

Cooperative Diffusion and Stochastic Plasticity in Dense Granular Flow

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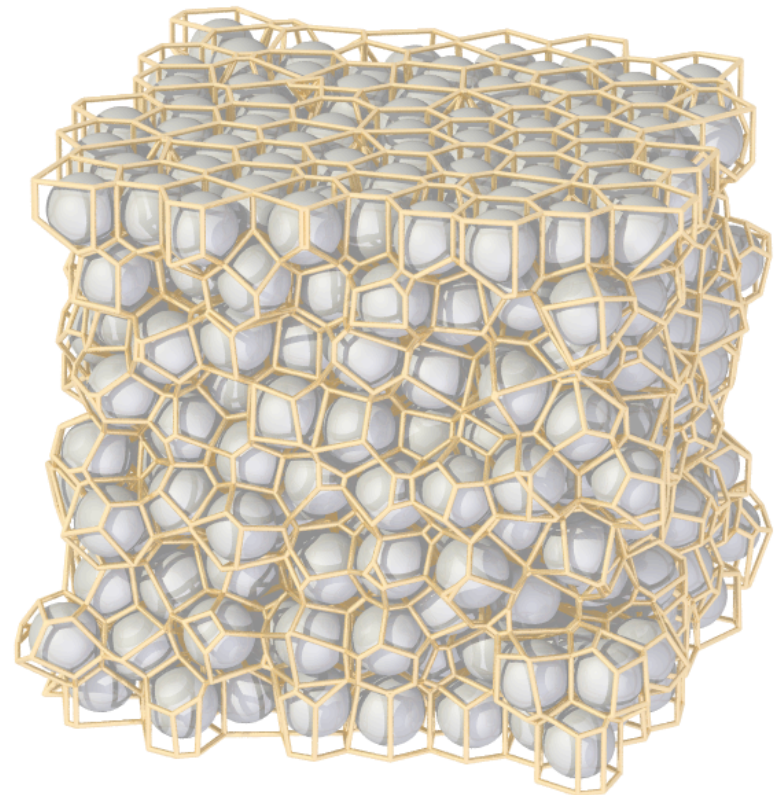
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Gary Grest (Sandia National Laboratories)

Ruben Rosales (MIT Applied Math)

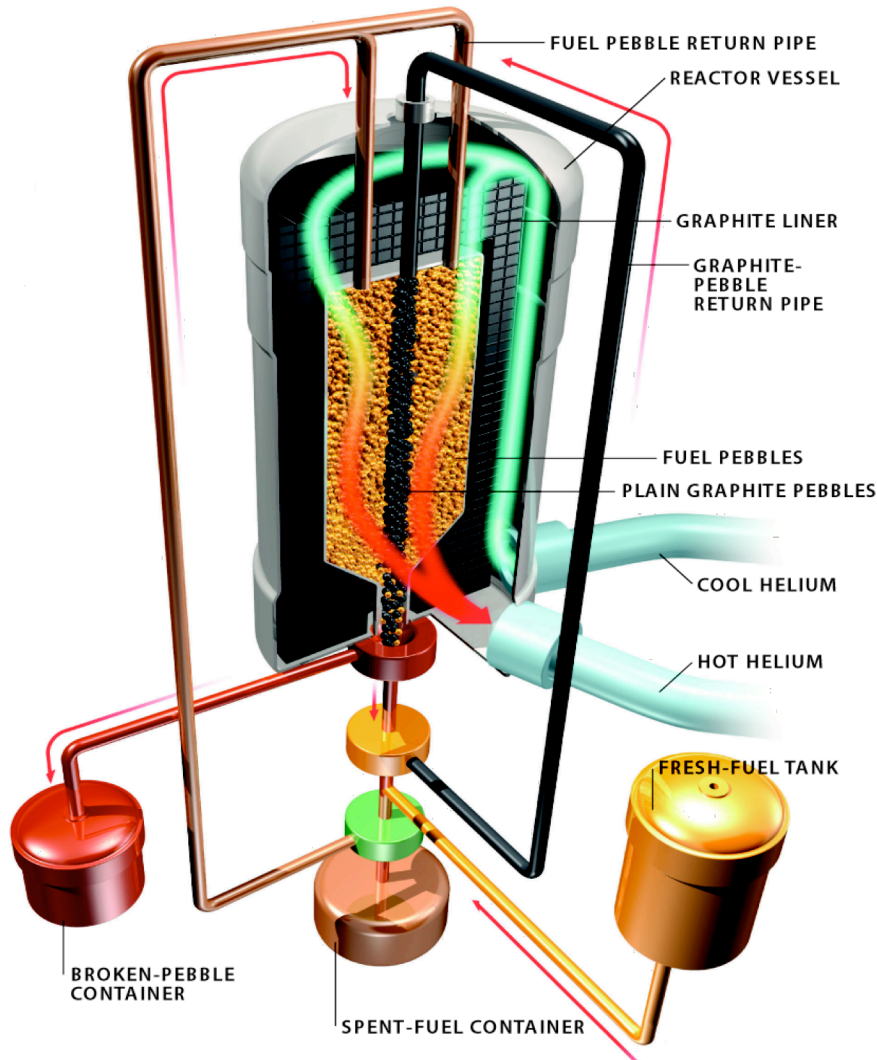
Support: U. S. Department of Energy,
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<http://math.mit.edu/dryfluids>



