

# Nonplanar objects in a fluctuating fluid out of equilibrium

self-forces, self-torques, and violation of  
the action-reaction principle

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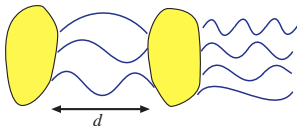
1. Introduction
2. A nonequilibrium fluid model
3. Two nonplanar systems
4. Conclusions

## Casimir-like forces at equilibrium

- Casimir (1948): EM vacuum fluctuations
- EM thermal fluctuations (Lifshitz)
- Other fluctuating systems:
  - critical fluids
  - broken continuous symmetry
  - proteins on cell membranes
  - ...



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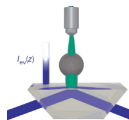
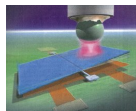
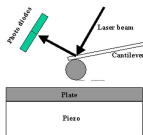


Long-range correlations of the fluctuating medium

Usually: strong geometry dependence

## Experiments / Applications

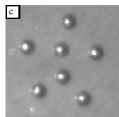
- Lamoreaux (1997), Mohideen & Roy (1998)
- MEMS, nanostructures  
Non-contact gears
- Helium films
- Direct measurement critical Casimir force
- Agregation/Segregation of colloidal particles



## Casimir-like forces **out of equilibrium**

Long-range fluctuations also appear in nonequilibrium:

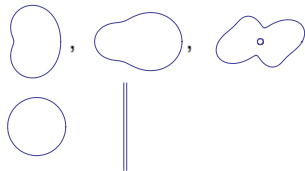
- Couette flow, Rayleigh-Bénard...
- granular fluids
- reaction-diffusion
- EM Casimir driven out of equilibrium, ...



No thermodynamic (equilibrium) potential

**Nonequilibrium** + **nonplanar**  $\Rightarrow$  **new effects**

- more control parameters: sign reversal, noise reduction
- “self-forces” on asymmetric objects
- violation of action-reaction principle



## A simple nonequilibrium fluid model

- Reaction–diffusion (w/o detailed balance)  $A + B \xrightarrow{k_1} 2B$ ,  $B \xrightarrow{k_2} A$
- Rate equations for  $A$  and  $B$ :

$$\begin{aligned}\frac{\partial}{\partial t}\rho_A &= D\nabla^2\rho_A - \frac{k_1}{\rho_{\text{tot}}}\rho_A\rho_B + k_2\rho_B \\ \frac{\partial}{\partial t}\rho_B &= D\nabla^2\rho_B + \frac{k_1}{\rho_{\text{tot}}}\rho_A\rho_B - k_2\rho_B\end{aligned}$$

- Homogeneous stationary solution:  $\rho_A^0 = \frac{k_2}{k_1}\rho_{\text{tot}}$ ,  $\rho_B^0 = \rho_{\text{tot}} - \rho_A^0$
- Density fluctuations:  $\Phi(\mathbf{r}, t) = \rho(\mathbf{r}, t) - \rho^0$ ,  $\rho^0 \equiv \langle \rho(\mathbf{r}, t) \rangle$

$$\boxed{\frac{\partial \Phi}{\partial t} = -\nabla \cdot (-D\nabla\Phi + \boldsymbol{\xi}_c) - \gamma\Phi + \xi_{nc}}, \quad \gamma = k_1 - k_2 > 0$$

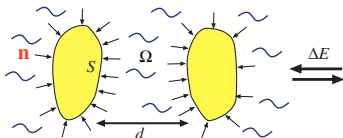
$$\langle \xi_c^\mu(\mathbf{r}, t) \xi_c^\nu(\mathbf{r}', t') \rangle = \Gamma_c \delta_{\mu\nu} \delta(\mathbf{r} - \mathbf{r}') \delta(t - t'),$$

$$\langle \xi_{nc}(\mathbf{r}, t) \xi_{nc}(\mathbf{r}', t') \rangle = \Gamma_{nc} \delta(\mathbf{r} - \mathbf{r}') \delta(t - t'),$$

## Force on a surface $S$

- Non-flux b.c.:  $\mathbf{n} \cdot (-D\nabla\Phi + \xi_{\mathbf{c}})|_{\mathbf{r} \in \partial\Omega} \equiv 0$
- Local pressure:  $p = p(\rho(\mathbf{r}, t)) \implies \langle p \rangle \approx p_0 + \frac{\rho_0''}{2} \langle \Phi^2 \rangle$
- Average force on  $S$

$$\mathbf{F}_S = \frac{\rho_0''}{2} \int_S d\sigma \mathbf{n} \langle \Phi^2 \rangle$$



