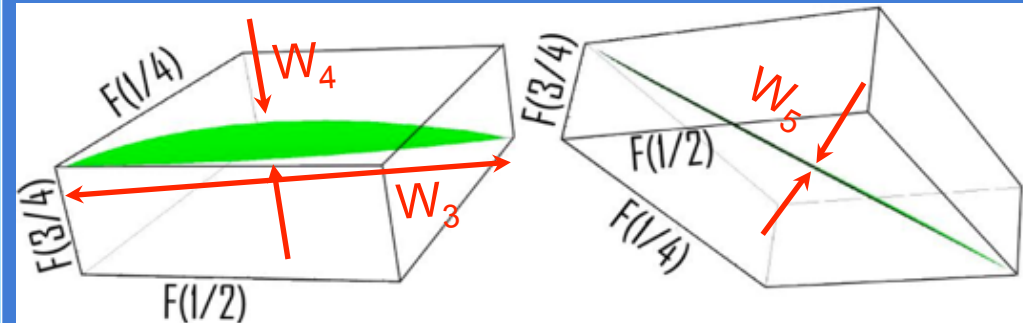
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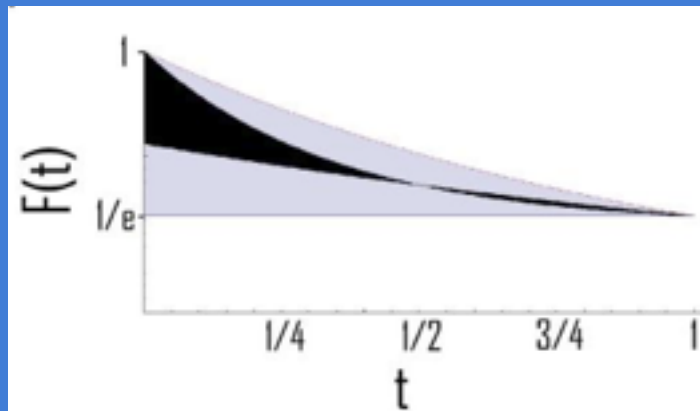
Diffusion equation after three time steps

# Hierarchy of widths and curvatures

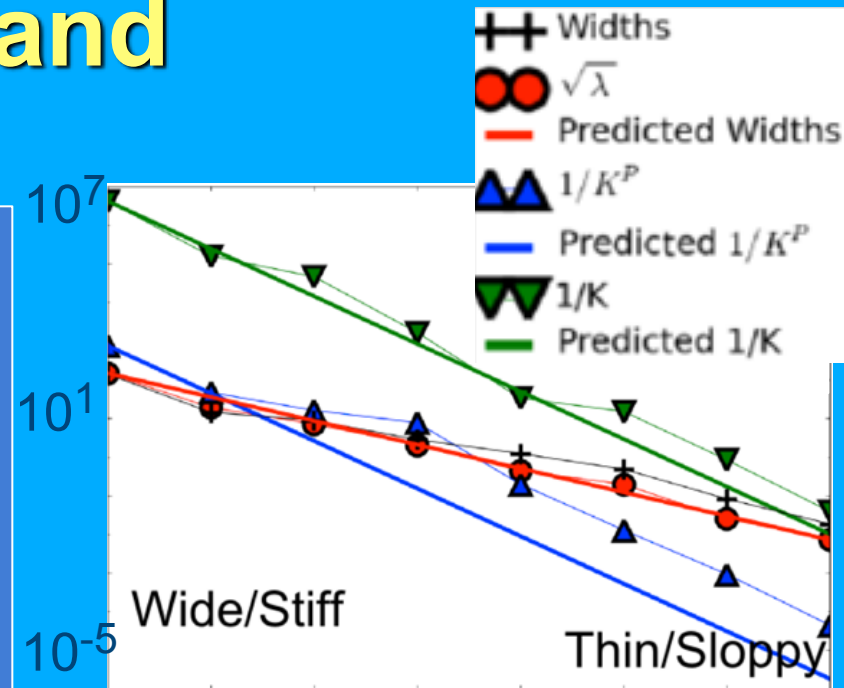
## Hierarchy of widths



Cross sections: fixing  $f$  at  $0, \frac{1}{2}, 1$



Theorem: interpolation good with many data points  
Geometrical convergence



Eigendirection at best fit

Multi-decade span of widths, curvatures, eigenvalues

Widths  $\sim \sqrt{\lambda}$  sloppy eigs

Parameter curvature  
 $K^P = 10^3 \times K$   
 $\gg$  extrinsic curvature

# Why is it so thin and flat?

Model  $f(t, \theta)$  analytic:

$$f^{(n)}(t)/n! \leq R^{-n}$$

Polynomial fit  $P_{m-1}(t)$

to  $f(t_1), \dots, f(t_m)$

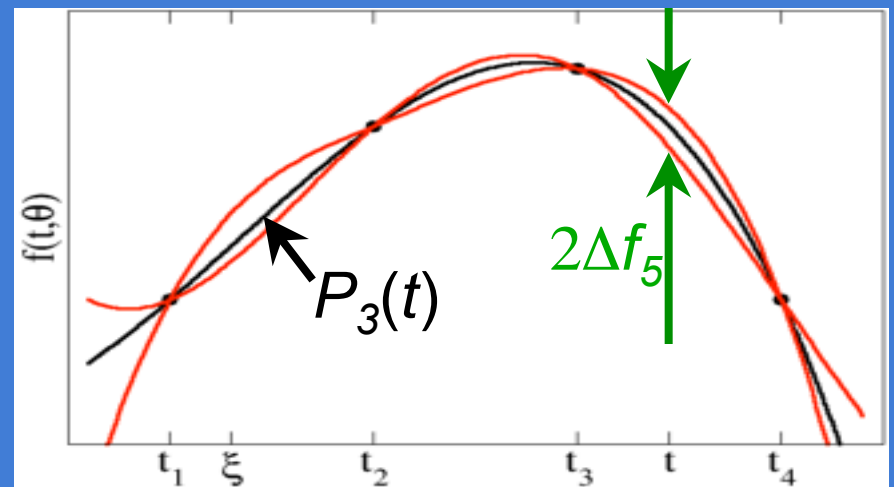
Interpolation convergence theorem

$$\Delta f_{m+1} = f(t) - P_{m-1}(t)$$

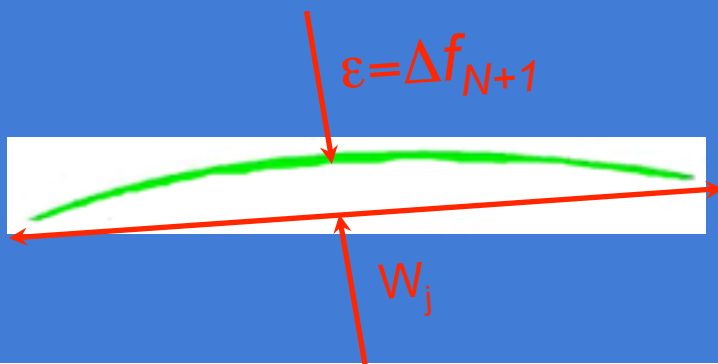
$$< (t-t_1)(t-t_2)\dots(t-t_m) f^{(m)}(\xi)/m!$$

$$\sim (\Delta t / R)^m$$

More than one data per R

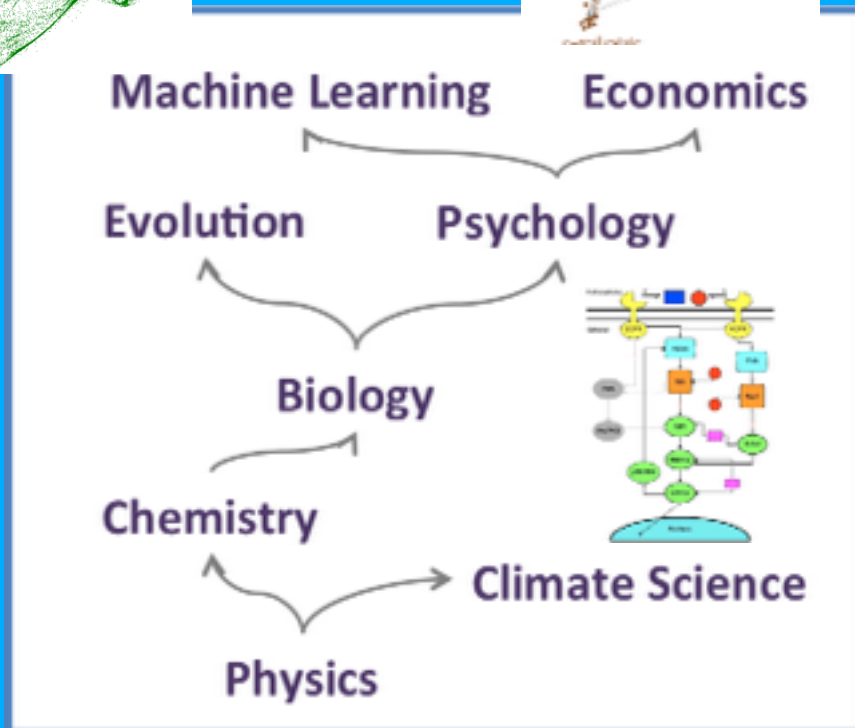
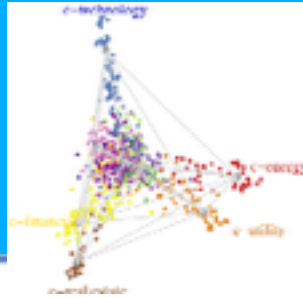
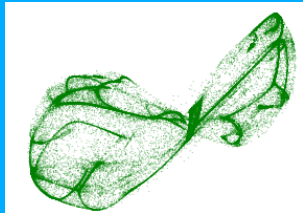


**Hyper-ribbon:** Cross section constraining  $m$  points has width  $W_{m+1} \sim \Delta f_{m+1} \sim (\Delta t / R)^m$



**Extrinsic flatness:**  $N=M$  trivially flat, extra data deviates  $\varepsilon \sim \Delta f_{N+1}$ , so curvature  $K \sim \varepsilon / W_j^2 \sim (\Delta t / R)^{N+1-j} / W_j$

# Big Sloppiness Questions.



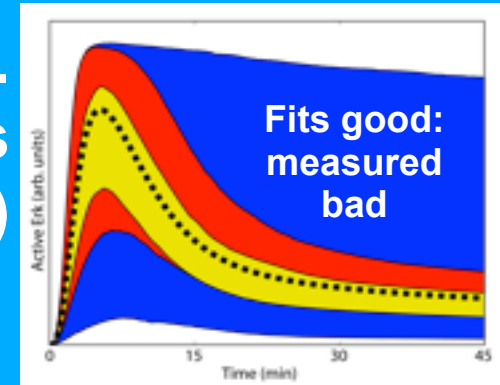
Science appears to rely on *parameter compression*: only a few stiff parameter combinations matter.

- How is our general explanation for the hierarchy of stiffness (interpolation theory) related to that in physics (small parameters)?
- Without sloppiness, science is hard. (If all the details matter, can't work toward the answer.) Is science selecting sloppy problems, or is everything sloppy?

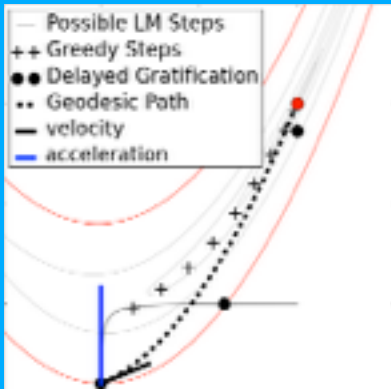
# Sloppy Applications

Several applications emerge

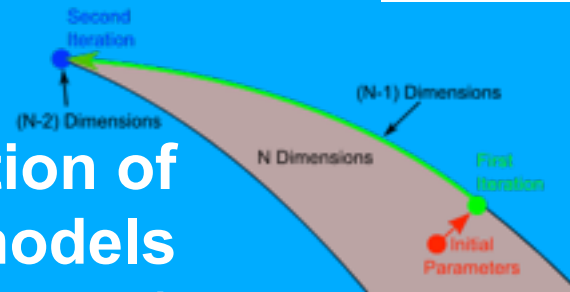
A. Fitting data vs. measuring parameters (Gutenkunst)



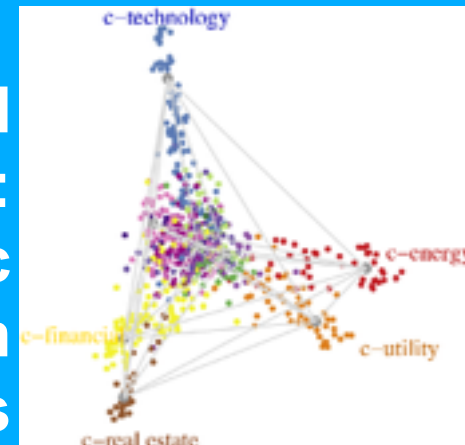
B. Finding best fits by geodesic acceleration (Transtrum)



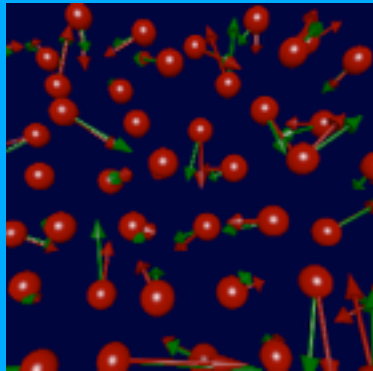
C. Generation of reduced models (Transtrum)



D. Unsupervised learning: Economic sectors from stock prices



E. Estimating systematic errors: DFT and interatomic potentials (Jacobsen et al.)

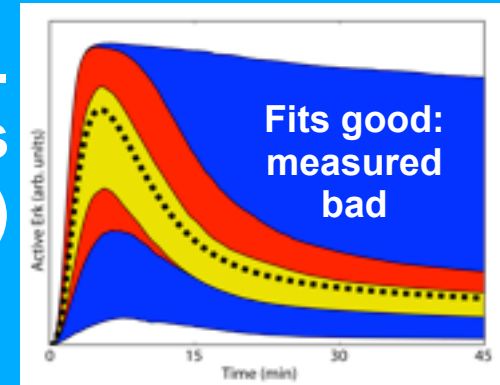




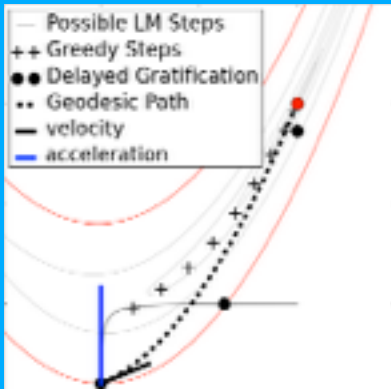
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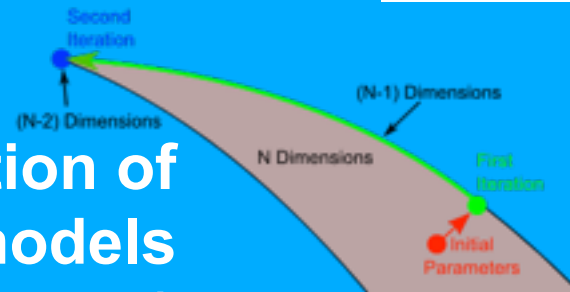
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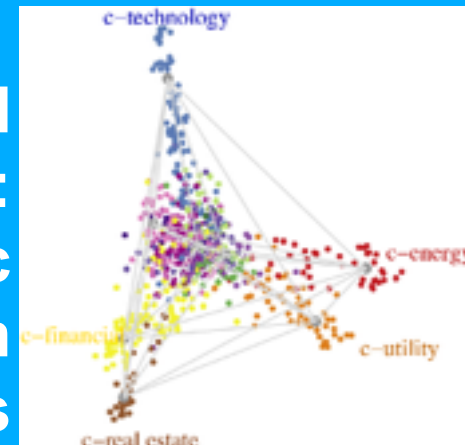
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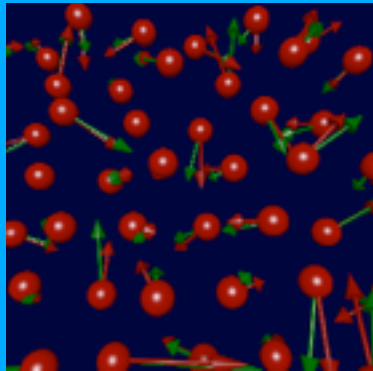
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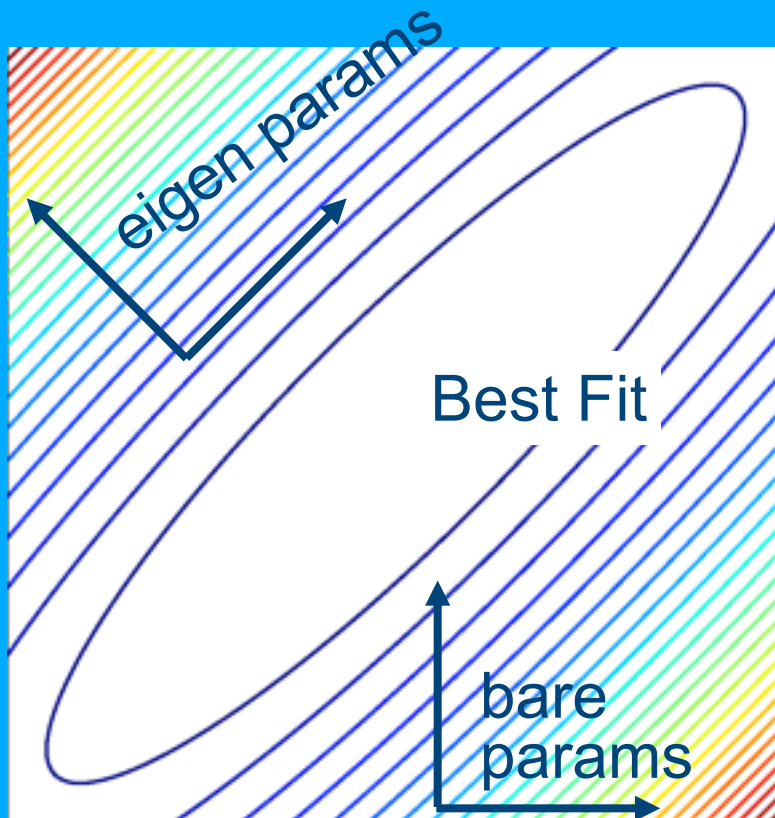


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# A. Are rate constants useful?