MIT Modular Pebble-Bed Reactor

<http://web.mit.edu/pebble-bed>

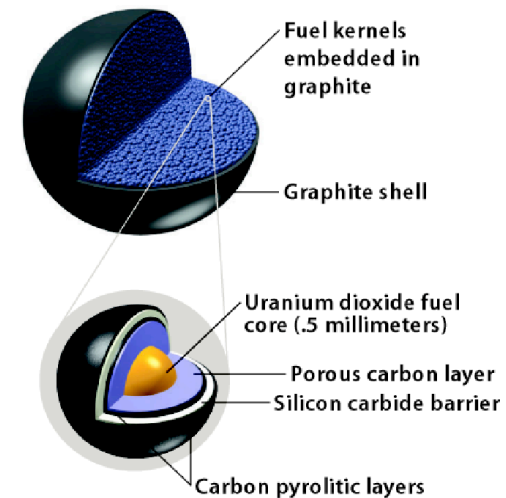


Reactor Core :

- $D = 3.5 \text{ m}$
- $H = 8\text{-}10\text{m}$
- 100,000 pebbles
- $d = 6 \text{ cm}$
- $Q = 1 \text{ pebble/min}$

Small Pebbles, Tiny Kernels

In the reactor core, 330,000 billiard-ball-sized graphite fuel pebbles (top) each contain 15,000 sand-sized (about one-millimeter) fuel kernels (bottom).

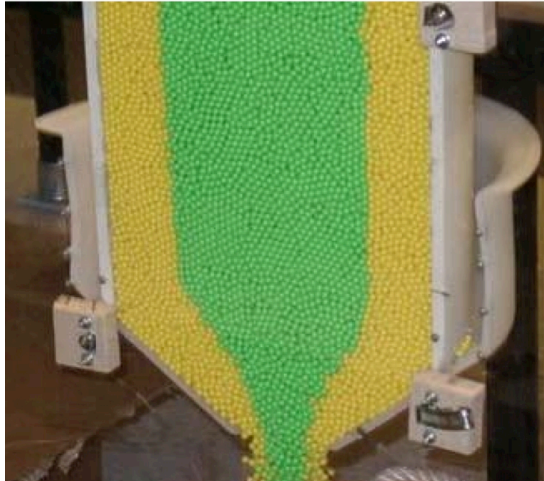


MIT Technology Review (2001)

Experiments and Simulations

MIT Dry Fluids Lab

<http://math.mit.edu/dryfluids>



Half-Reactor Model

Kadak & Bazant (2004)

Plastic or glass beads

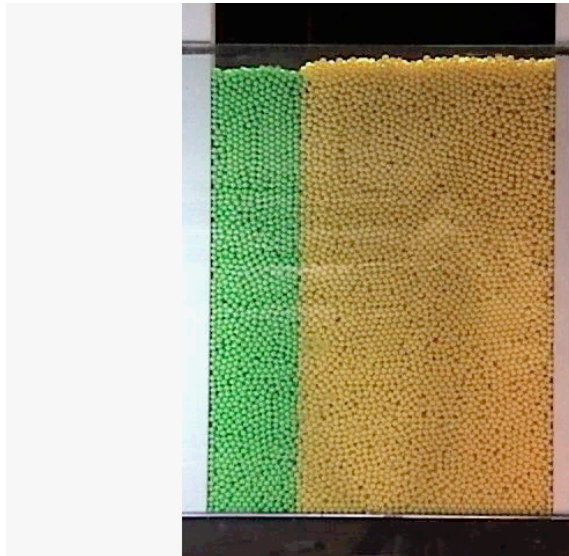
3d Discrete Elements

(“Molecular Dynamics”)