## Stationary state

After characteristic time  $\approx O(\gamma^{-1})$ :

$$\begin{aligned} \Phi_{\text{st}}(\mathbf{r}, t) = & \int dt' \int_{\Omega} d\mathbf{r}' G(\mathbf{r}, \mathbf{r}', Dt - Dt') (-\nabla \cdot \xi_{\mathbf{c}} + \xi_{\text{nc}})(\mathbf{r}', t') \\ & + \int dt' \int_{\partial\Omega} d\sigma(\mathbf{r}') G(\mathbf{r}, \mathbf{r}', Dt - Dt') \mathbf{n}(\mathbf{r}') \cdot \xi_{\mathbf{c}}(\mathbf{r}', t') \end{aligned}$$

- Green function  $G(\mathbf{r}, \mathbf{r}', \tau)$

$$(-\nabla^2 + \kappa^2 - i\omega)G(\mathbf{r}, \mathbf{r}', \omega) = \delta(\mathbf{r} - \mathbf{r}'), \quad \kappa^{-1} = \left[\frac{\gamma}{D}\right]^{-\frac{1}{2}}$$

$$\mathbf{n}(\mathbf{r}) \cdot \nabla G(\mathbf{r}, \mathbf{r}', \omega)|_{\mathbf{r} \in \partial\Omega} \equiv 0 \quad = \text{corr. length mesosc. scale}$$

- Static structure factor

$$\langle \Phi_{\text{st}}(\mathbf{r}, t) \Phi_{\text{st}}(\mathbf{r}', t) \rangle$$

$$= \frac{\Gamma_{\text{c}}}{2D} \delta(\mathbf{r} - \mathbf{r}') + \frac{\Gamma}{2D} G(\mathbf{r}, \mathbf{r}', \omega = 0), \quad \Gamma = \Gamma_{\text{nc}} - \frac{\gamma}{D} \Gamma_{\text{c}}$$

- At thermal equilibrium: fluctuation–dissipation theorem

$$\Gamma_{\text{c}} = 2k_{\text{B}}TD, \quad \Gamma_{\text{nc}} = 2k_{\text{B}}T\gamma \quad \Longrightarrow \quad \begin{cases} \Gamma = 0 \\ \text{Only microscopic corr.} \end{cases}$$

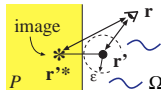
- Multiple scattering



$$G(\mathbf{r}, \mathbf{r}') = G_0(\mathbf{r} - \mathbf{r}') - \int_S d\sigma_1 G(\mathbf{r}, \mathbf{r}_1) \mathbf{n}_1 \cdot \nabla_1 G_0(\mathbf{r}_1 - \mathbf{r}'),$$

## Short-range divergencies

- 3D:  $G_0(\mathbf{r} - \mathbf{r}') = \frac{e^{-\kappa|\mathbf{r} - \mathbf{r}'|}}{4\pi|\mathbf{r} - \mathbf{r}'|}$ ; 2D:  $G_0(\mathbf{r} - \mathbf{r}') = \frac{K_0(\kappa|\mathbf{r} - \mathbf{r}'|)}{2\pi}$
- 1 plate:  $G_P(\mathbf{r}, \mathbf{r}') = G_0(\mathbf{r} - \mathbf{r}') + G_0(\mathbf{r} - \mathbf{r}'^*)$
- 2 short-range divergencies for  $\langle \Phi_{st}^2(\mathbf{r}) \rangle |_{\mathbf{r} \in S}$ 
  - “bulk”  $\Rightarrow (G_P - G_0)(\mathbf{r}, \mathbf{r})$
  - “wall”: integrated along  $S$ ... compensation?