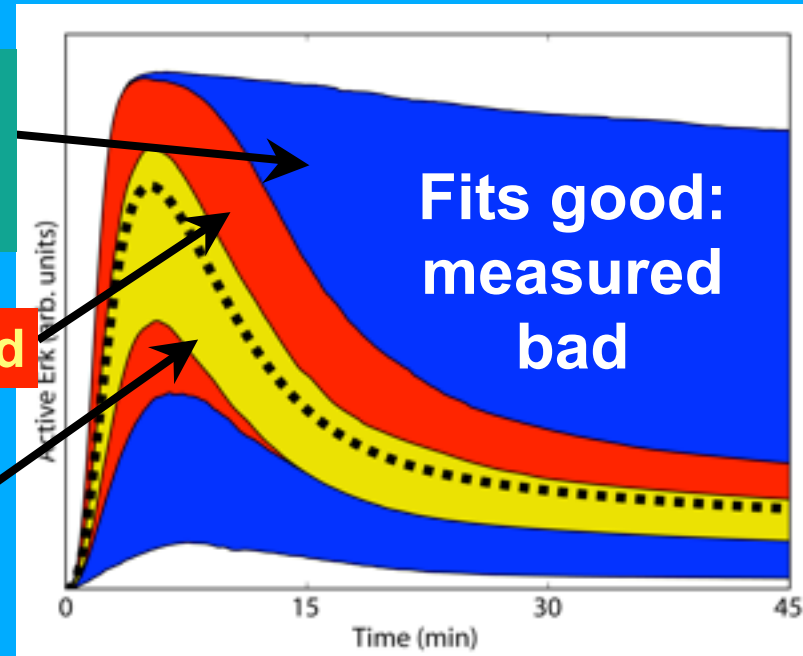
## Fits vs. measurements



Missing one param

Measured

Fit

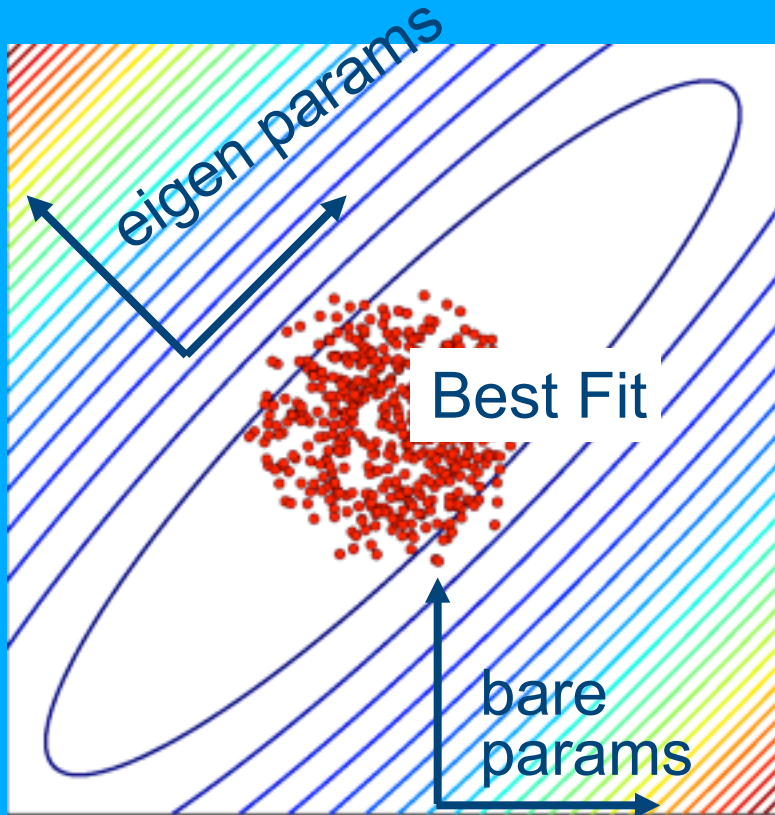


Monte Carlo (anharmonic)

- Easy to Fit (14 expts); Measuring huge job (48 params, 25%)
- One missing parameter measurement = No predictivity
- Sloppy Directions = Enormous Fluctuations in Parameters
- Sloppy Directions often do not impinge on predictivity

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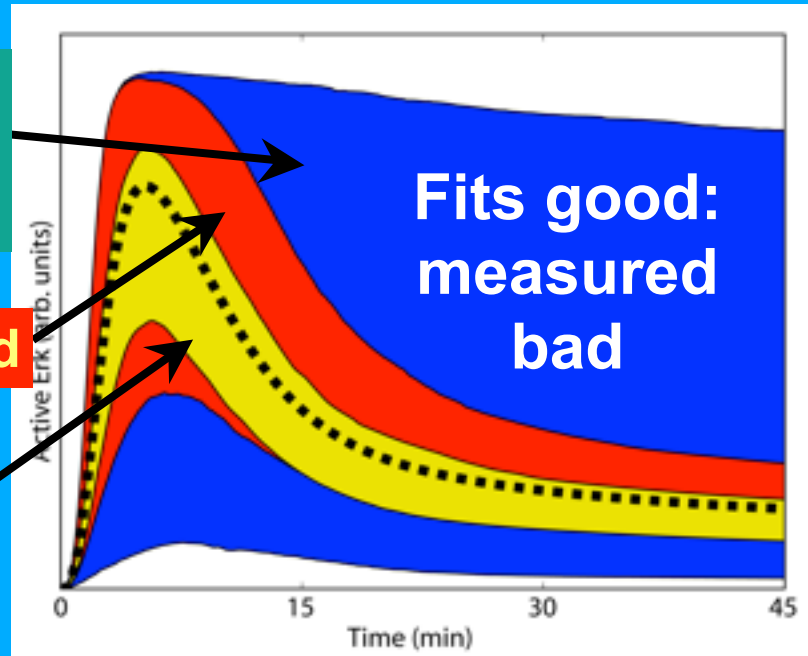
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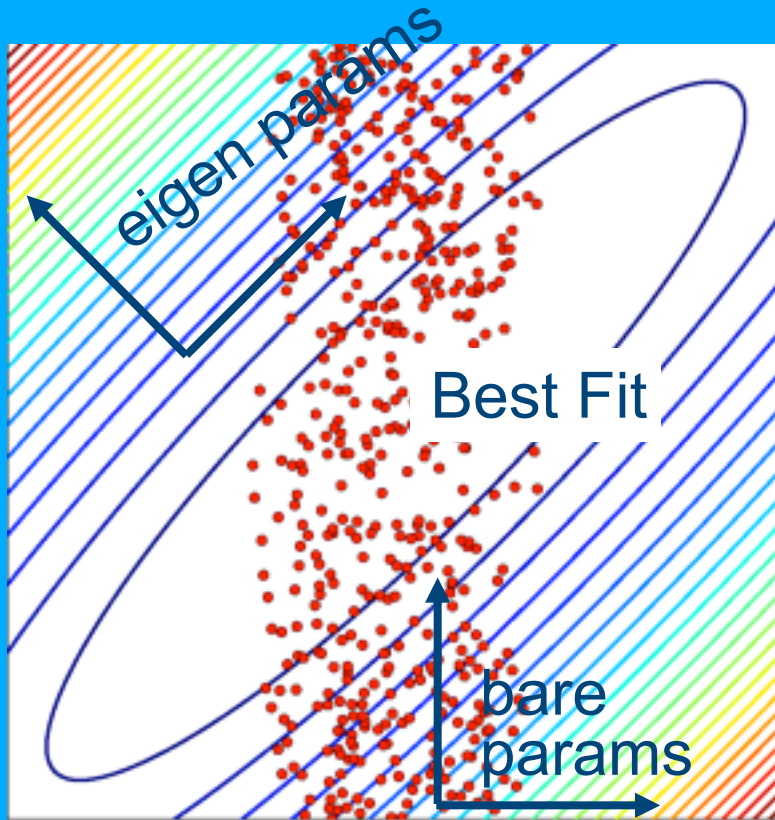


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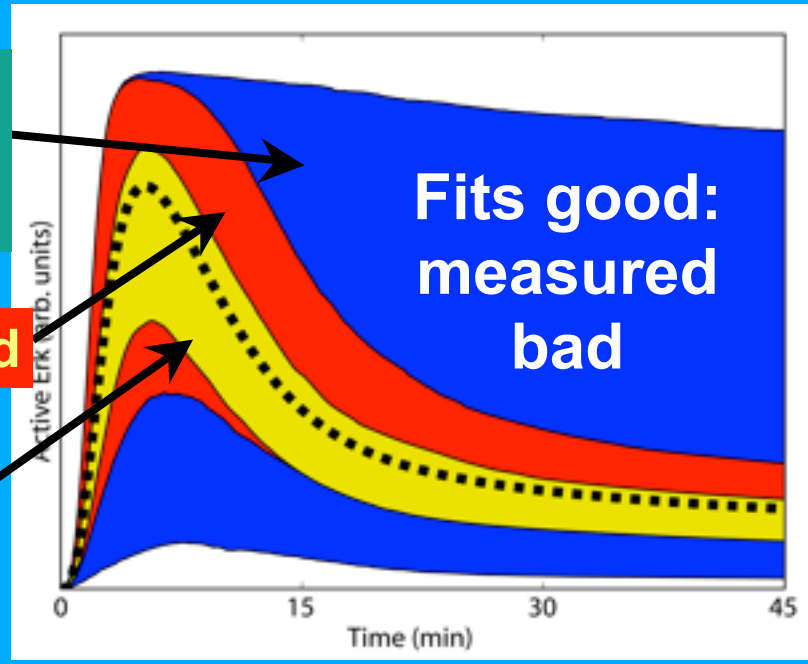
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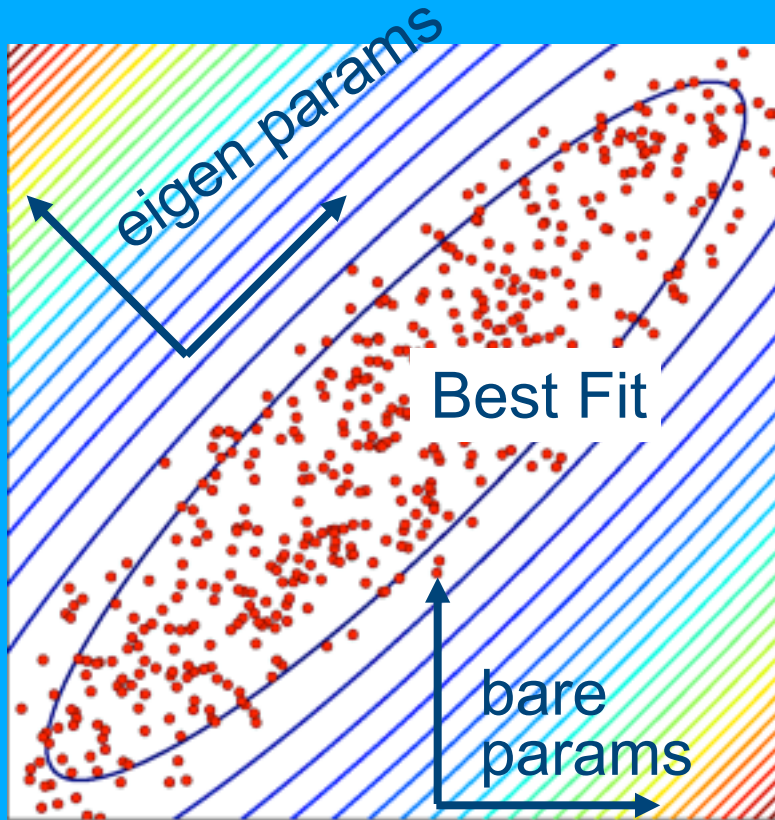


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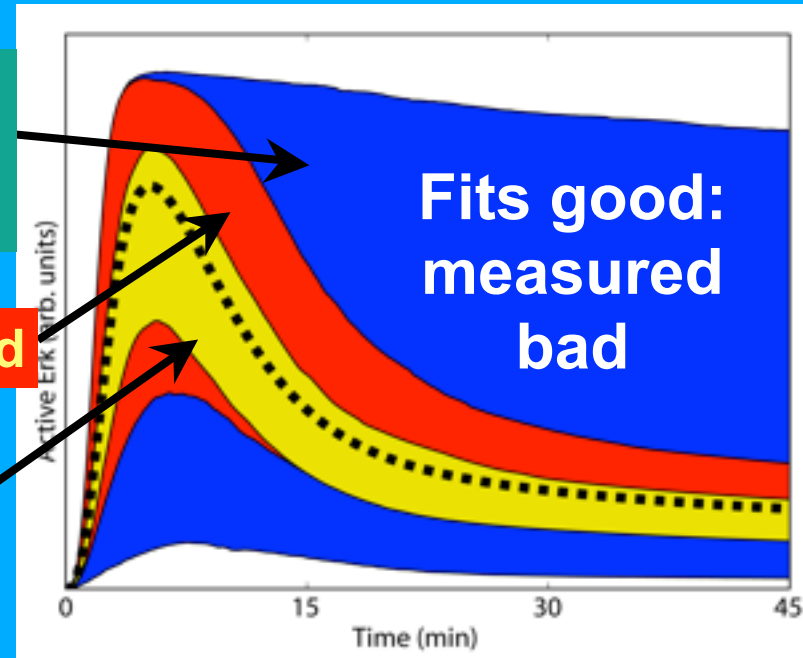
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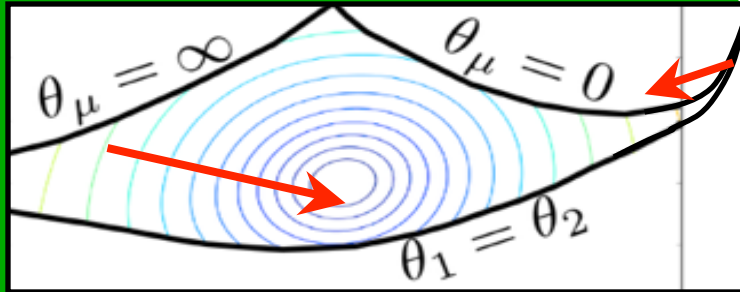
Fit



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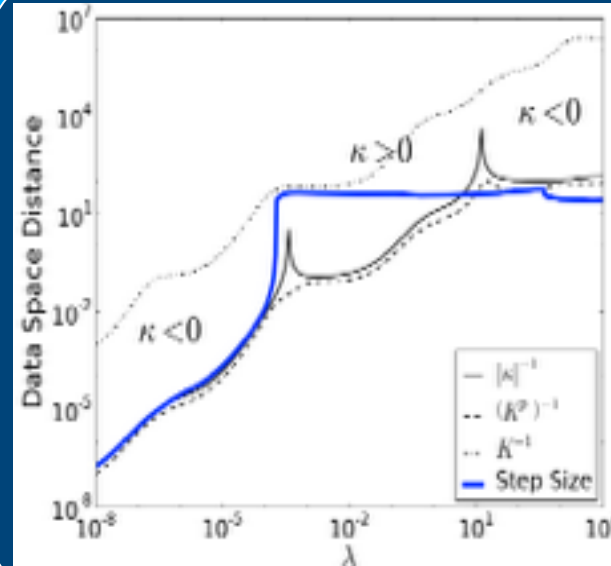
# B. Finding best fits: Geodesic acceleration



Geodesic Paths nearly circles  
Follow local geodesic velocity?

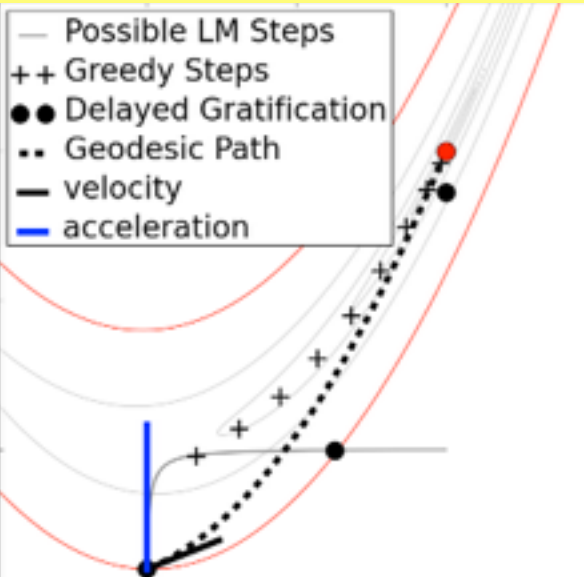
$$\delta\theta^\mu = -g_{\mu\nu} \nabla_\nu C$$

- ➔ Gauss-Newton
- ➔ Hits manifold boundary



## Model Graph

add weight  $\lambda$  of parameter metric yields Levenberg-Marquardt: Step size now limited by curvature



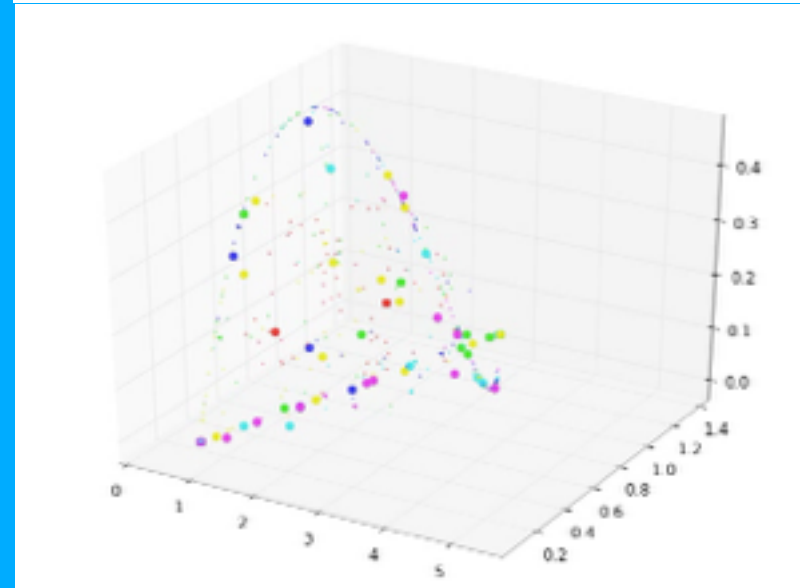
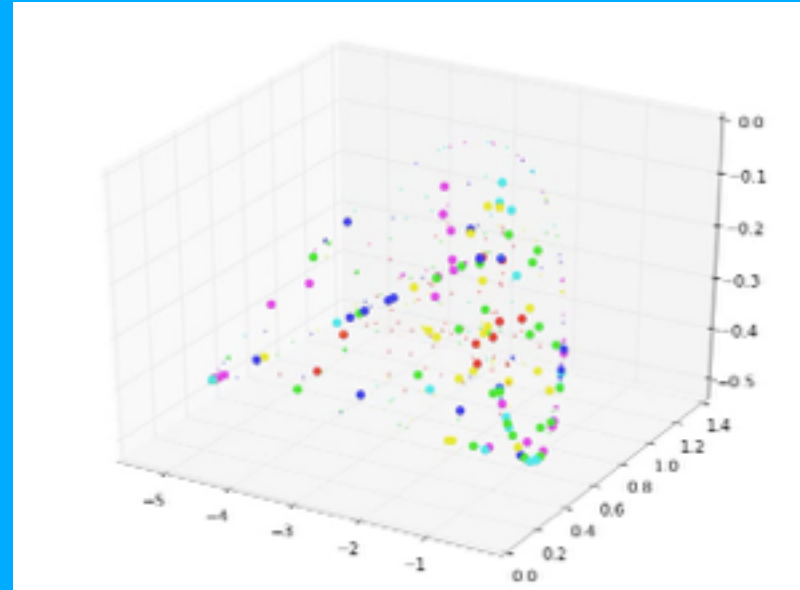
Algorithm	Success Rate	Mean njev	Mean nfev
Traditional LM + accel	65%	258	1494
Traditional LM	33%	2002	4003
Trust Region LM	12%	1517	1649
BFGS	8%	5363	5365

Follow parabola, **geodesic acceleration**  
Cheap to calculate; faster; more success

# B. Finding best fits: Model manifold dynamics (Isabel Kloumann)

*Dynamics on the model manifold: Searching for the best fit*

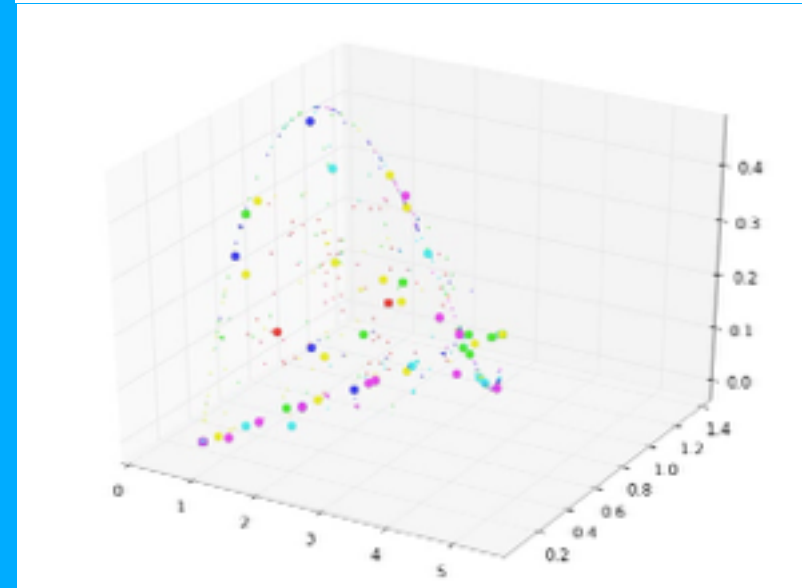
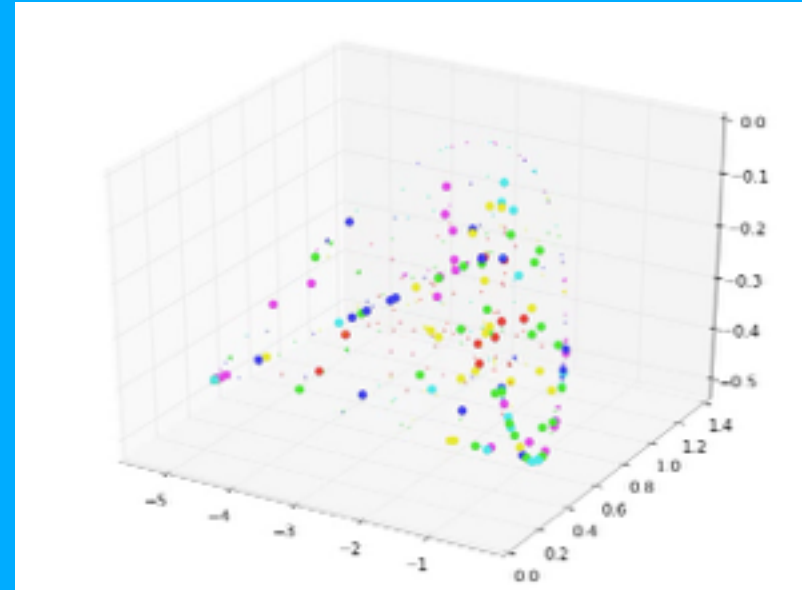
- Jeffrey's prior plus noise
- Big noise concentrates on manifold edges
- Note scales: flat
- Top: Levenberg-Marquardt
- Bottom: Geodesic acceleration
- Large points: Initial conditions which fail to converge to best fit