Sandia parallel code from Gary Grest
Rycroft, Bazant, Landry, Grest (2005)

Frictional, viscoelastic spheres

$N=400,000$



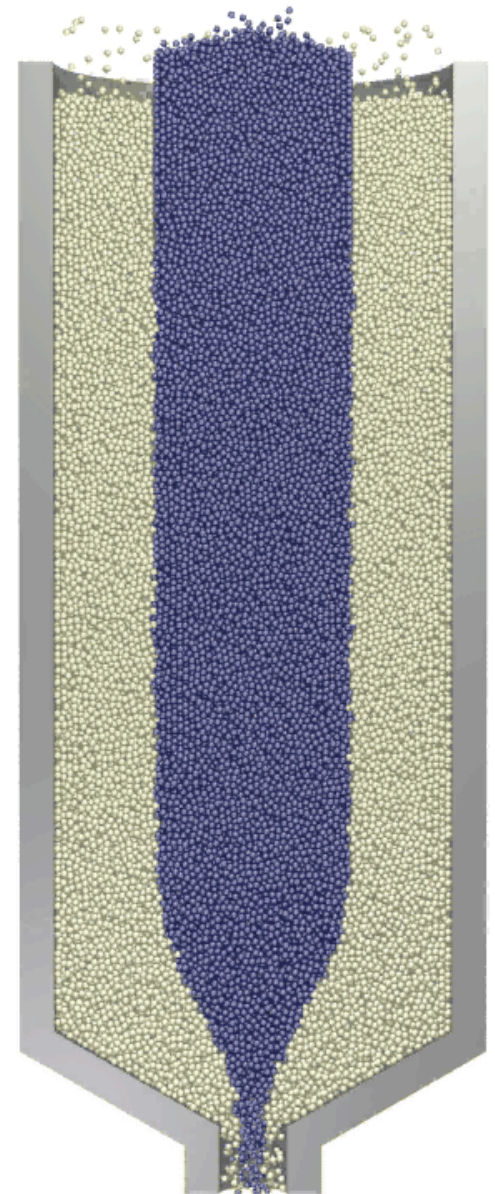
Quasi-2d Silo

Choi et al., Phys. Rev. Lett. (2003)

Choi et al., Granular Matter (2005)

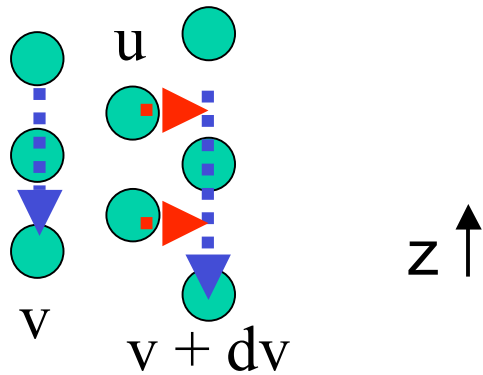
$d=3\text{mm}$ glass beads

Digital-video particle tracking near wall



“Kinematic Model” for the *Mean Velocity* in a Silo

Nedderman & Tuzun, *Powder Tech.* (1979)



Choi, Kudrolli & Bazant, *J. Phys. A: Condensed Matter* (2005).