## Regularized force

$$\mathbf{F}_S = F_0 \kappa \lim_{\epsilon \rightarrow 0} \int_S d\sigma \mathbf{n}(\mathbf{r}) [G - G_0](\mathbf{r} - \epsilon \mathbf{n}(\mathbf{r}), \mathbf{r} - \epsilon \mathbf{n}(\mathbf{r}))$$

$$F_0 = \frac{\rho_0'' \Gamma}{4D\kappa}, \quad \Gamma = \Gamma_{nc} - \kappa^2 \Gamma_c \geq 0 : \text{sign control}$$



## Self-force/torque on a deformed circle

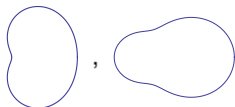
- General solution for bounded obstacle:

$$G(\mathbf{r}, \mathbf{r}') = G_0(\mathbf{r} - \mathbf{r}') + \sum_{m, n \in \mathbb{Z}} \frac{e^{im\theta + in\theta'}}{2\pi} a_{mn} K_m(\kappa\rho) K_n(\kappa\rho')$$

- Deformed circle:  $\rho(\theta) = R + \eta s(\theta)$ ,  $\eta \ll R, \kappa^{-1}$
- $a_{mn}$  and then  $\mathbf{F}$  determined perturbatively in  $\eta \ll R, \kappa^{-1}$

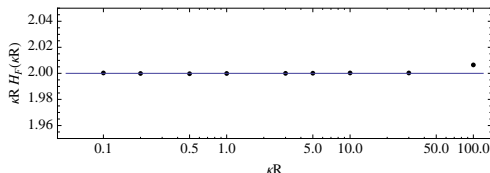
- Self-force:  $s(\theta) = 2s_1 \cos(\theta) + 2s_2 \cos(2\theta)$

$$\mathbf{F} \sim -F_0 s_1 s_2 (\kappa\eta)^2 H(\kappa R) \hat{\mathbf{x}}$$



$$H(\kappa R) = \lim_{\epsilon \rightarrow 0} \sum_{n \in \mathbb{Z}} \{ \sigma_{n,1-n}(\kappa R, \kappa(R+\epsilon)) + \sigma_{n,-2-n}(\kappa R, \kappa(R+\epsilon)) \}$$

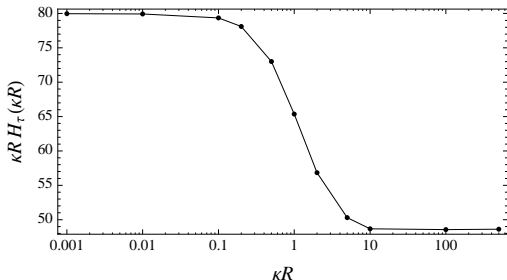
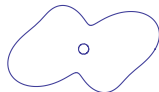
$$= \frac{2}{\kappa R} ?$$



$$\begin{aligned} \sigma_{n,q}(x,y) = & \frac{I'_n(x)}{K'_n(x)} \left\{ K_n(y)K'_n(y) + x \left[ K_n''(y) + K_n(y)K_n''(y) \right] \right\} \\ & + \frac{K_n(y)K_{n+1}(y)}{K'_n(x)K'_{n+1}(x)} \left\{ \left[ 1 - \frac{(n+1)q}{x^2} \right] \left[ 1 - \frac{nq}{x^2} \right] \frac{K_q(x)}{K'_q(x)} - \frac{1}{2x} \left[ 1 - \frac{n(n+1)}{x^2} \right] \right\} \\ & + \frac{1}{K'_n(x)K'_q(x)} \left[ 1 - \frac{nq}{x^2} \right] \left\{ \frac{n+q}{x} K_n(y)K_q(y) - K'_n(y)K_q(y) - K_n(y)K'_q(y) \right\} \end{aligned}$$

- Self-torque:  $s(\theta) = 2s_2 \cos(2\theta) + 2s_4 \sin(4\theta)$

$$\mathbf{T} \sim -\frac{F_0}{\kappa} s_2^2 s_4 (\kappa\eta)^3 H_\tau(\kappa R) \hat{\mathbf{z}}$$



$$H_\tau(\kappa R) \approx \frac{80}{\kappa R}, \quad \kappa R \ll 1$$

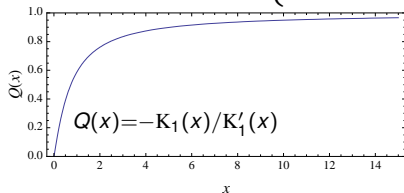
$$H_\tau(\kappa R) \approx \frac{48.5}{\kappa R}, \quad \kappa R \gg 1$$