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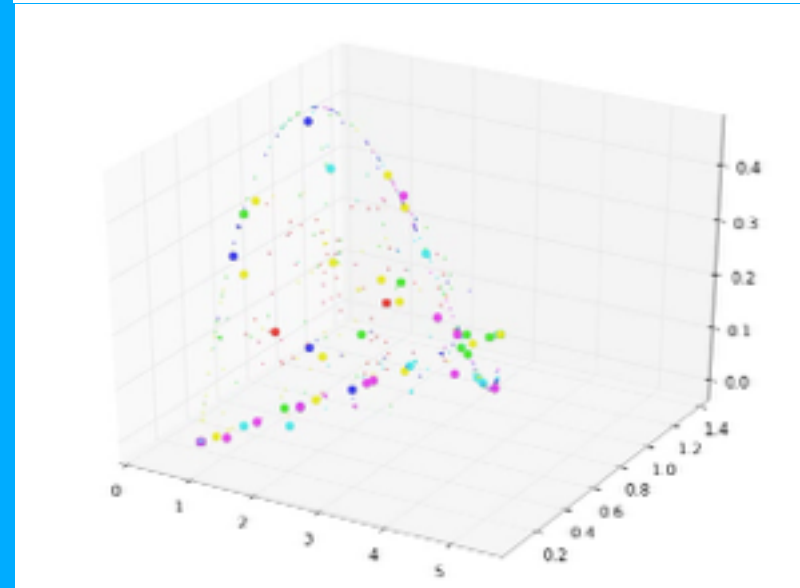
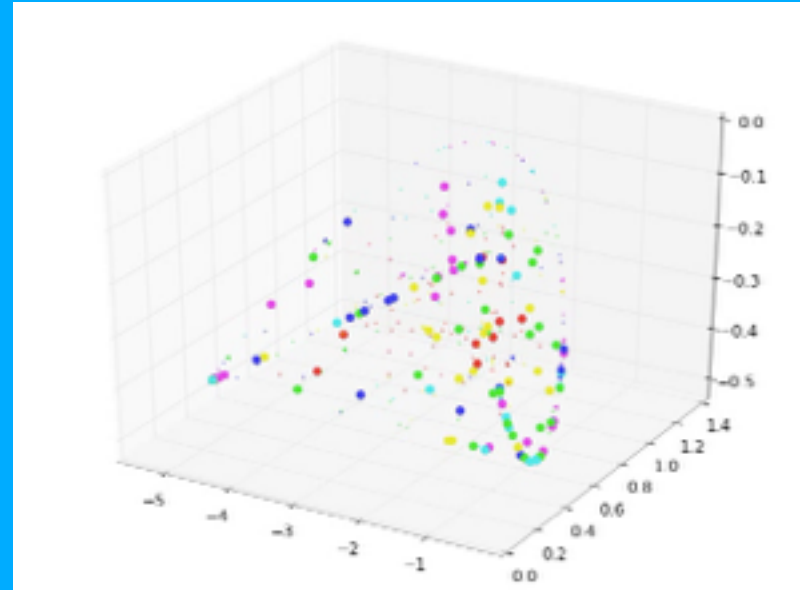




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# C. Generation of Reduced Models

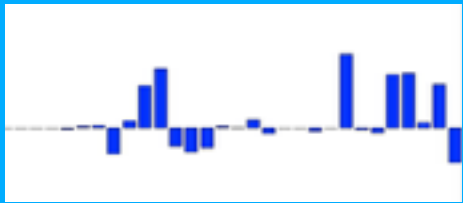
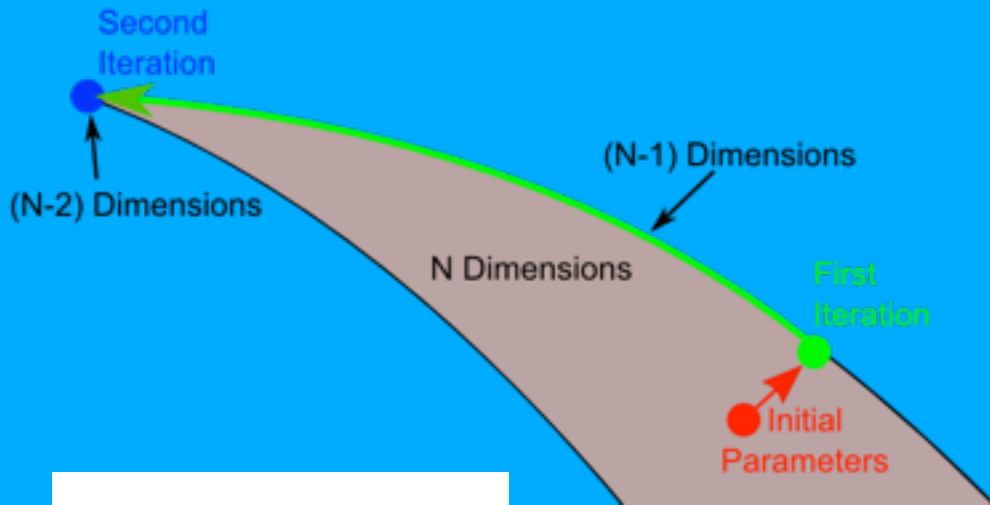
Mark Transtrum (not me)

Can we coarse-grain sloppy models? If most parameter directions are useless, why not remove some?

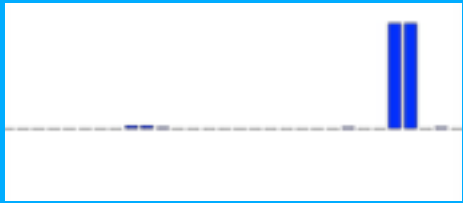
Transtrum has *systematic* method!

- (1) Geodesic along sloppiest direction to nearby point on manifold boundary
- (2) Eigendirection simplifies at model boundary to chemically reasonable simplified model

**Coarse-graining = boundaries of model manifold.**



Sloppiest Eigendirection



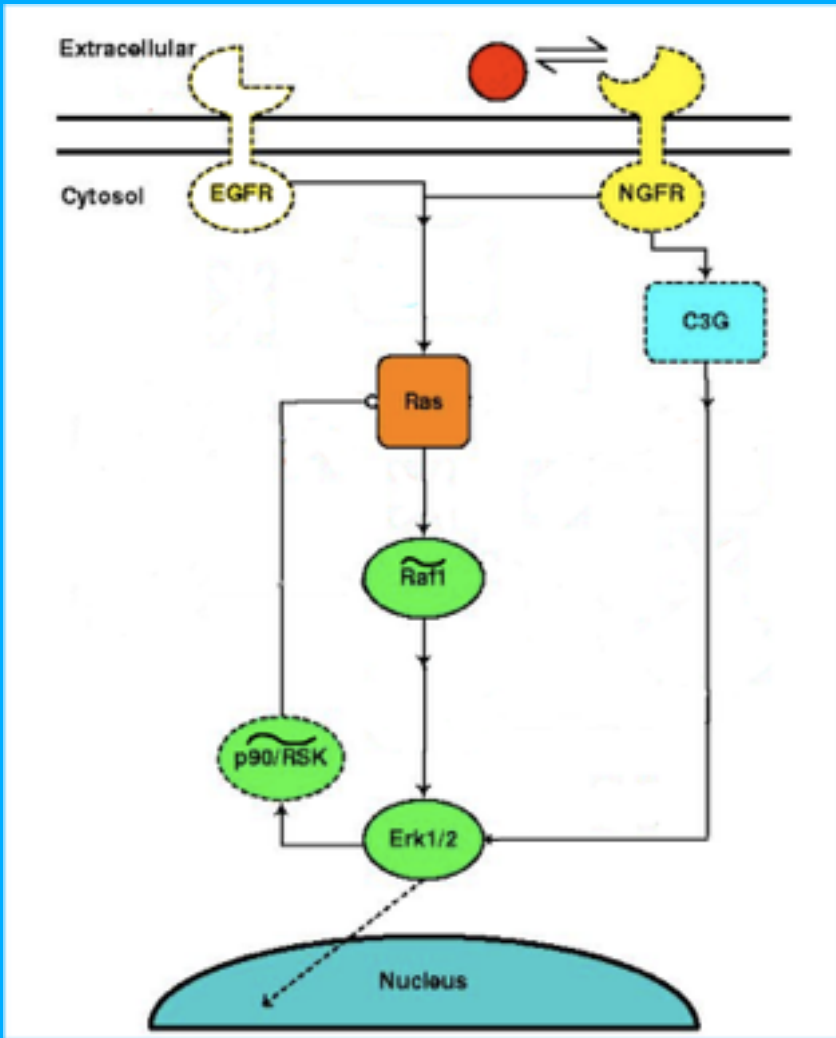
Simplified at Boundary (Unsaturation reaction)



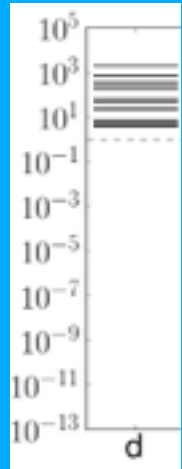


# C. Generation of Reduced Models

Mark Transtrum (not me)



12 params  
6 ODEs



$$[bEGFR] = \begin{cases} 1 & \text{EGF Present} \\ 0 & \text{Otherwise} \end{cases}$$

$$\frac{d}{dt}[bNGFR] = \theta_1[NGF][fNGFR]$$

$$\frac{d}{dt}[NGF] = -\theta_1[NGF][fNGFR]$$

$$\frac{d}{dt}[RasA] = -[RasA][P90RskA] + \theta_2[bEGFR] + \theta_3[bNGFR]$$

$$\frac{d}{dt}[\widetilde{Raf1A}] = \theta_4[RasA] - \theta_5[\widetilde{Raf1A}]/([\widetilde{Raf1A}] + \theta_6)$$

$$\frac{d}{dt}[C3GA] = \theta_7[bNGFR][C3GI]$$

$$[Rap1A] = \theta_8[C3GA]$$

$$[MekA] = [\widetilde{Raf1A}][MekI] + \theta_9[Rap1A]$$

$$\frac{d}{dt}[Erk] = -\theta_{10}[ErkA] + \theta_{11}[MekA][ErkI]$$

$$\frac{d}{dt}[\widetilde{P90RskA}] = \theta_{12}[ErkA]$$

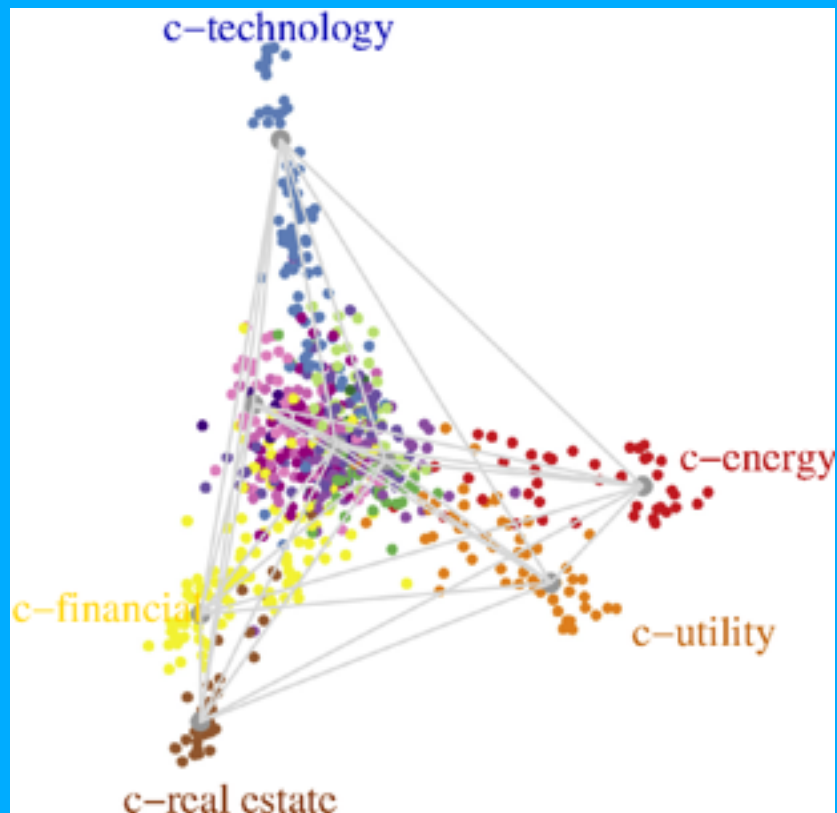
Reduced model fits all experimental data

$$\theta_9 = \frac{[BRafI] kRap1toBRaf KmdBRAF kpBRaf KmdMek}{[PP2AA] [Raf1PPtase] kdBRaf KmRap1toBRaf kdMek}$$

Effective 'renormalized' params

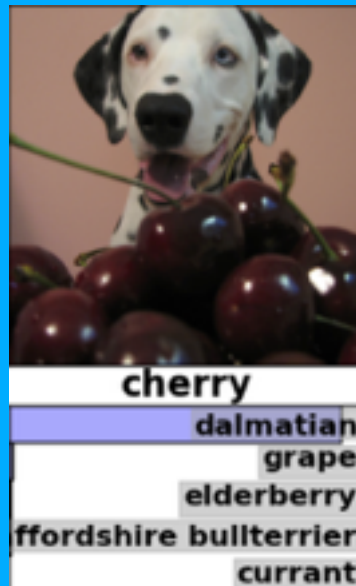
# D. Machine Learning

Ricky Chachra, Alex Alemi, Paul Ginsparg



Stock Returns Decomposed into 'Canonical' Sectors (unsupervised learning)

Low dimensional representations of high-dimensional data

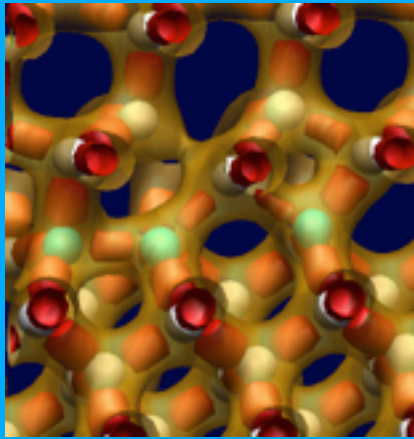


Neural Networks categorize images

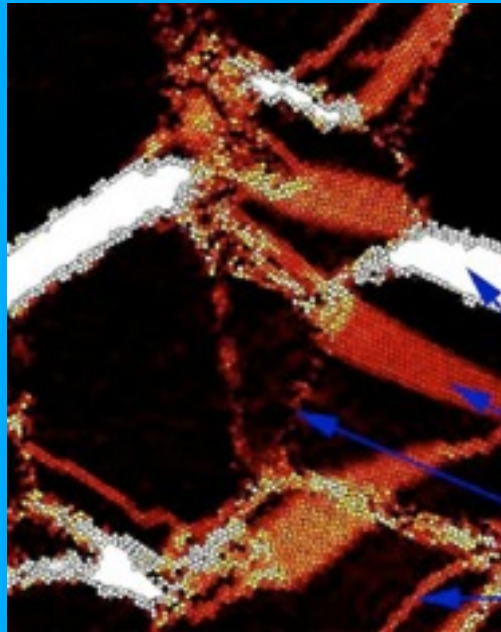
# E. Bayesian Errors for Atoms

'Sloppy Model' Approach to Error Estimation of Interatomic Potentials

Søren Frederiksen, Karsten W. Jacobsen, Kevin Brown, JPS



Quantum  
Electronic  
Structure (Si)  
90 atoms (Mo)  
(Arias)



Atomistic potential  
820,000 Mo atoms  
(Jacobsen, Schiøtz)

Interatomic Potentials  $V(r_1, r_2, \dots)$

- Fast to compute
- Limit  $m_e/M \rightarrow 0$  justified
- Guess functional form  
Pair potential  $\sum V(r_i - r_j)$  poor  
Bond angle dependence  
Coordination dependence
- Fit to experiment (old)
- Fit to forces from electronic structure calculations (new)

**17 Parameter Fit**

# E. Interatomic Potential Error Bars

Ensemble of Acceptable Fits to Data

Not *transferable*

Unknown errors

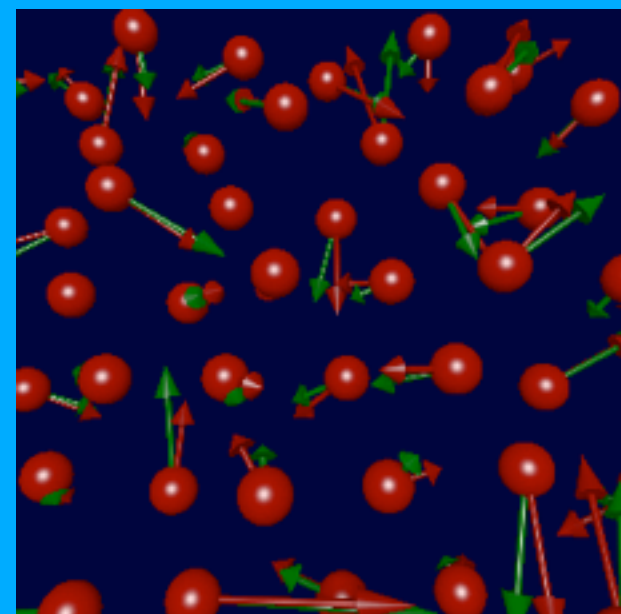
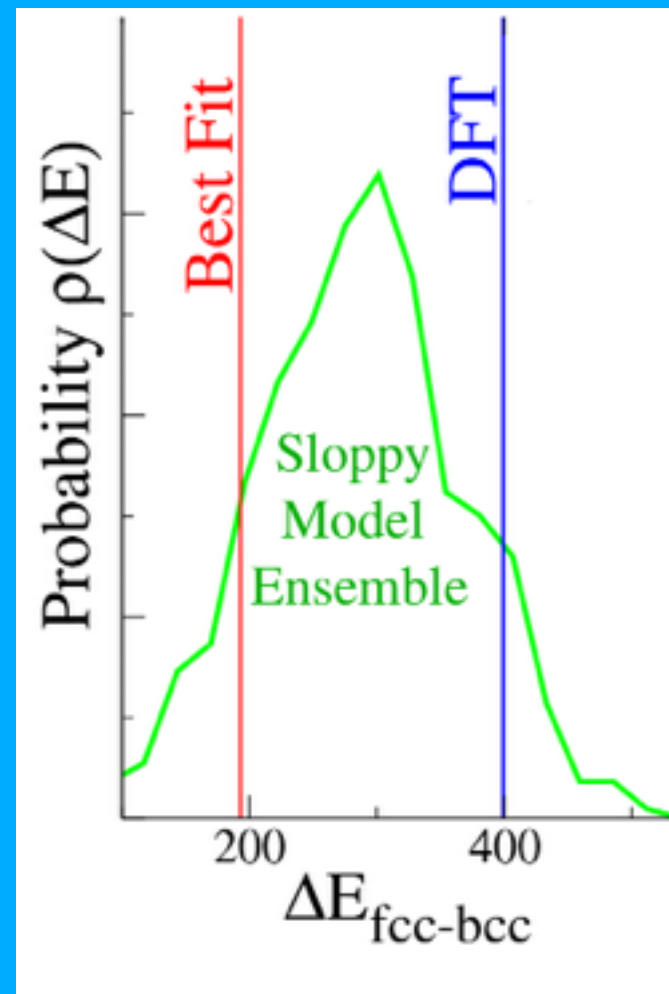
- 3% elastic constant
- 10% forces
- 100% fcc-bcc, dislocation core

Best fit is *sloppy*: ensemble of fits that aren't much worse than best fit.