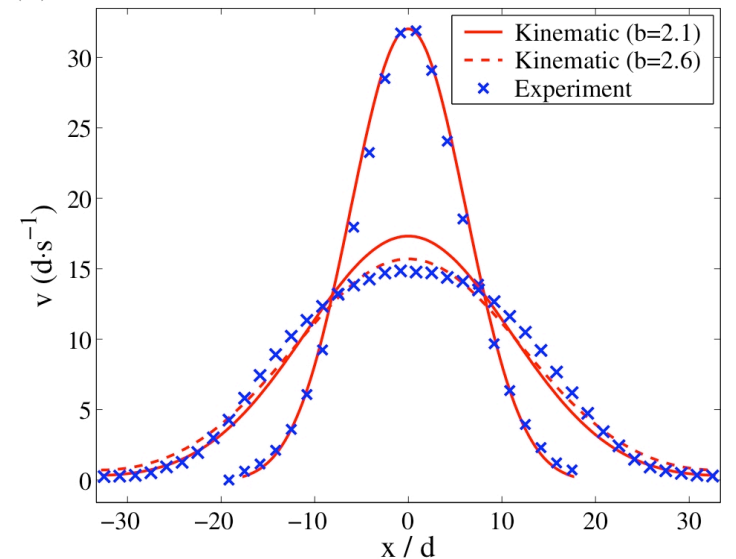
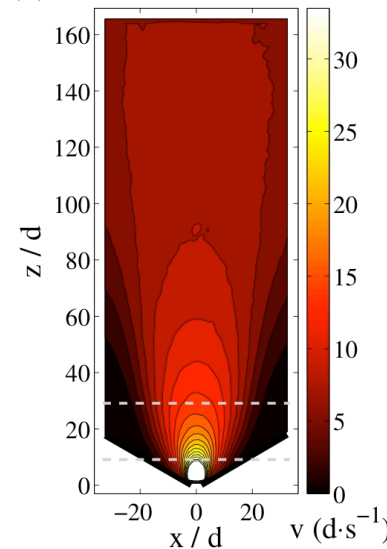
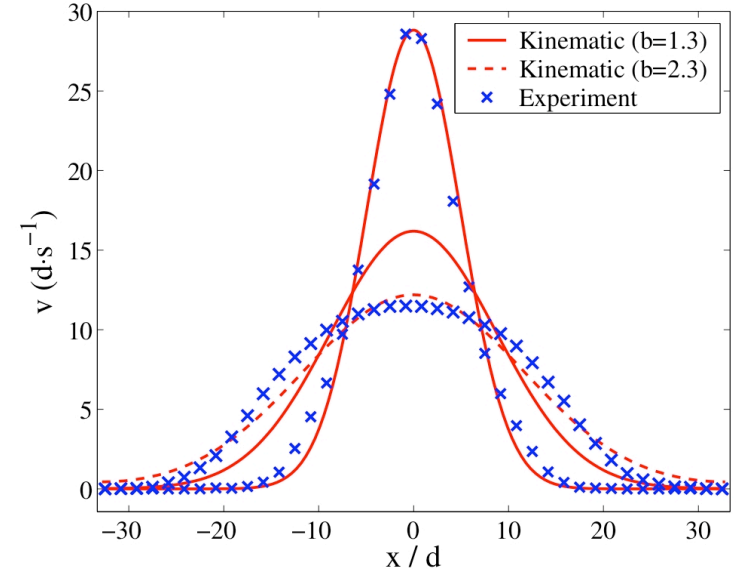
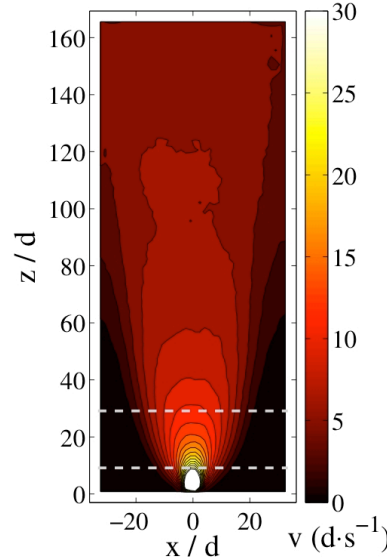
$$u = b \frac{\partial v}{\partial x}, \quad \frac{\partial v}{\partial z} = b \frac{\partial^2 v}{\partial x^2}$$

Green function = point opening
Parabolic streamlines

$$v(x, z = 0) = Q\delta(x)$$

$$v = \frac{Q}{\sqrt{4\pi bz}} \exp\left(-\frac{x^2}{4bz}\right)$$

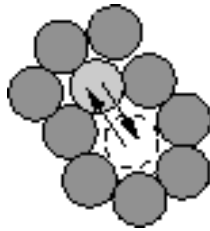
What is “diffusing”?



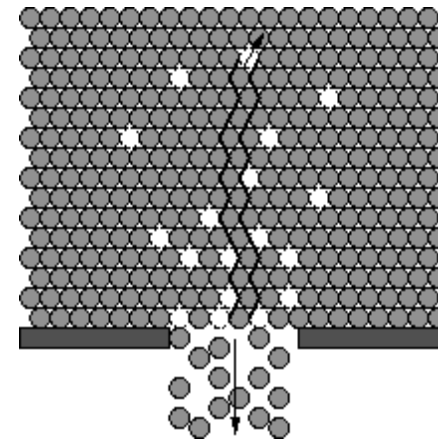
Microscopic Flow Mechanisms for Dense Amorphous Materials