## Fluctuations of the force

- $$\begin{aligned} \langle F_S^\mu F_S^\nu \rangle - \langle F_S^\mu \rangle \langle F_S^\nu \rangle &= p_0'^2 \int_S d\sigma_1 \int_S d\sigma_2 n_1^\mu n_2^\nu \langle \Phi_{\text{st}}(\mathbf{r}_1) \Phi_{\text{st}}(\mathbf{r}_2) \rangle \\ &= \frac{p_0'^2}{2D} \left\{ \frac{\Gamma_c}{\epsilon} \int_S d\sigma n^\mu n^\nu + \Gamma \int_S d\sigma_1 \int_S d\sigma_2 n_1^\mu n_2^\nu G(\mathbf{r}_1, \mathbf{r}_2) \right\} \end{aligned}$$

- Force fluctuations on the (undeformed) circle:

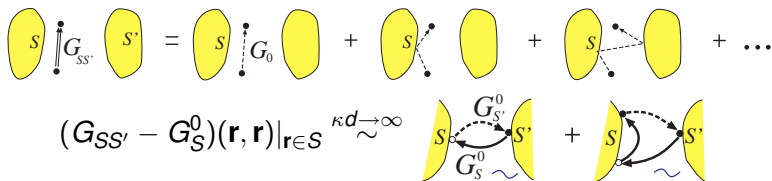
$$\langle F_C^\mu F_C^\nu \rangle = \delta_{\mu\nu} \frac{p_0'^2 |C|}{4D} \left\{ \frac{\Gamma_c}{\epsilon} + \frac{\Gamma}{\kappa} Q(\kappa R) \right\}$$



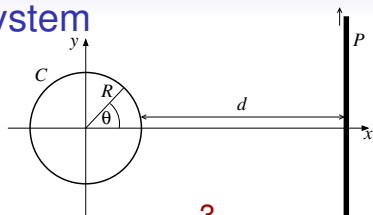
- $\implies$  Force noise can be lowered by noneq. fluctuations

## Two obstacles

- 2 objects,  $S, S'$ . Total force  $\mathbf{F}_S$  on  $S$  decomposed as
  - “self-force”  $\mathbf{F}_S^0$
  - “two-body” force  $\mathbf{F}_{S \leftarrow S'} \equiv \mathbf{F}_S - \mathbf{F}_S^0 = F_0 \kappa \int_S d\sigma \mathbf{n} (G_{SS'} - G_S^0)$
- Action–reaction?  $\mathbf{F}_{S \leftarrow S'} + \mathbf{F}_{S' \leftarrow S} = \mathbf{F}_{SS'} - \mathbf{F}_S^0 - \mathbf{F}_{S'}^0$
- Self-forces  $\rightsquigarrow \nexists$  action–reaction
- Multiple scattering



## Circle-plate system



- Regime  $R \ll \kappa^{-1} \ll d$ :

$$\mathbf{F}_{C \leftarrow P} \sim -F_0 \frac{\sqrt{\pi}(\kappa R)^2 e^{-2\kappa d}}{\sqrt{\kappa d}} \hat{\mathbf{x}},$$

$$\mathbf{F}_{P \leftarrow C} \sim -\frac{3}{2} \mathbf{F}_{C \leftarrow P}$$

Total force on the circle-plate assembly:

$$\mathbf{F}_{CP} \sim \frac{1}{2} F_0 \frac{\sqrt{\pi}(\kappa R)^2 e^{-2\kappa d}}{\sqrt{\kappa d}} \hat{\mathbf{x}}$$

same order of magnitude!

- Regimes  $\kappa^{-1} \ll R, d$ : (same as Derjaguin)

$$\mathbf{F}_{C \leftarrow P} \sim -F_0 \frac{\sqrt{\kappa R} e^{-2\kappa d}}{\sqrt{\kappa d}} \hat{\mathbf{x}},$$

$$\mathbf{F}_{P \leftarrow C} \sim -\mathbf{F}_{C \leftarrow P}$$

## Conclusions

Nonequ. ( $\nexists$  time-reversal) + Nonplanar ( $\nexists$  space symm.)



### Self-forces

- Directed motion (ratchets)
- Tunable
- Stresses on asymmetrical structures
- Motor axles with external energy source, self-assembly

### Violation of action–reaction

- Special care in experimental measurements
- No effective potential (nonconservative forces)