**Ensemble in Model Space!**

$T_0$  set by equipartition energy = best cost

Error Bars from quality of best fit



Green = DFT, Red = Fits

# E. Interatomic Potential Error Bars

Ensemble of Acceptable Fits to Data

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Unknown errors

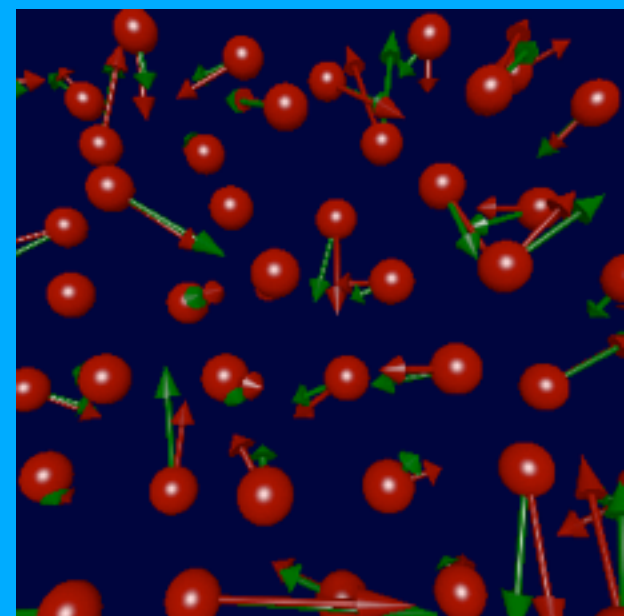
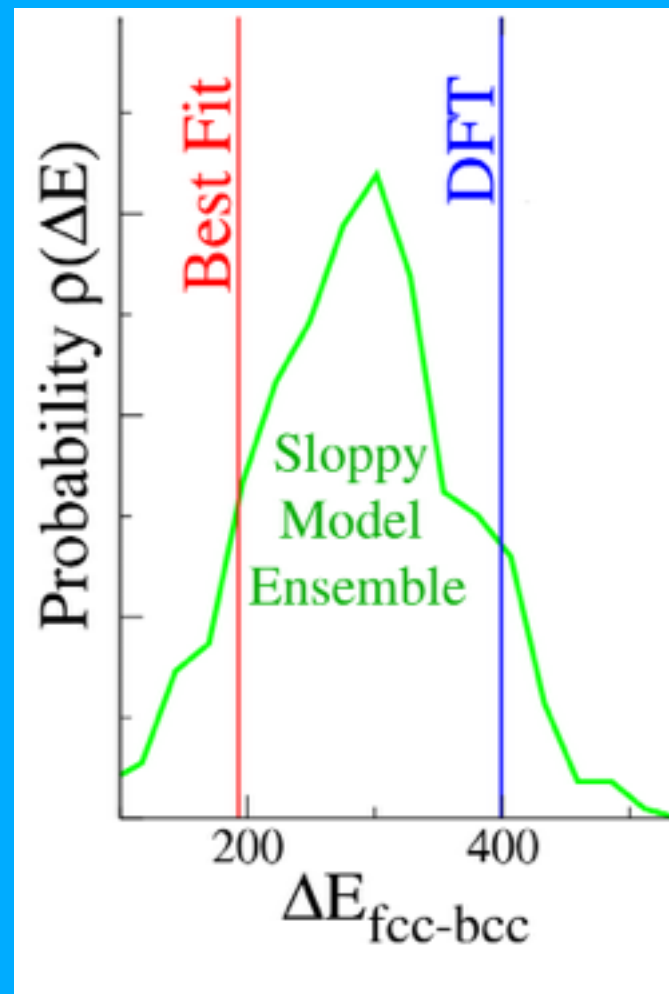
- 3% elastic constant
- 10% forces
- 100% fcc-bcc, dislocation core

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**Ensemble in Model Space!**

$T_0$  set by equipartition energy = best cost

Error Bars from quality of best fit



Green = DFT, Red = Fits



# Sloppy Molybdenum: Does it Work?

## Estimating *Systematic* Errors

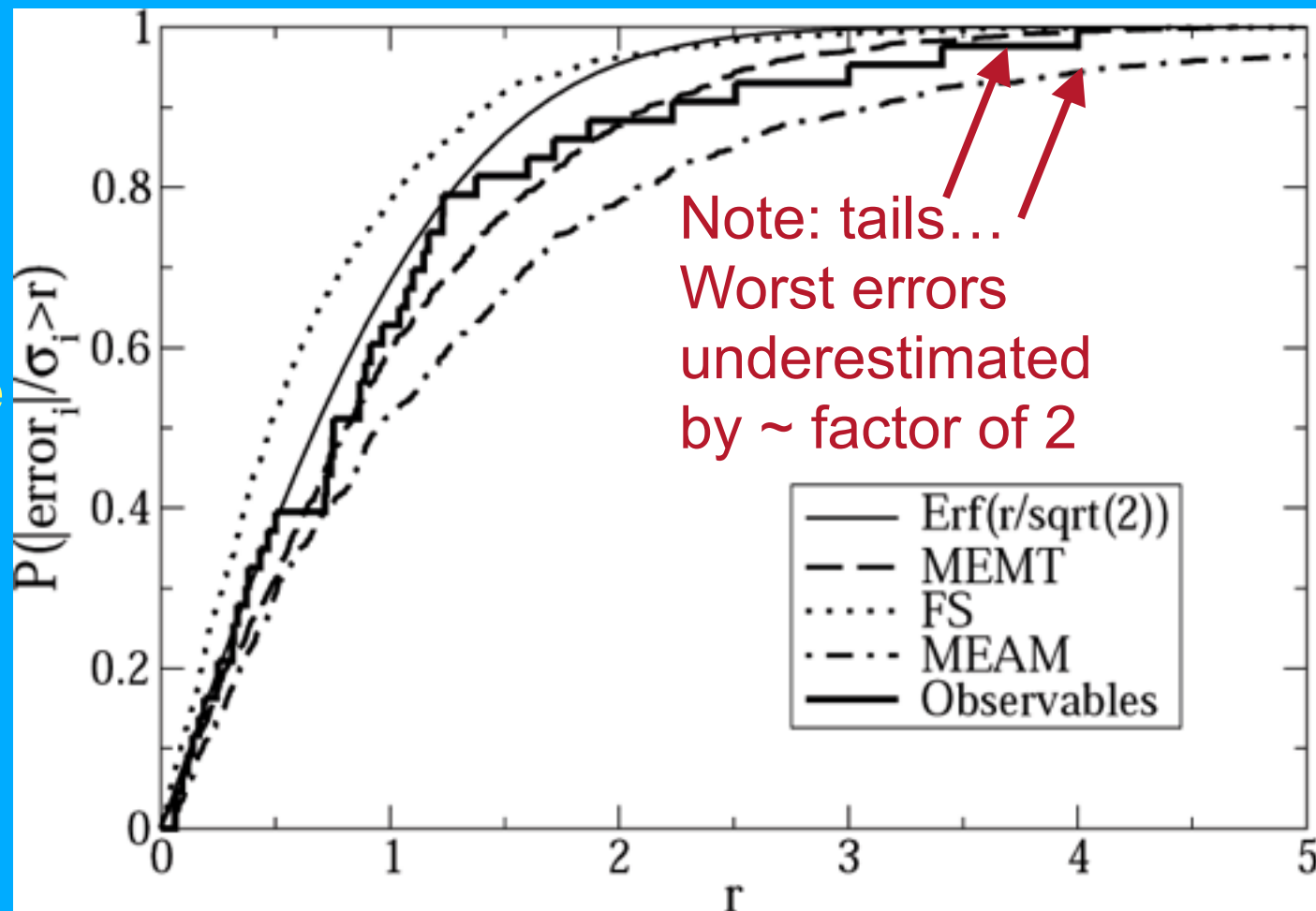
Bayesian error  $\sigma_i$  gives total error if ratio  $r = \text{error}_i/\sigma_i$  distributed as a Gaussian: cumulative distribution  $P(r) = \text{Erf}(r/\sqrt{2})$

### Three potentials

- Force errors
- Elastic moduli
- Surfaces
- Structural
- Dislocation core
- $7\% < \sigma_i < 200\%$

“Sloppy model”  
systematic  
error most of  
total

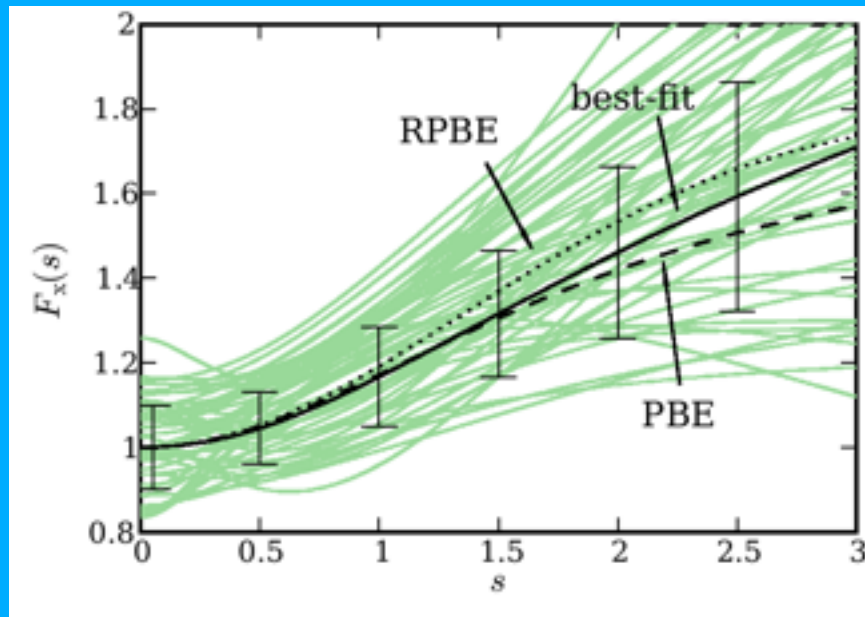
$\sim 2 \ll 200\%/7\%$



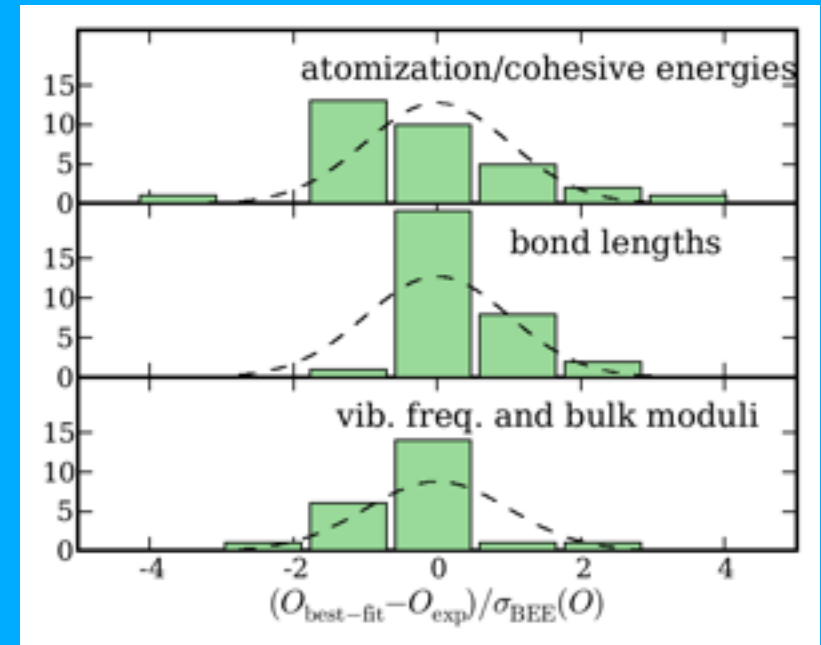
# Systematic Error Estimates for DFT

## GGA-DFT as Multiparameter Fit?

J. J. Mortensen, K. Kaasbjerg, S. L. Frederiksen,  
J. K. Nørskov, JPS, K. W. Jacobsen,  
(Anja Tuftelund, Vivien Petzold, Thomas Bligaard)



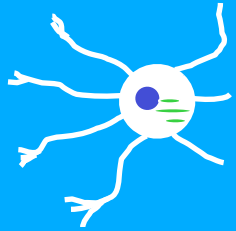
Enhancement factor  $F_x(s)$   
in the exchange energy  $E_x$   
**Large fluctuations**



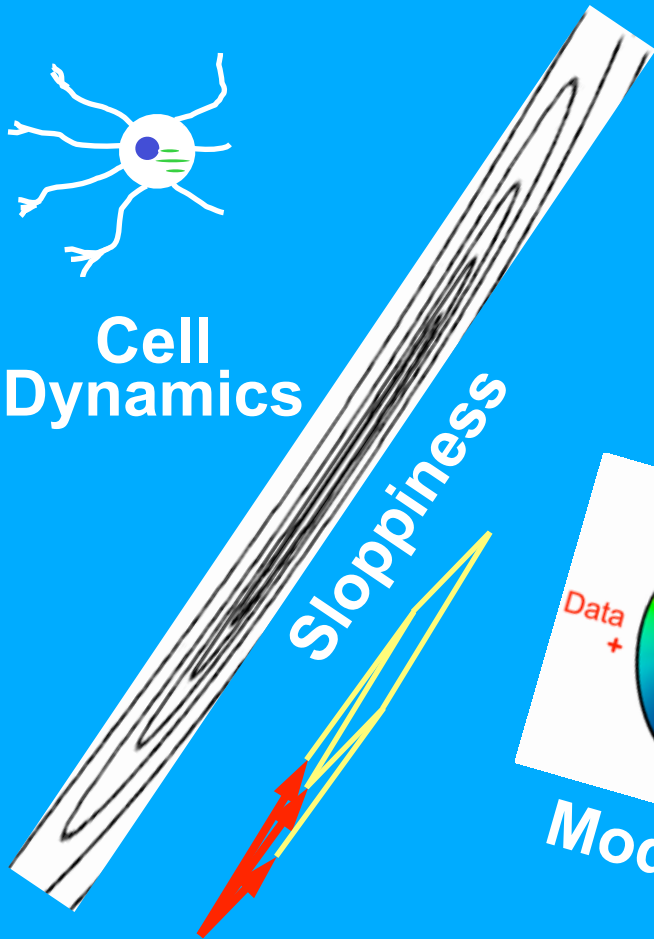
Actual error / predicted error  
**Deviation from experiment  
well described by ensemble!**

# 'Sloppy Model' Nonlinear Fits: Signal Transduction to Differential Geometry

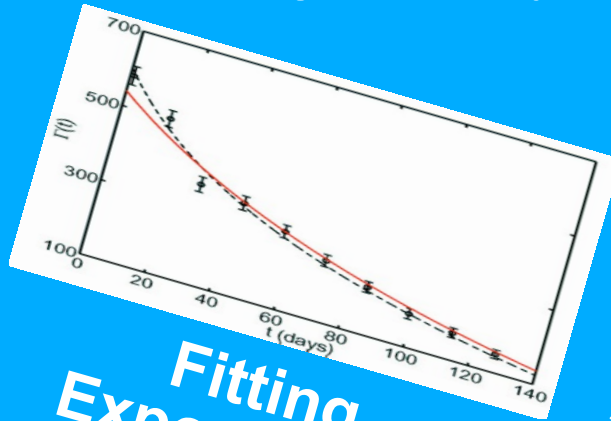
JPS, Mark Transtrum, Ben Machta, Ricky Chachra, Lorien Hayden, Alex Alemi, Isabel Kloumann, Colin Clement, Kevin Brown, Ryan Gutenkunst, Josh Waterfall, Paul Ginsparg, Chris Myers, ...



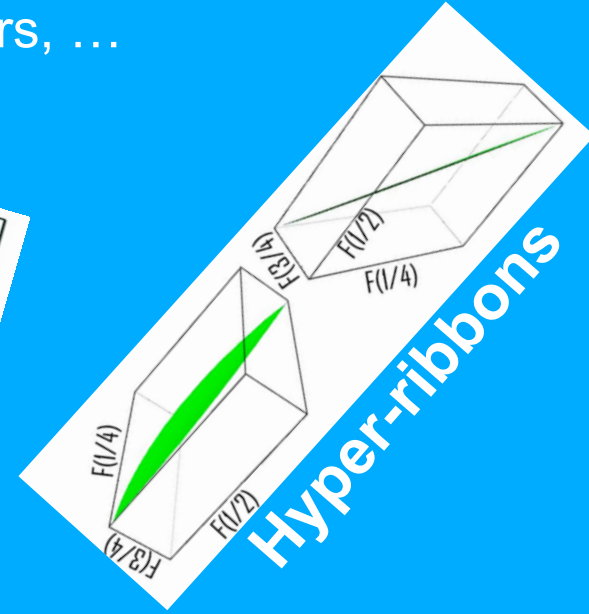
Cell Dynamics



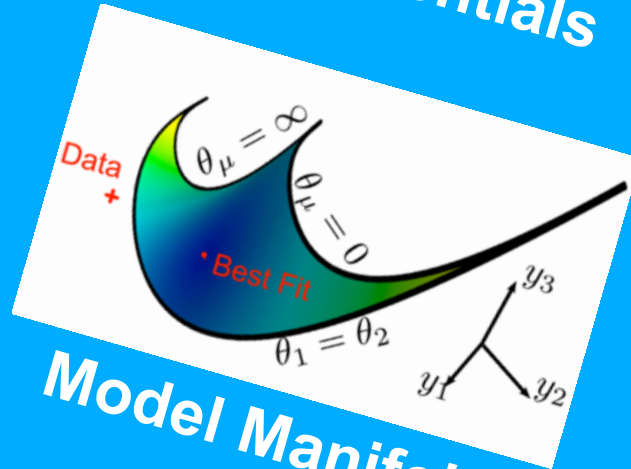
Sloppiness



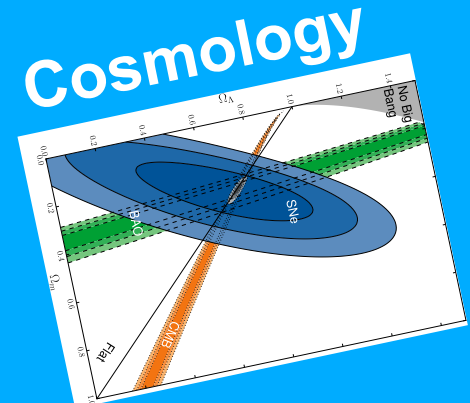
Fitting Exponentials



Hyper-ribbons



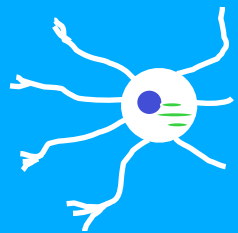
Model Manifold



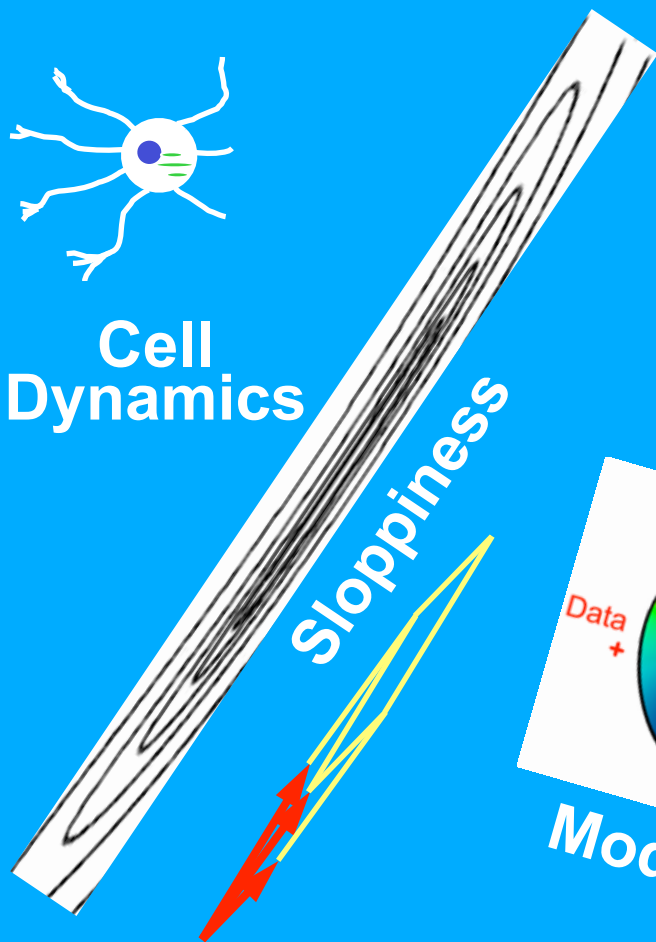
Cosmology

# 'Sloppy Model' Nonlinear Fits: Signal Transduction to Differential Geometry

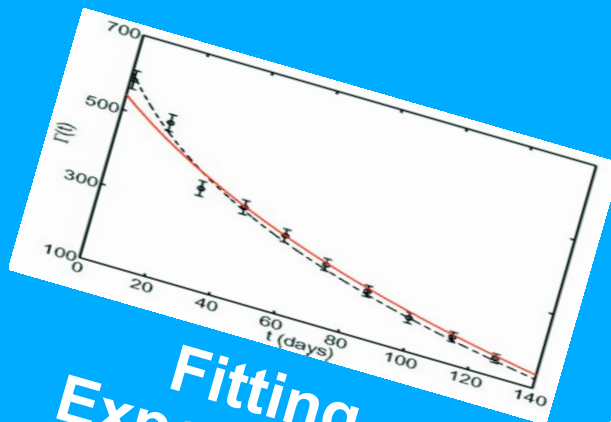
JPS, Mark Transtrum, Ben Machta, Ricky Chachra, Isabel Kloumann, Kevin Brown, Ryan Gutenkunst, Josh Waterfall, Chris Myers, ...



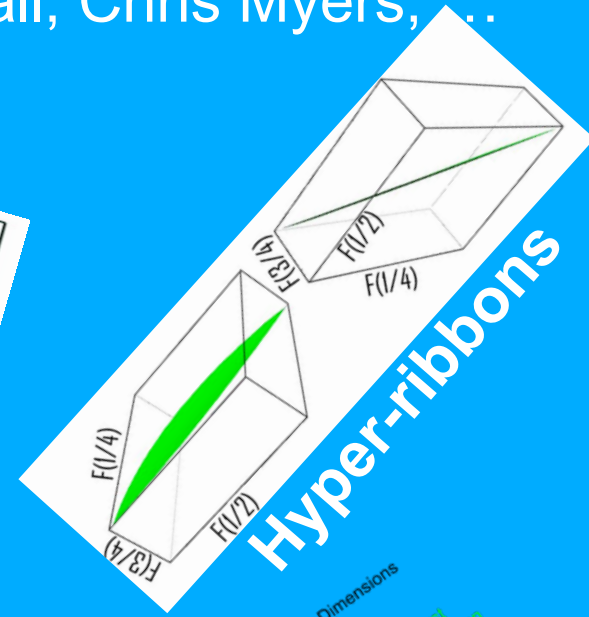
Cell Dynamics



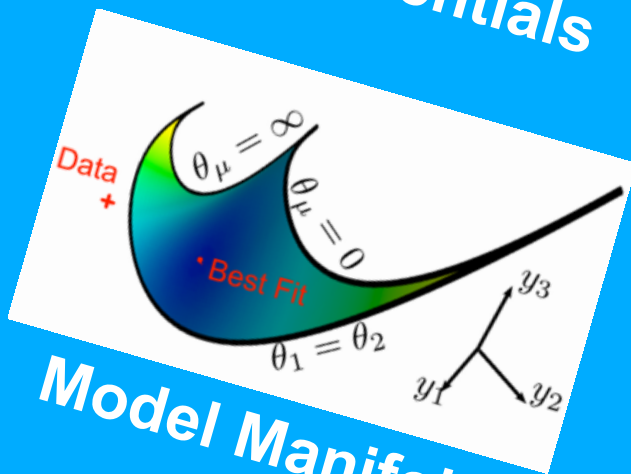
Sloppiness



Fitting Exponentials



Hyper-ribbons



Model Manifold

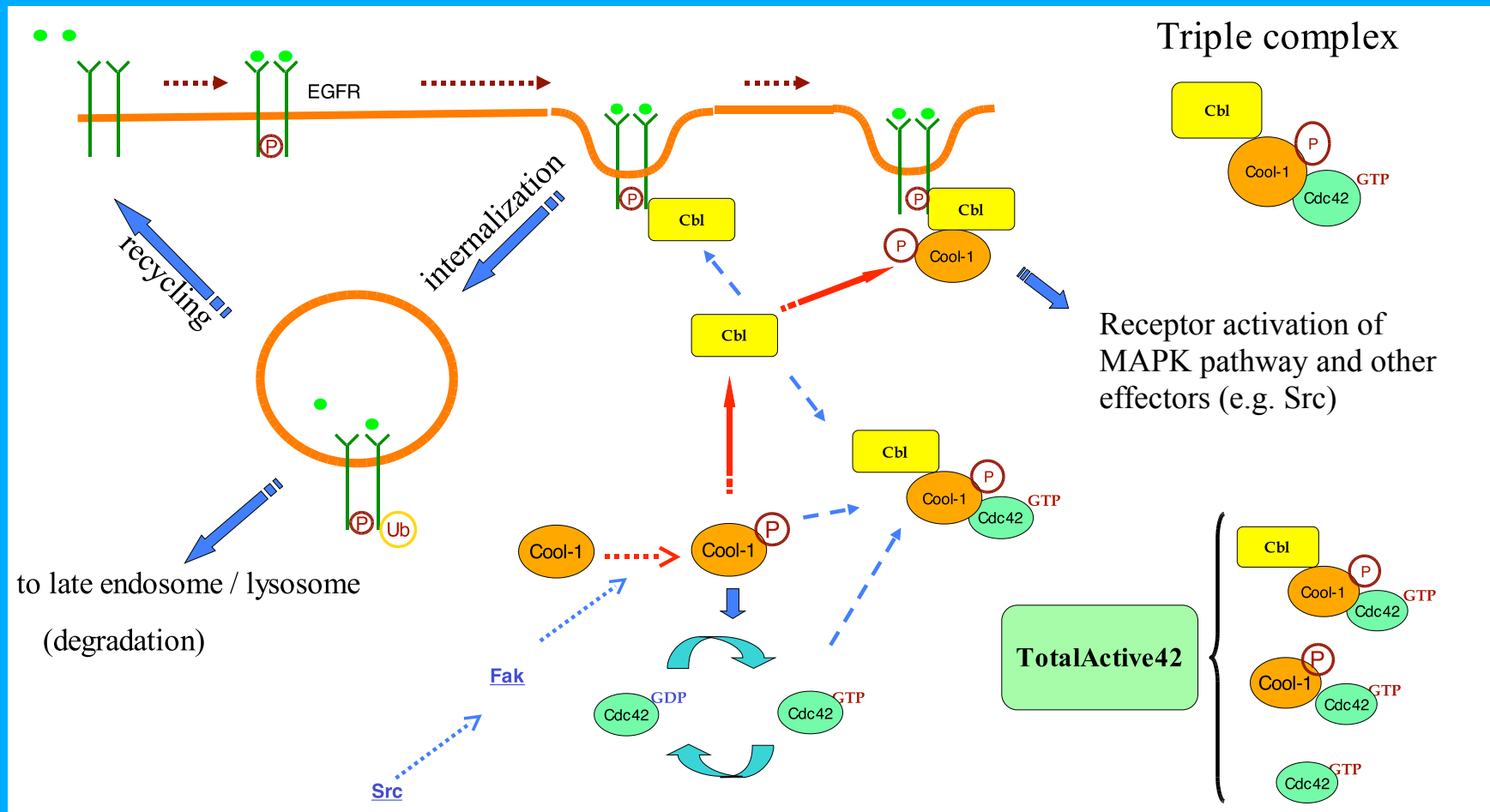


Coarse-Grained Models

# C. EGFR Trafficking Model

Fergal Casey, Cerione lab

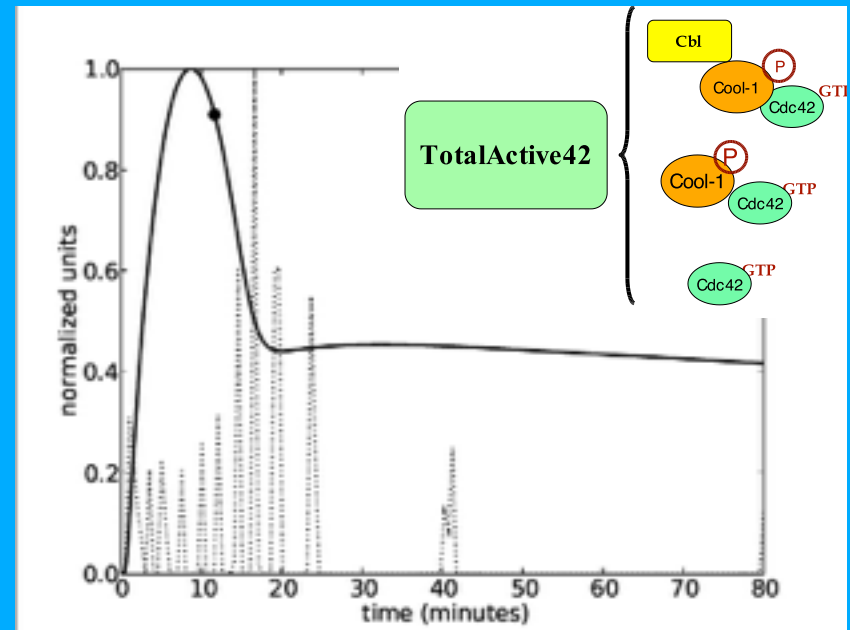
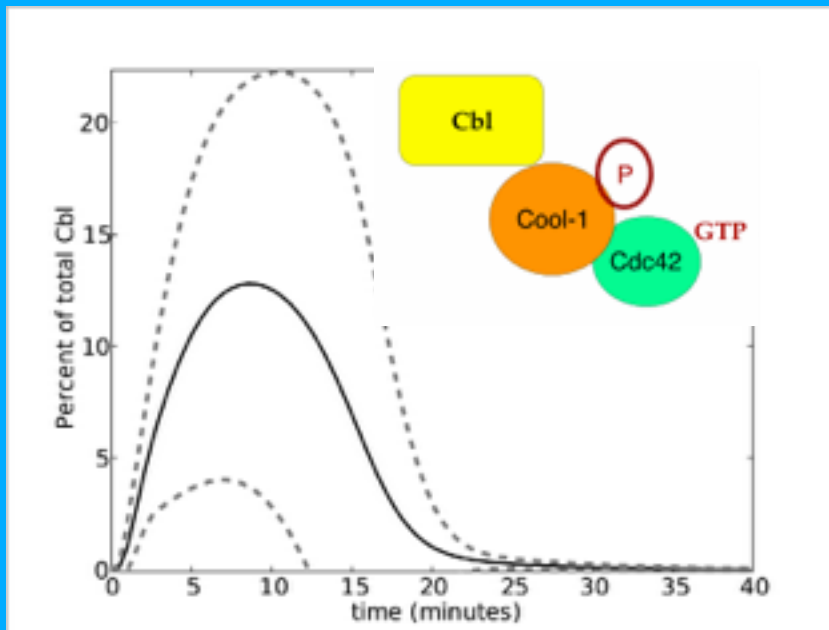
- Active research, Cerione lab: testing hypothesis, experimental design (Cool1 $\equiv$  $\beta$ -PIX)
- 41 chemicals, 53 rate constants; only 11 of 41 species can be measured
- Does Cool-1 triple complex sequester Cbl, delay endocytosis in wild type NIH3T3 cells?



# C. Trafficking: experimental design

Which experiment best reduces prediction uncertainty?

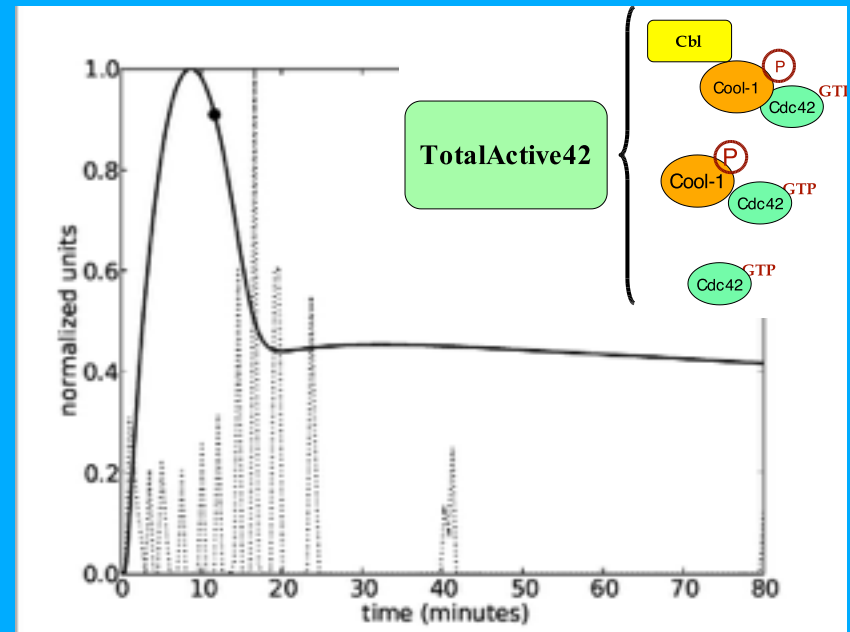
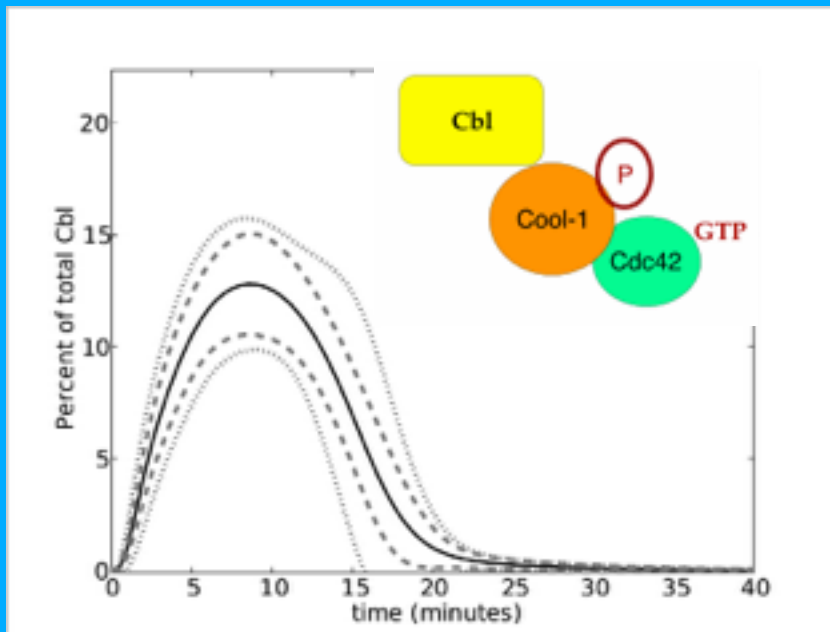
- Amount of triple complex was not well predicted
- V-optimal experimental design: single & multiple measurements
- Total active Cdc42 at 10 min.; Cerione independently concurs
- Experiment indicates significant sequestering in wild type
- Predictivity without decreasing parameter uncertainty



# C. Trafficking: experimental design

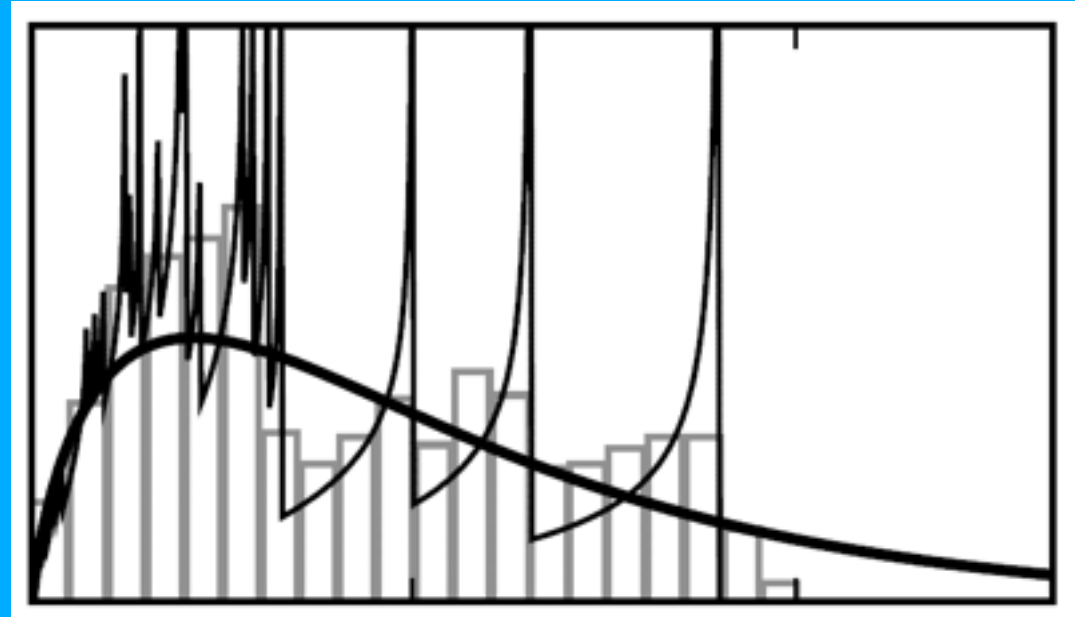
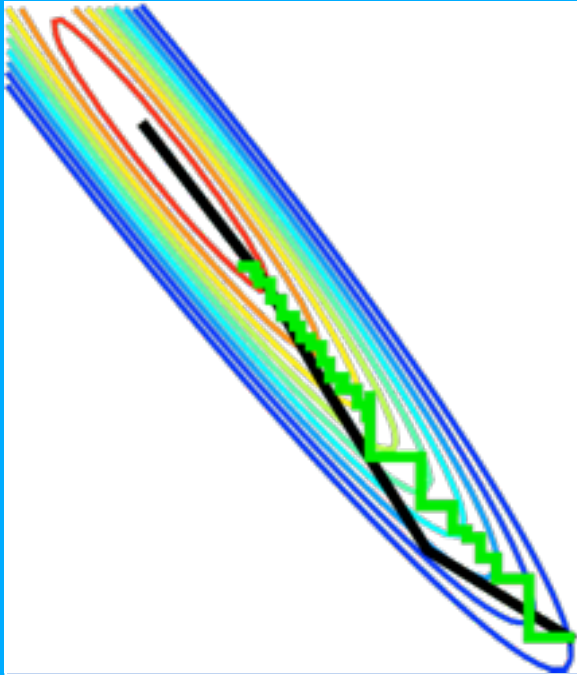
Which experiment best reduces prediction uncertainty?

- Amount of triple complex was not well predicted
- V-optimal experimental design: single & multiple measurements
- Total active Cdc42 at 10 min.; Cerione independently concurs
- Experiment indicates significant sequestering in wild type
- Predictivity without decreasing parameter uncertainty



# D. Evolution in Chemotype space

## Implications of sloppiness?



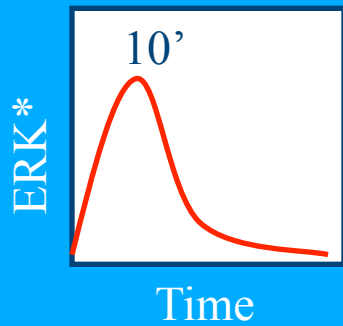
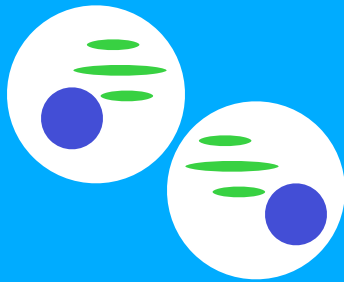
Fitness gain from first successful mutation

- Culture of identical bacteria, one mutation at a time
- Mutation changes one or two rate constants (no *pleiotropy*): orthogonal moves in rate constant (chemotype) space
- **Cusps** in first fitness gain (one for each rate constant, big gap)
- Multiple mutations get stuck on ridge in sloppy landscape

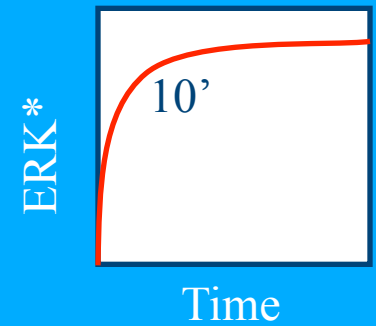
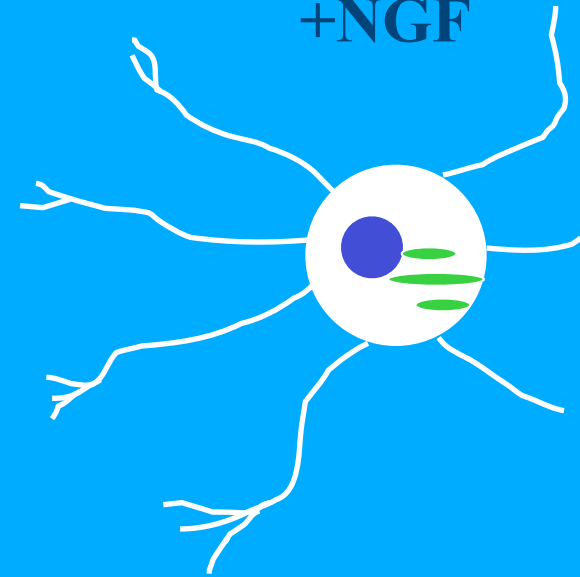


# PC12 Differentiation

+EGF



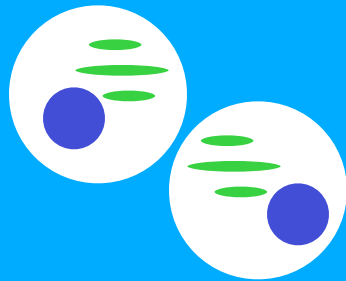
+NGF



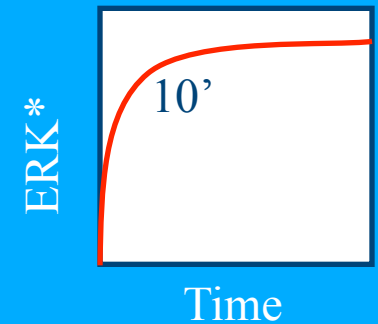
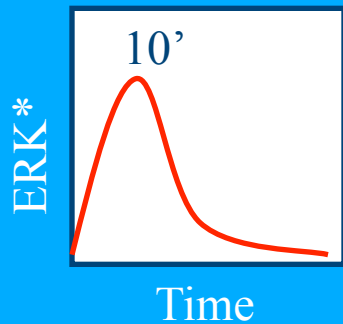
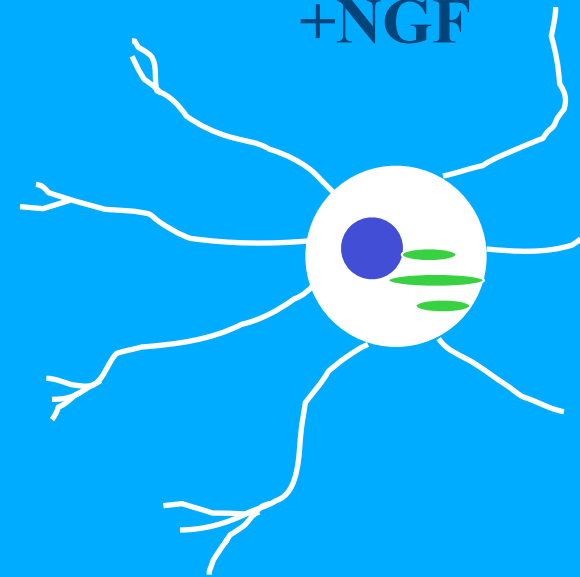
Biologists study which proteins talk to which. Modeling?

# PC12 Differentiation

+EGF



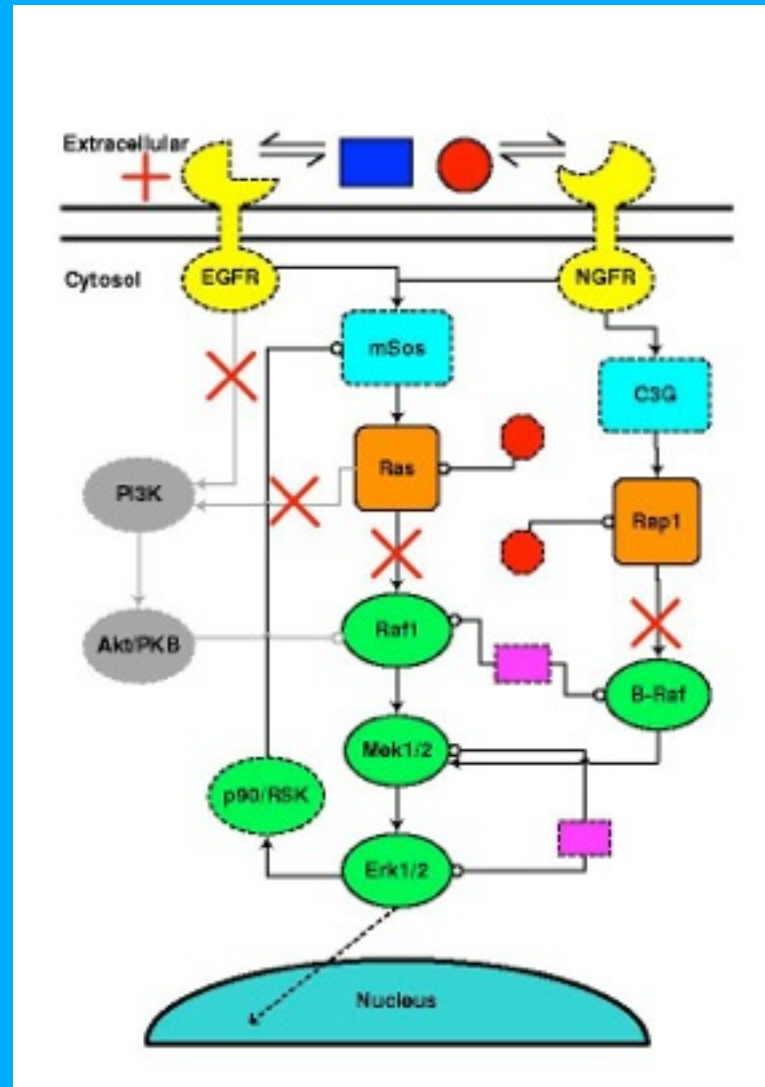
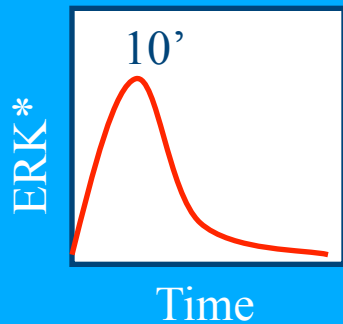
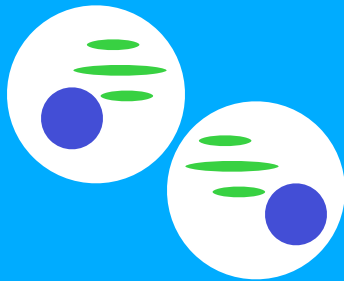
+NGF



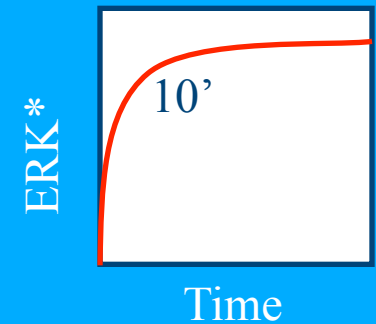
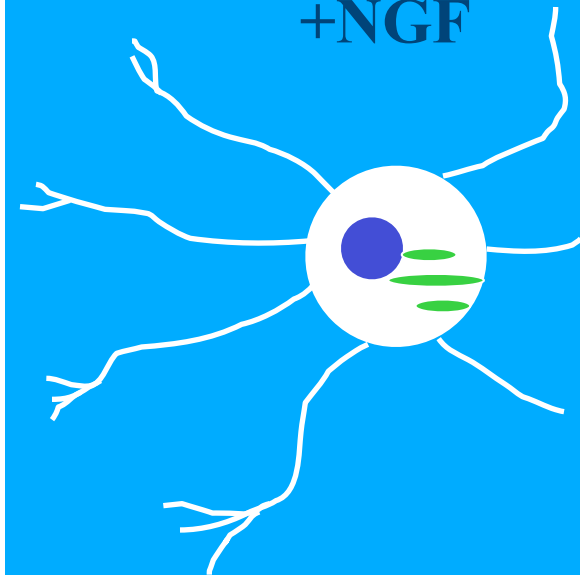
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# PC12 Differentiation

+EGF

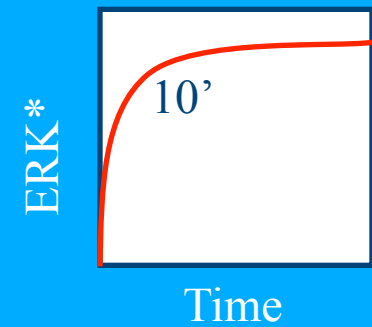
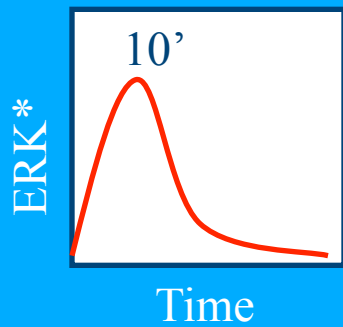
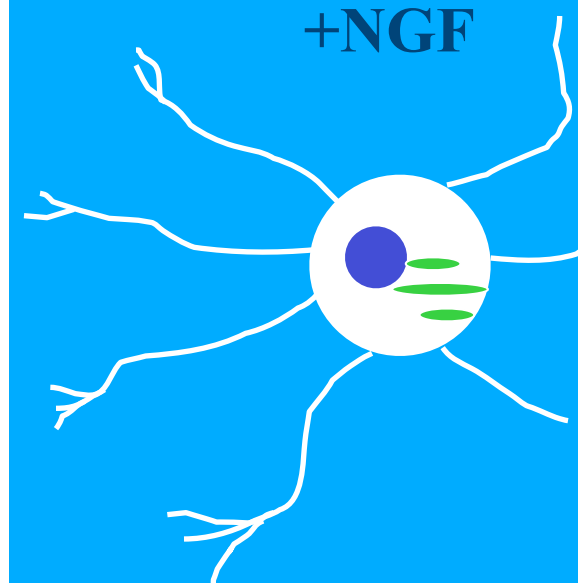
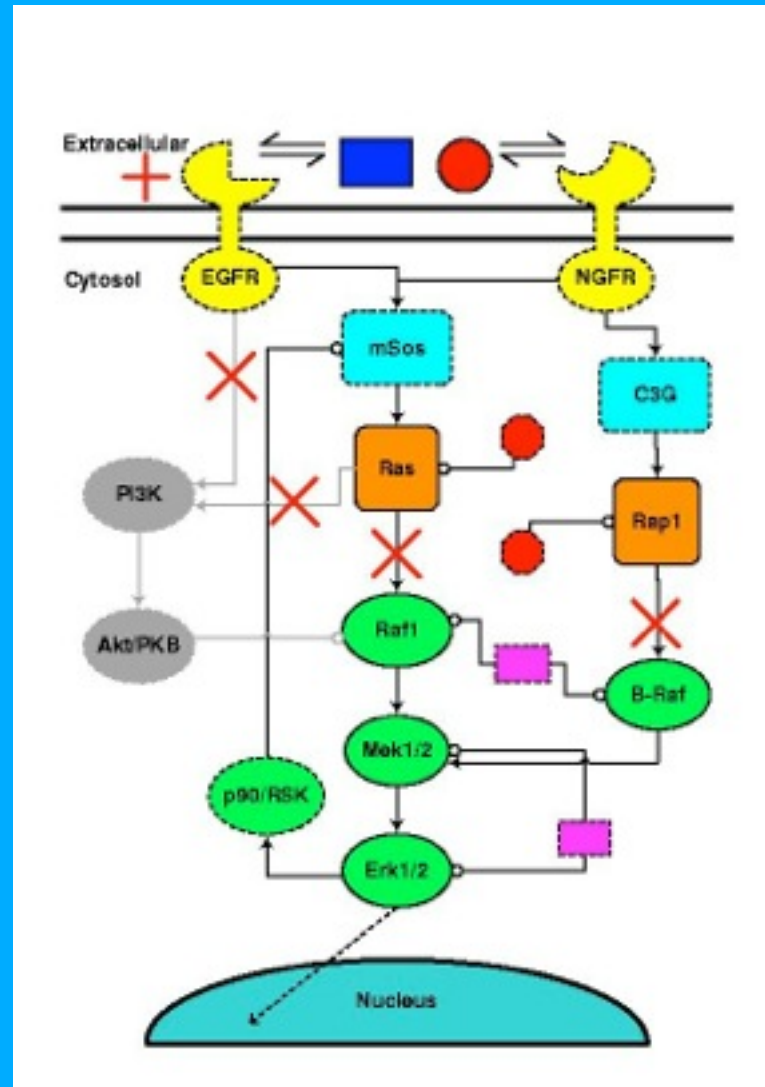


+NGF



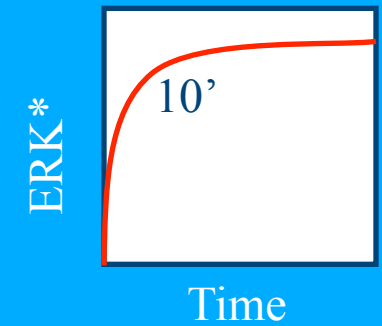
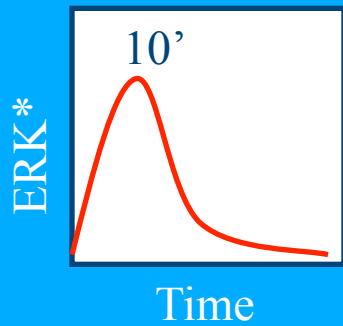
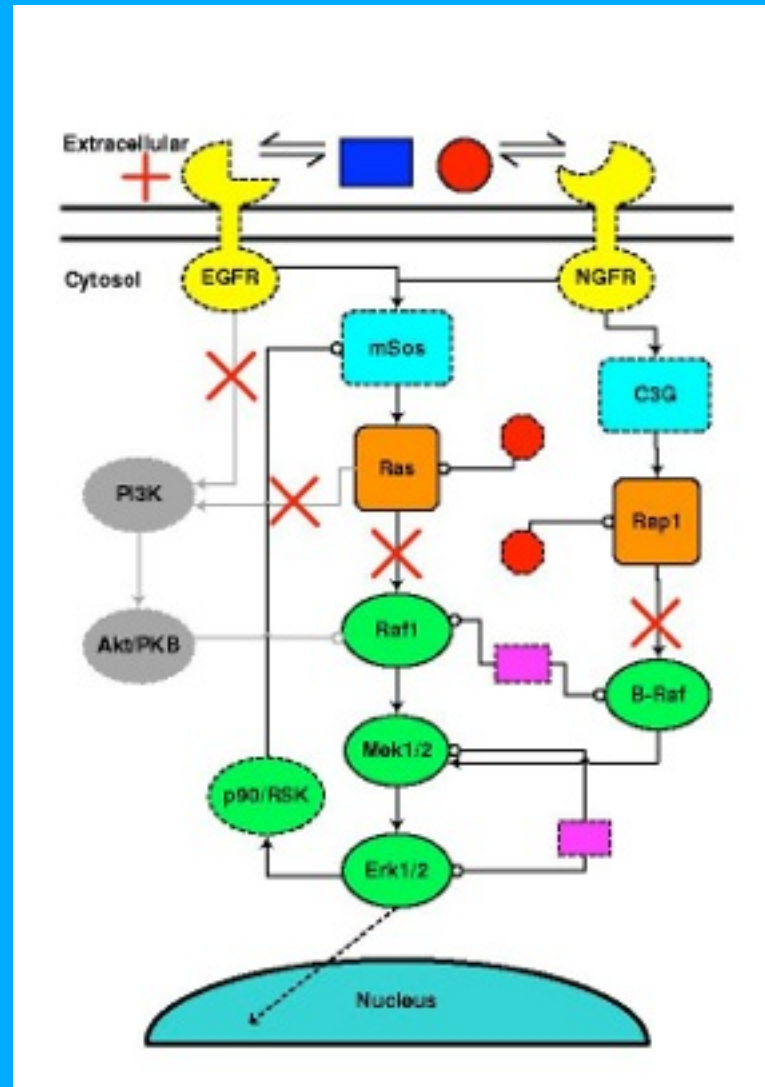
Biologists study which proteins talk to which. Modeling?

# PC12 Differentiation



Biologists study which proteins talk to which. Modeling?

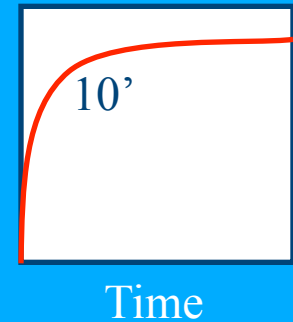
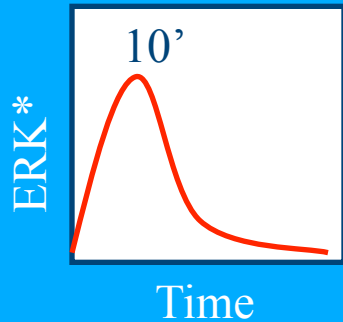
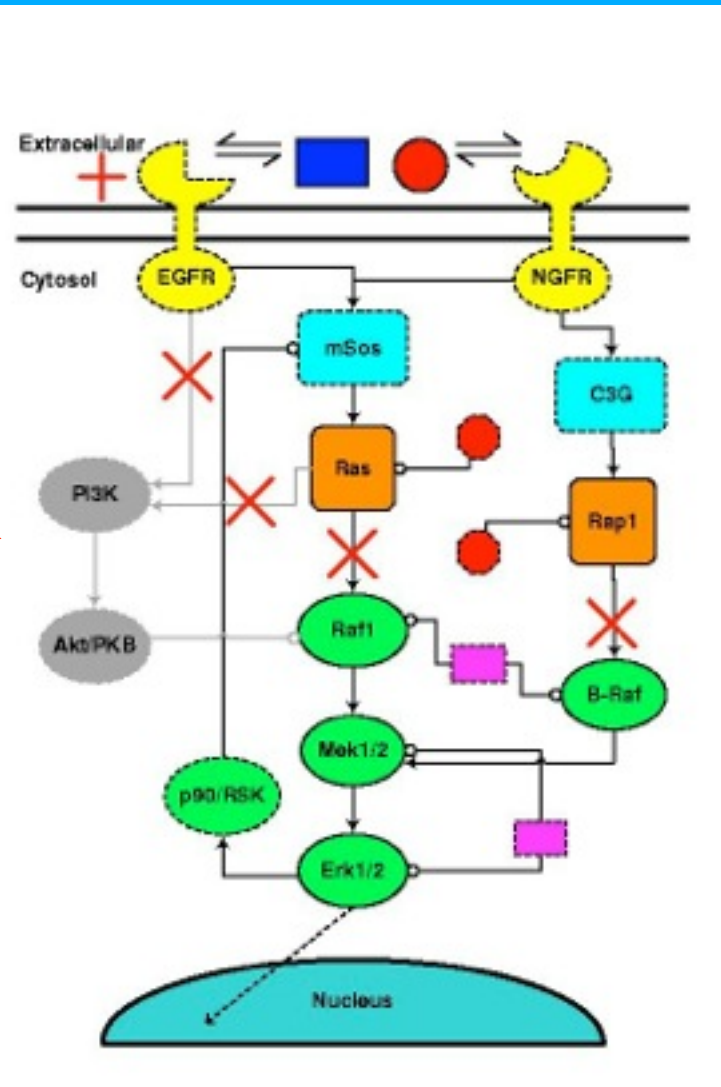
# PC12 Differentiation



Biologists study which proteins talk to which. Modeling?

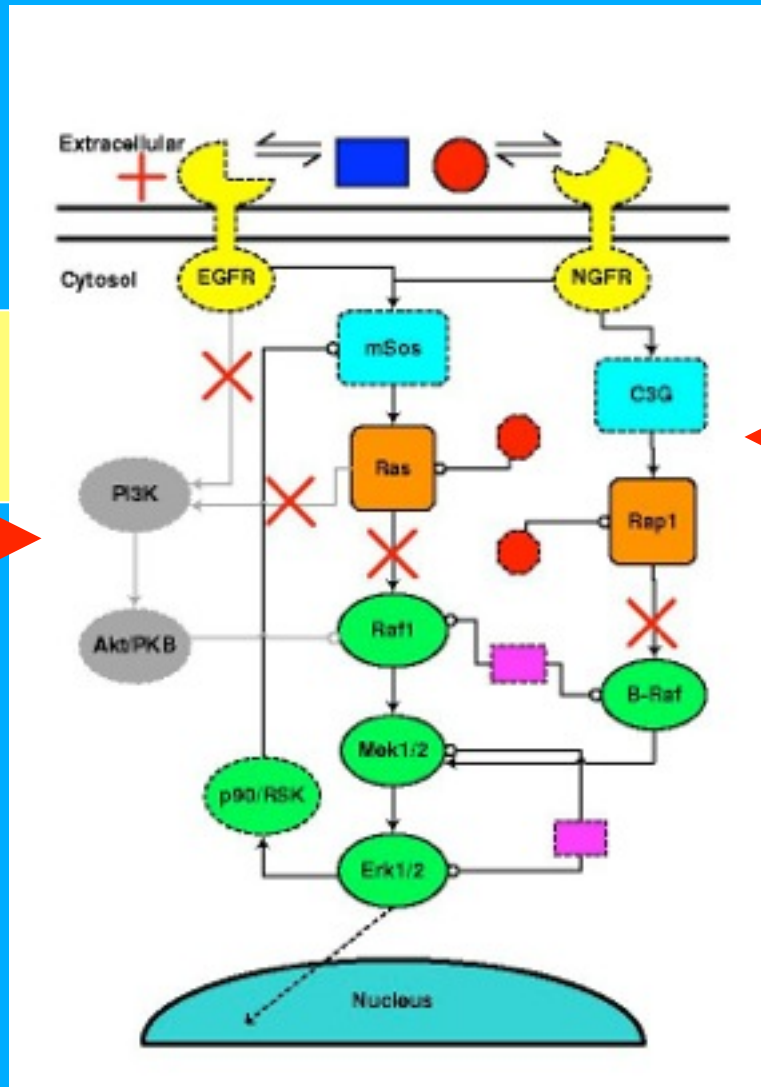
# PC12 Differentiation

Tunes down signal (Raf-1)



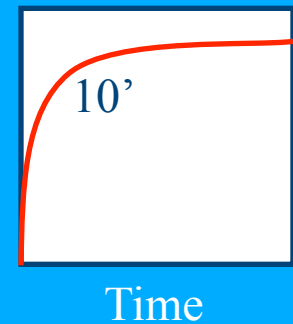
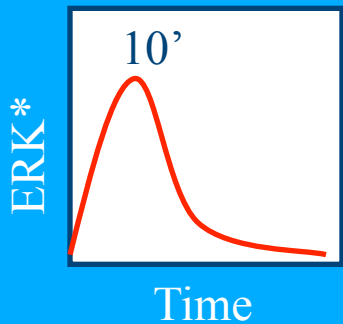
Biologists study which proteins talk to which. Modeling?

# PC12 Differentiation



Pumps up signal (Mek)

Tunes down signal (Raf-1)

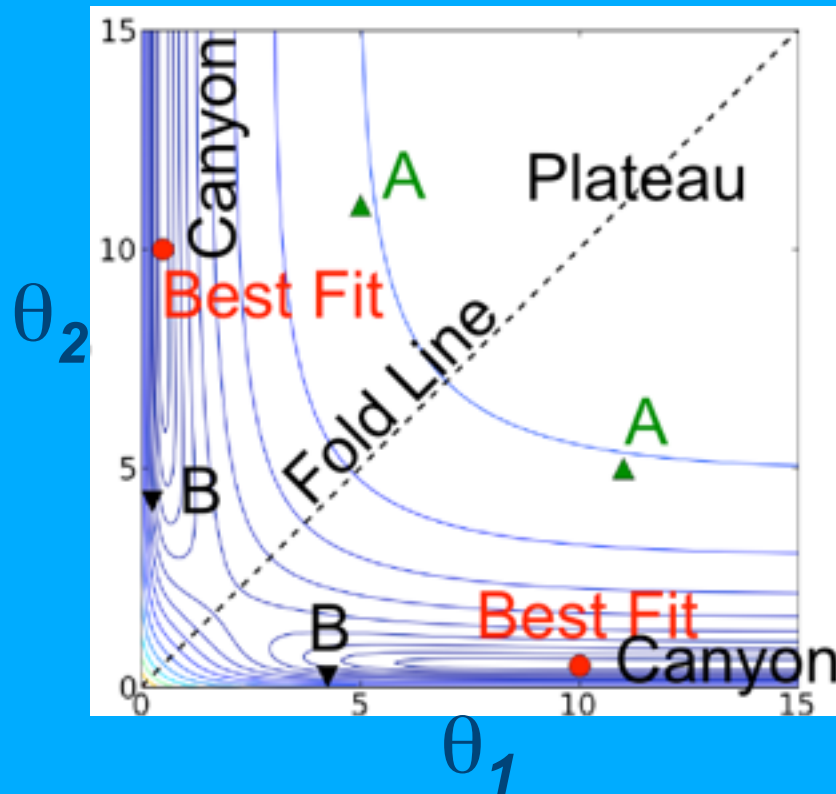
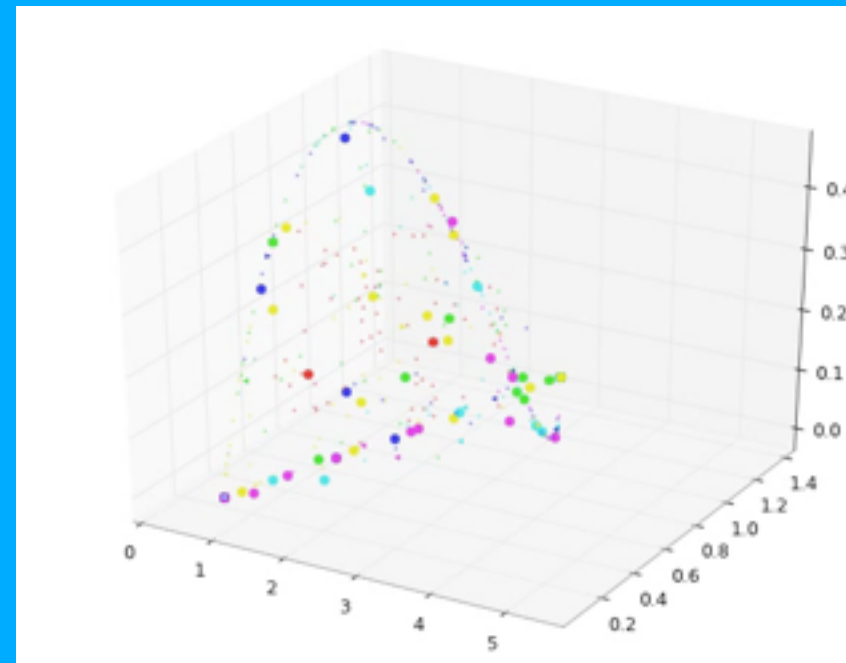
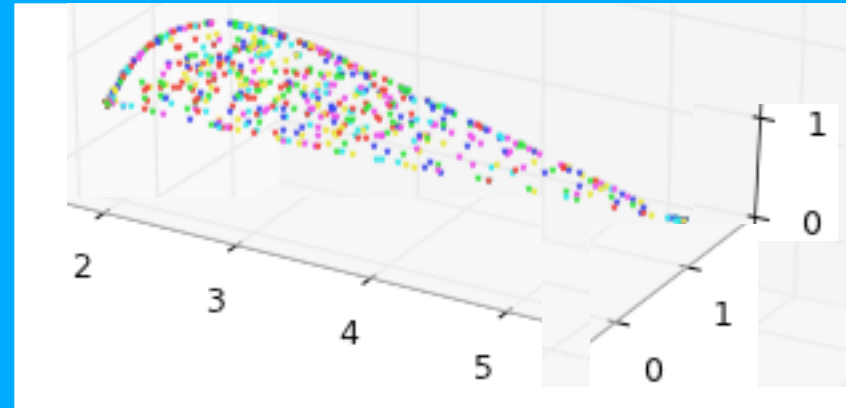


Biologists study which proteins talk to which. Modeling?

# Edges of the model manifold

## *Fitting Exponentials*

Top: Flat model manifold;  
articulated edges = plateau  
Bottom: Stretch to uniform  
aspect ratio (Isabel Kloumann)

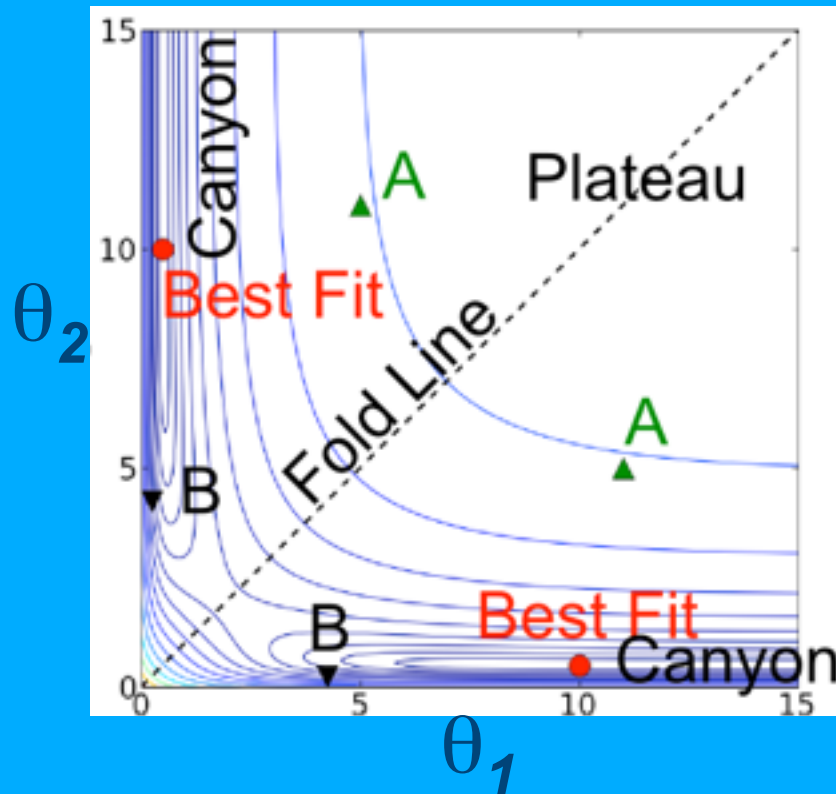
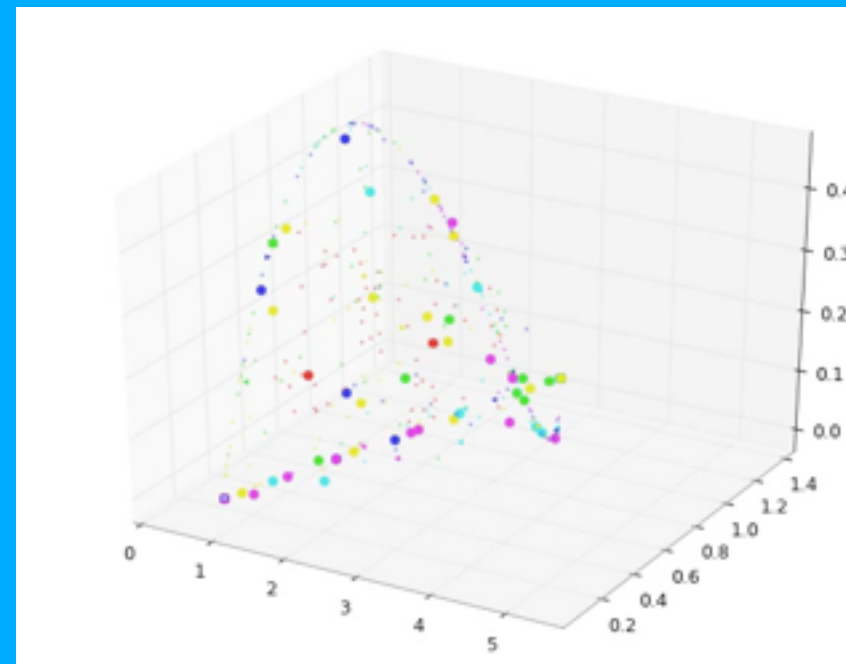
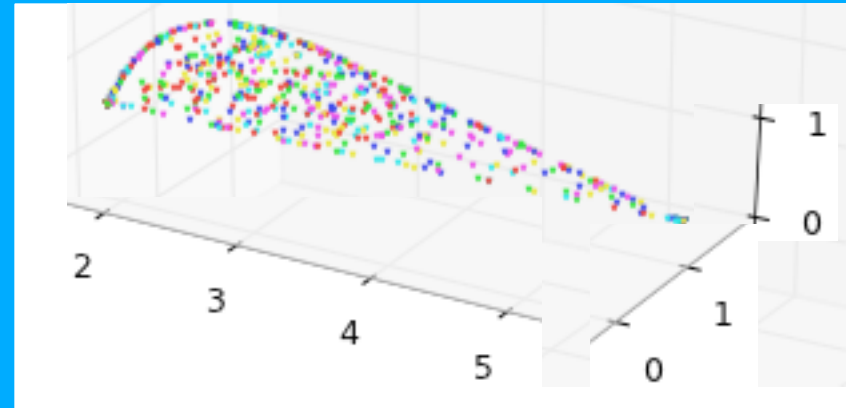




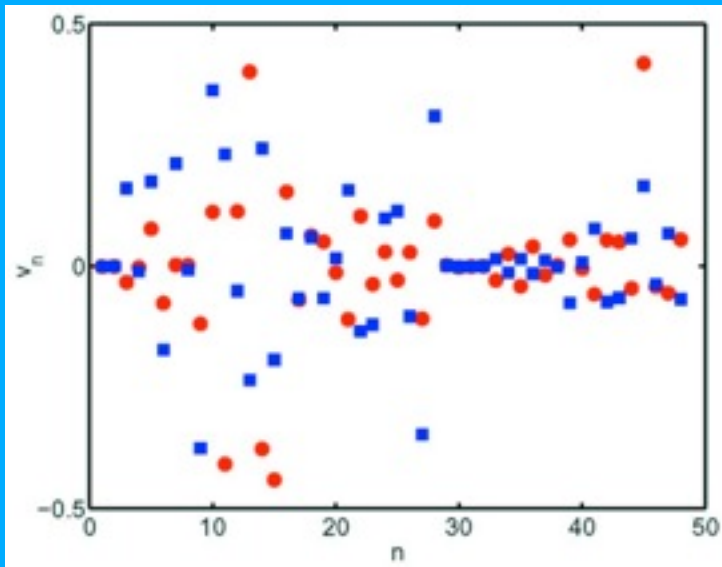
# Edges of the model manifold

## *Fitting Exponentials*

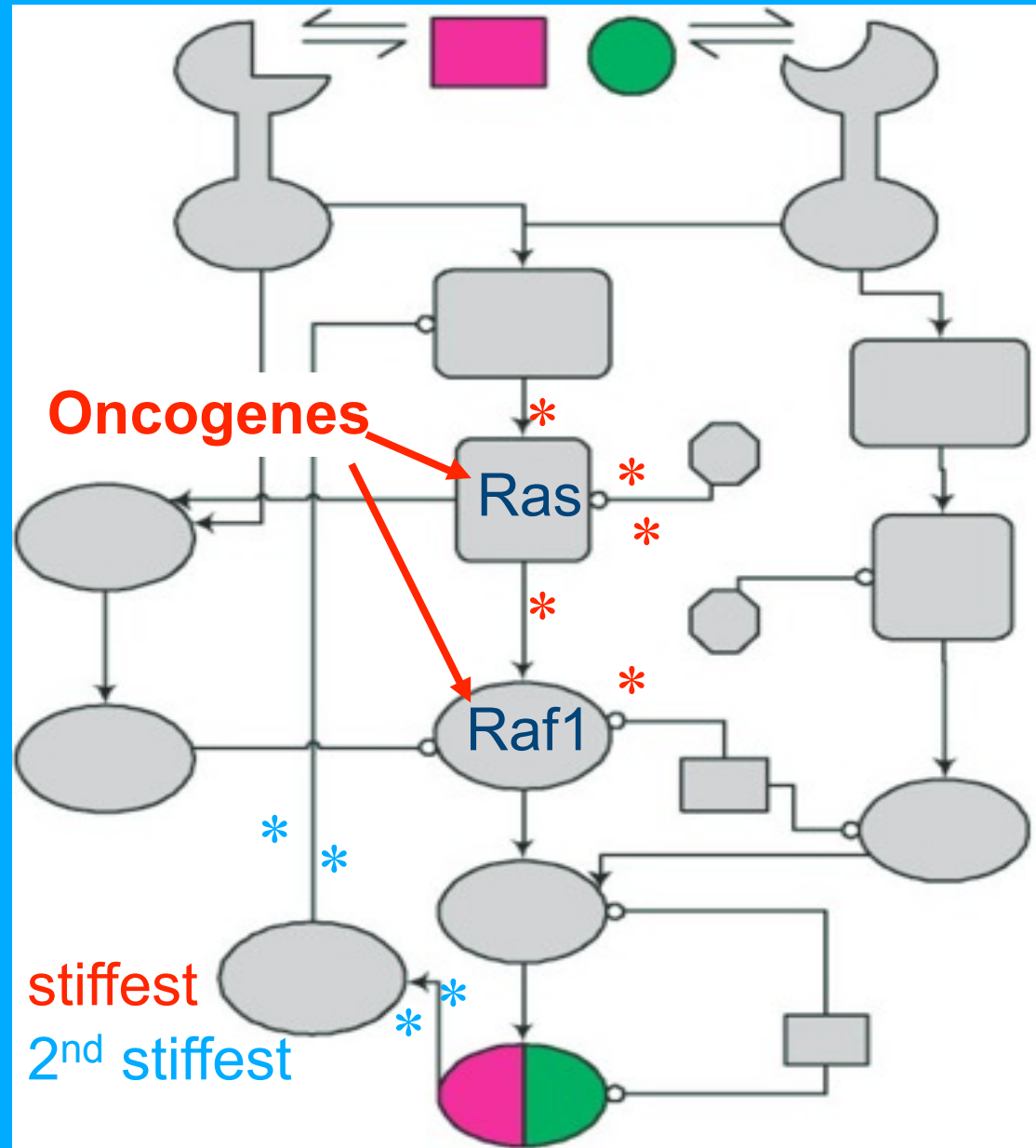
Top: Flat model manifold;  
articulated edges = plateau  
Bottom: Stretch to uniform  
aspect ratio (Isabel Kloumann)



# Which Rate Constants are in the Stiffest Eigenvector?

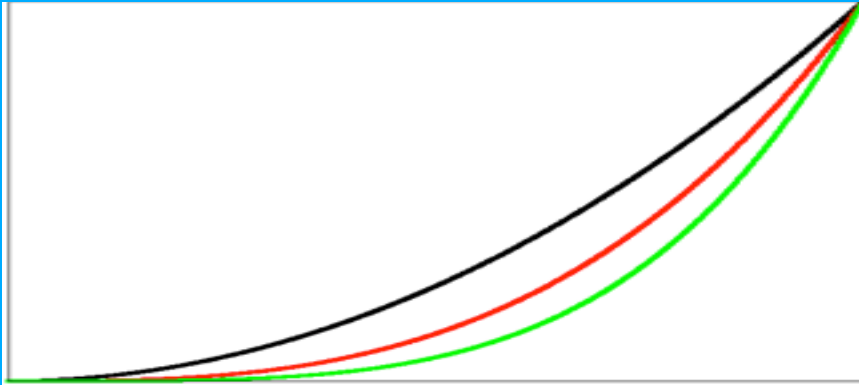


Eigenvector components along the bare parameters reveal which ones are most important for a given eigenvector.



# Where is Sloppiness From?

## Fitting Polynomials to Data



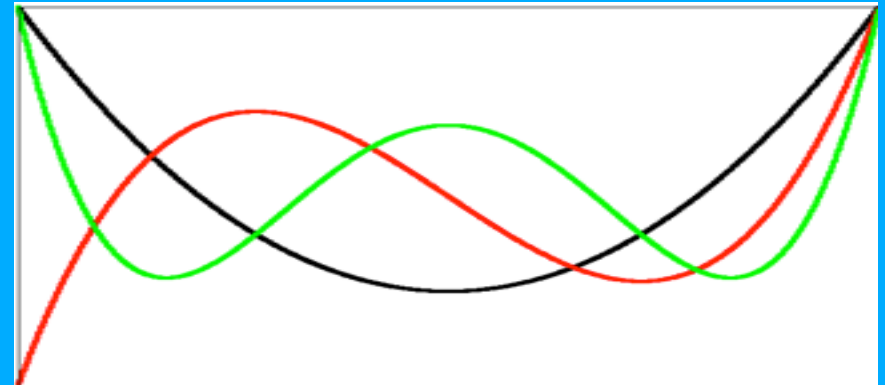
Fitting Monomials to Data

$$y = \sum a_n x^n$$

Functional Forms Same

Hessian  $H_{ij} = 1/(i+j+1)$

Hilbert matrix: famous



Orthogonal Polynomials

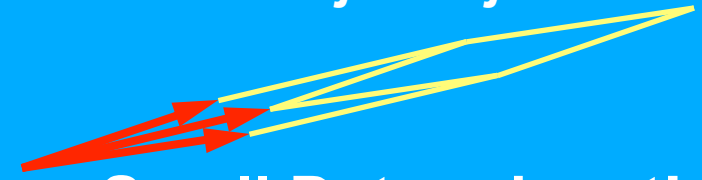
$$y = \sum b_n L_n(x)$$

Functional Forms Distinct

Eigen Parameters

Hessian  $H_{ij} = \delta_{ij}$

**Sloppiness arises when bare parameters skew in eigenbasis**

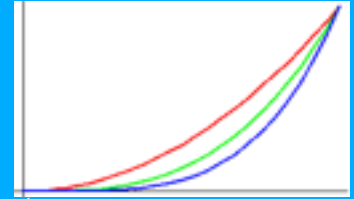


**Small Determinant!**

$$|H| = \prod \lambda_n$$

# Proposed universal ensemble

## Why are they sloppy?



Assumptions: (Not one experiment per parameter)

- i. Model predictions all depend on every parameter, *symmetrically*:  $y_i(\theta_1, \theta_2, \theta_3) = y_i(\theta_2, \theta_3, \theta_1)$
- ii. Parameters are nearly degenerate:  $\theta_i = \theta_0 + \varepsilon_i$

$$H = J^T J = V^T A^T A V$$

$$V = \begin{bmatrix} 1 & 1 & \cdots & 1 \\ \varepsilon_1 & \varepsilon_2 & \cdots & \varepsilon_N \\ \vdots & \vdots & \ddots & \vdots \\ \varepsilon_1^d & \varepsilon_2^d & \cdots & \varepsilon_N^d \end{bmatrix}$$

Vandermonde  
Matrix

$$\det(V) = \prod_{d=N-1} \prod_{i < j} (\varepsilon_i - \varepsilon_j) \propto \varepsilon^{N(N-1)/2}$$

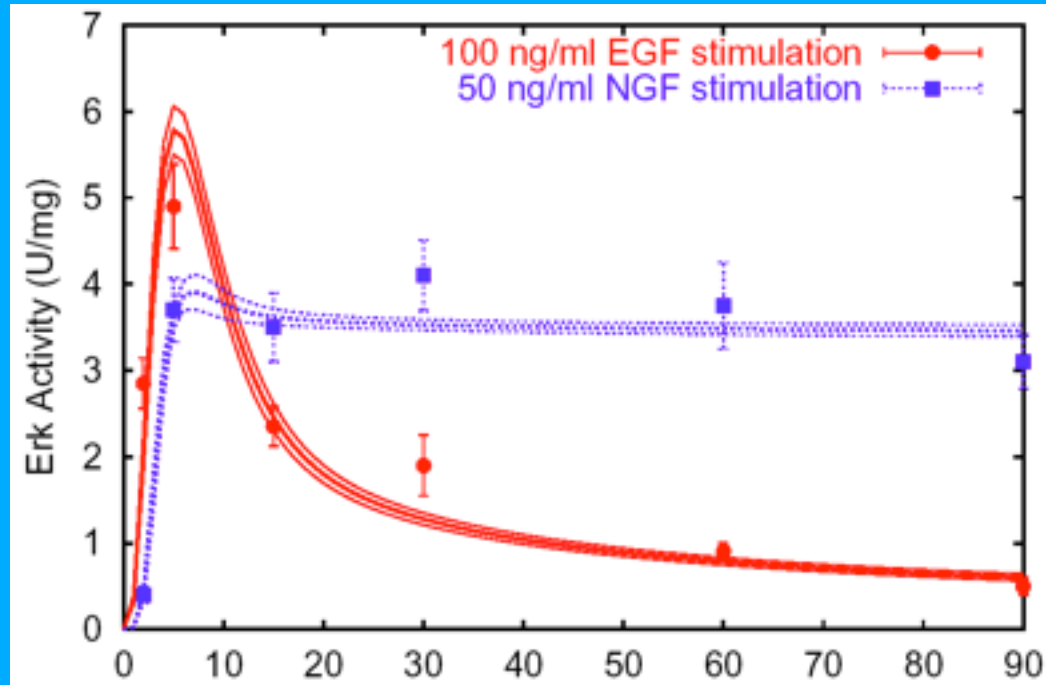
- Implies enormous range of eigenvalues
- Implies equal spacing of log eigenvalues
- Like universality for random matrices

# 48 Parameter "Fit" to Data

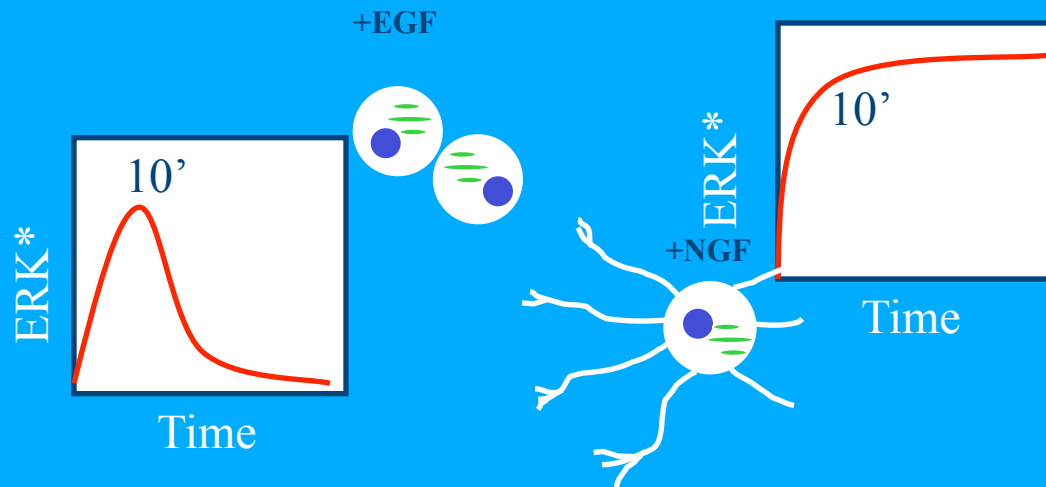
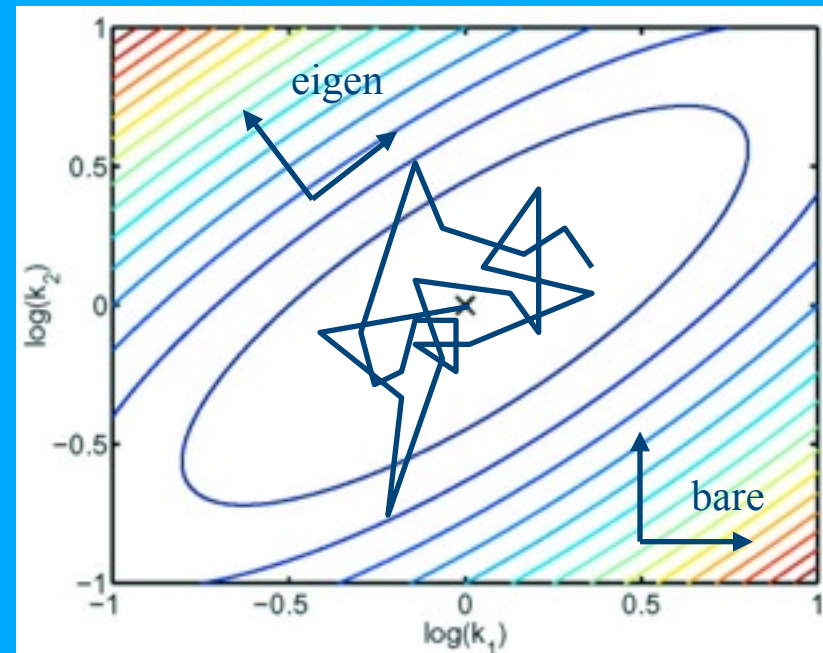
Cost is Energy

$$C(\vec{\theta}) = \frac{1}{2} \sum_{i=1}^{N_D} \frac{(y(\vec{\theta}) - y_i)^2}{\sigma_i^2}$$

Ensemble of Fits  
Gives Error Bars



Error Bars from Data Uncertainty



# Exploring Parameter Space

Rugged? More like Grand Canyon (Josh)

Glasses: Rugged Landscape

Metastable Local Valleys

Transition State Passes

Optimization Hell: Golf Course

Sloppy Models

Minima: 5 stiff, N-5 sloppy

Search: Flat planes with cliffs



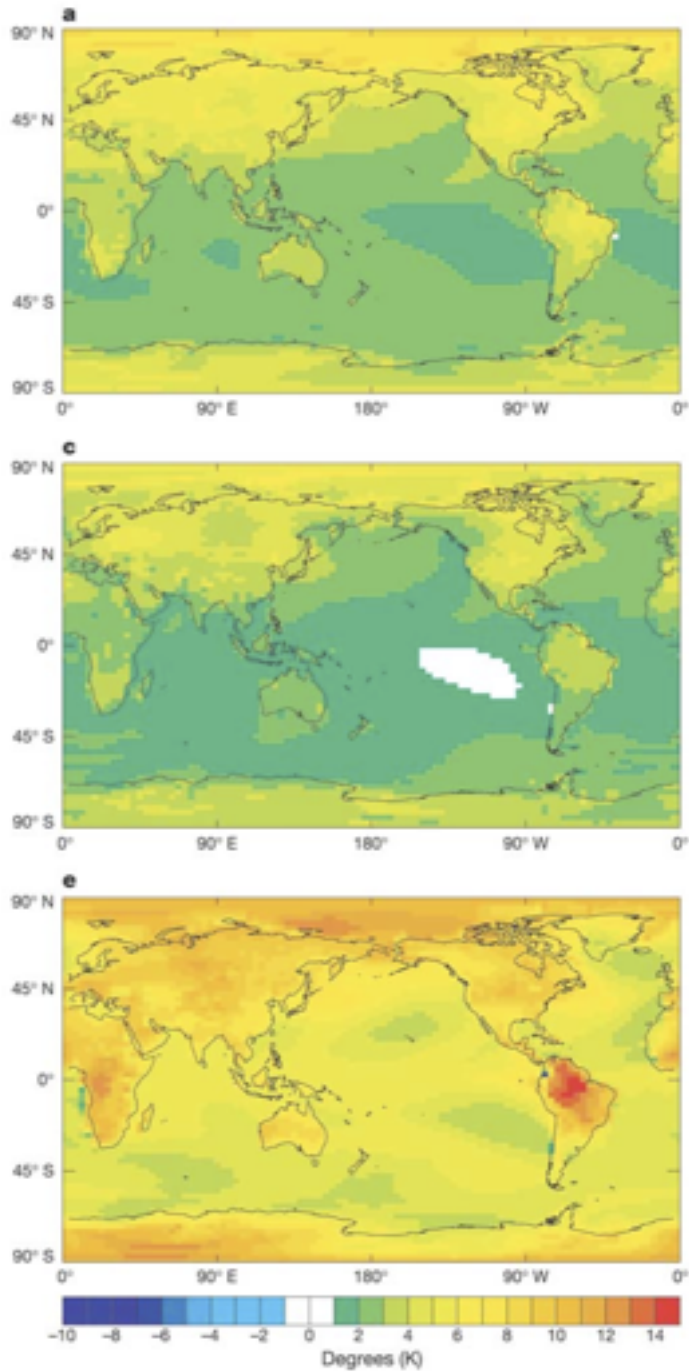
# Climate Change

Climate models contain many unknown parameters, fit to data

- General Circulation Model (air, oceans, clouds), exploring doubling of CO<sub>2</sub>
- 21 total parameters
- Initial conditions and (only) 6 “cloud dynamics” parameters varied
- Heating typically 3.4K, ranged from < 2K to > 11K

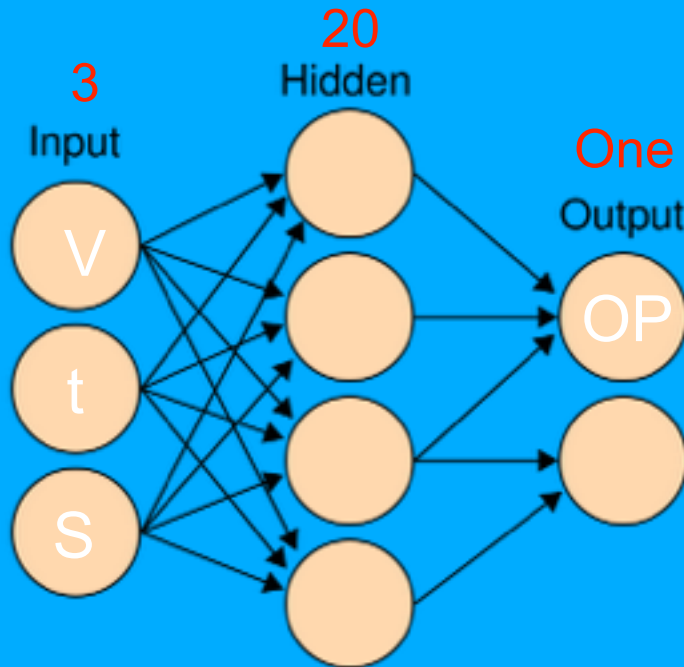
Stainforth et al., *Uncertainty in predictions of the climate response to rising levels of greenhouse gases*, **Nature** **433**, 403-406 (2005)

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# Neural Networks

Mark Transtrum



V	t	S	OP
0.20	5.0	75.	25.0000
0.40	5.0	93.	7.2537
0.40	15.0	79.	21.0225
0.66	10.0	91.	10.3957

...

- Neural net “trained” to predict Black-Scholes output option price OP, given inputs volatility V, time t, and strike S
- Each circular “neuron” has sigmoidal response signal  $s_j$  to input signals  $s_i$ :

$$s_j = \tanh(\sum_i w_{ij} s_i)$$

- Inputs and outputs scaled to  $[-1,1]$
- 101 parameters  $w_{ij}$  fit to 1530 data points

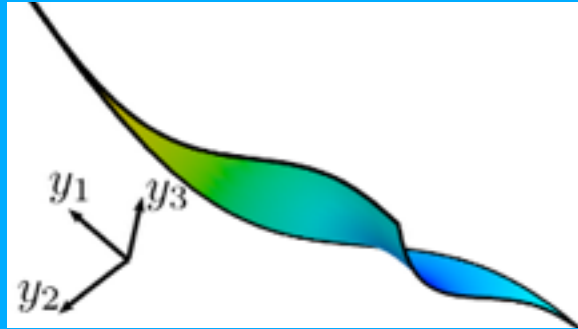
(<http://www.scientific-consultants.com/nabd.html>)



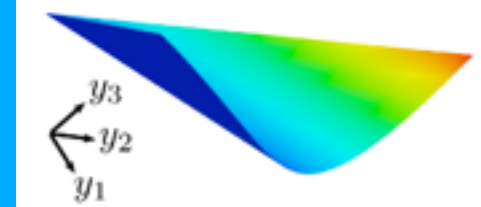
# Curvatures

## Intrinsic curvature $R^\mu_{\nu\alpha\beta}$

- determines geodesic shortest paths
- independent of embedding, parameters

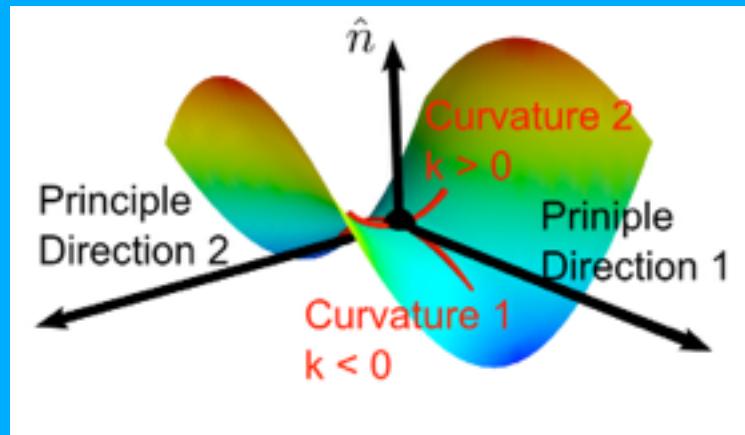


No intrinsic curvature



## Extrinsic curvature

- also measures bending in embedding space (i.e., cylinder)
- independent of parameters
- Shape operator, geodesic curvature

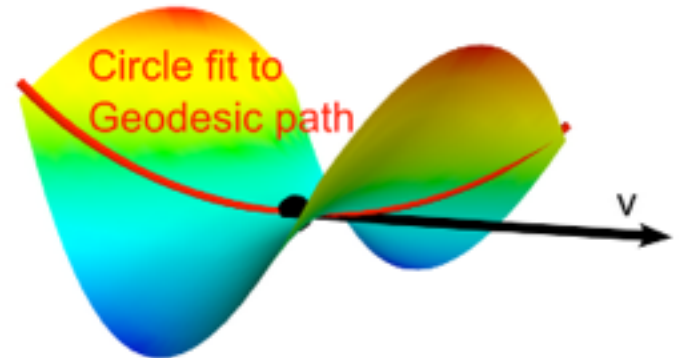


Shape Operator

## Parameter effects “curvature”

- Usually much the largest
- Defined in analogy to extrinsic curvature (projecting out of surface, rather than into)

Geodesic Curvature



# Why is it so thin?

Model  $f(t, \theta)$  analytic:

$$f^{(n)}(t)/n! \leq R^{-n}$$

Polynomial fit  $P_{m-1}(t)$

to  $f(t_1), \dots, f(t_m)$

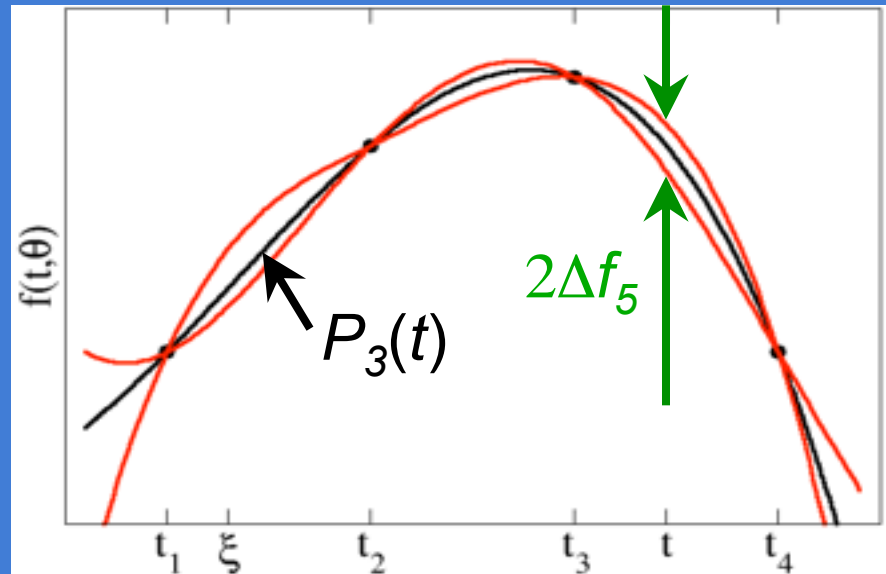
Interpolation convergence theorem

$$\Delta f_{m+1} = f(t) - P_{m-1}(t)$$

$$< (t-t_1) \dots (t-t_m) f^{(m)}(\xi)/m!$$

$$\sim (\Delta t / R)^m$$

More than one data per R



**Hyper-ribbon:** Cross-section constraining  $m$  points has width  $W_{m+1} \sim \Delta f_{m+1} \sim (\Delta t/R)^m$

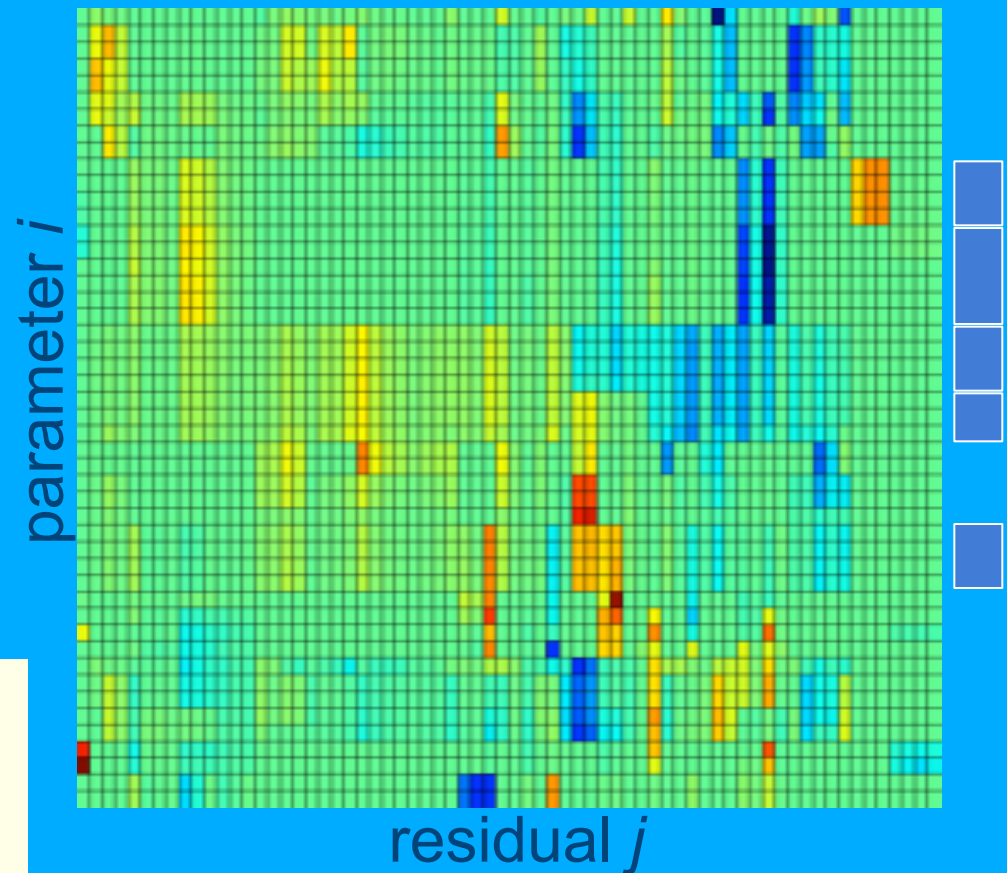
# B. Finding sloppy subsystems

## Model reduction?

- Sloppy model as multiple redundant parameters?
- Subsystem = subspace of parameters  $p_i$  with similar effects on model behavior
- Similar = same effects on residuals  $r_j$
- Apply clustering algorithm to rows of  $J_{ij}^T = \partial r_j / \partial p_i$

Continuum mechanics,  
renormalization group,  
Lyapunov exponents can  
also be viewed as sloppy  
model reduction

PC12 differentiation model



# References

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- “**The Statistical Mechanics of Complex Signaling Networks: Nerve Growth Factor Signaling**”, K. S. Brown, C. C. Hill, G. A. Calero, C. R. Myers, K. H. Lee, J. P. Sethna, and R. A. Cerione, *Physical Biology* 1, 184-195 (2004) .
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