1. “Vacancy” mechanism for flow in viscous liquids (Eyring, 1936);

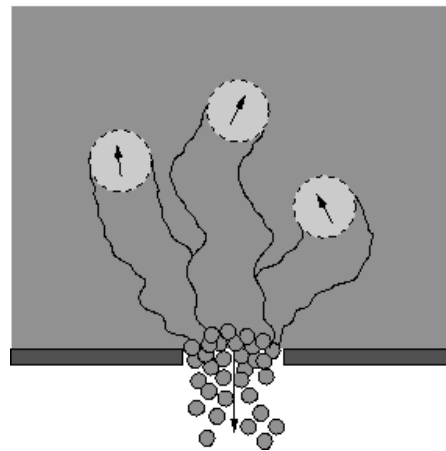
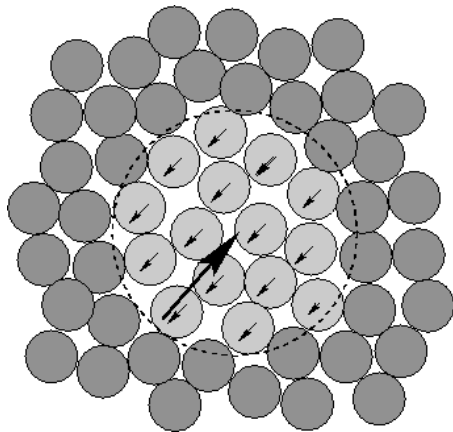
Also: “free volume” theories of glasses (Turnbull & Cohen 1958, Spaepen 1977,...)



2. “Void” model for granular drainage (Litwiniszyn 1963, Mullins 1972)



3. “Spot” model for random-packing dynamics (M. Z. Bazant, Mechanics of Materials 2005)



4. “Localized inelastic transformations” (Argon 1979, Bulatov & Argon 1994)

“Shear Transformation Zones” (Falk & Langer 1998, Lemaitre 2003)

DEM



Spot Model



Void Model

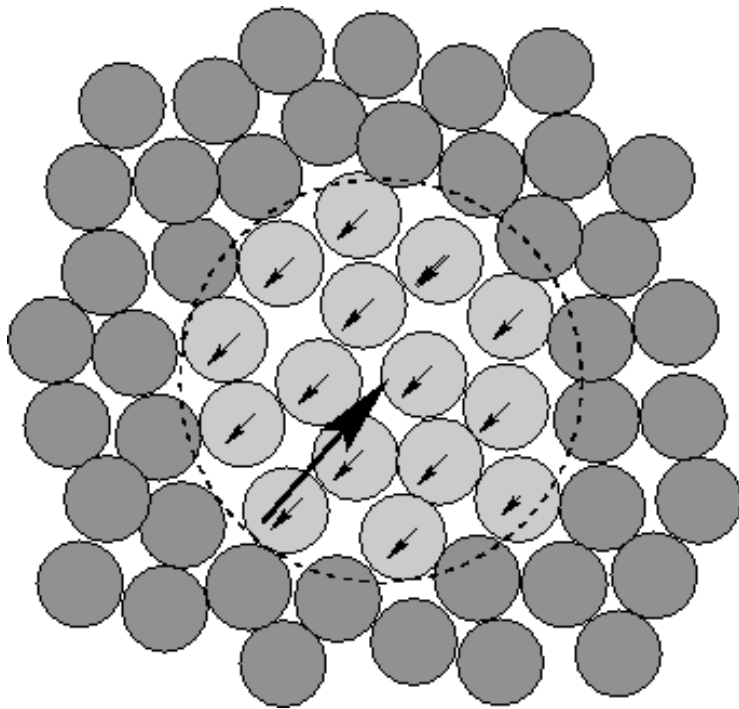


Simple spot model predicts mean flow and tracer diffusion in silo drainage fairly well (with only 3 params), but does not enforce packing constraints.

Simulations by Chris Rycroft

Correlations Reduce Diffusion

Simplest example: A uniform spot affects N particles.



- Volume conservation (approx.)

$$N V_p (\Delta x_p, \Delta z_p) = -V_s (\Delta x_s, \Delta z_s)$$

- Particle diffusion length

$$b_p = \frac{\text{Var}(\Delta x_p)}{2|\Delta z_p|} = \frac{\alpha^2 \text{Var}(\Delta x_s)}{2\alpha \Delta z_s} = \alpha b$$

where

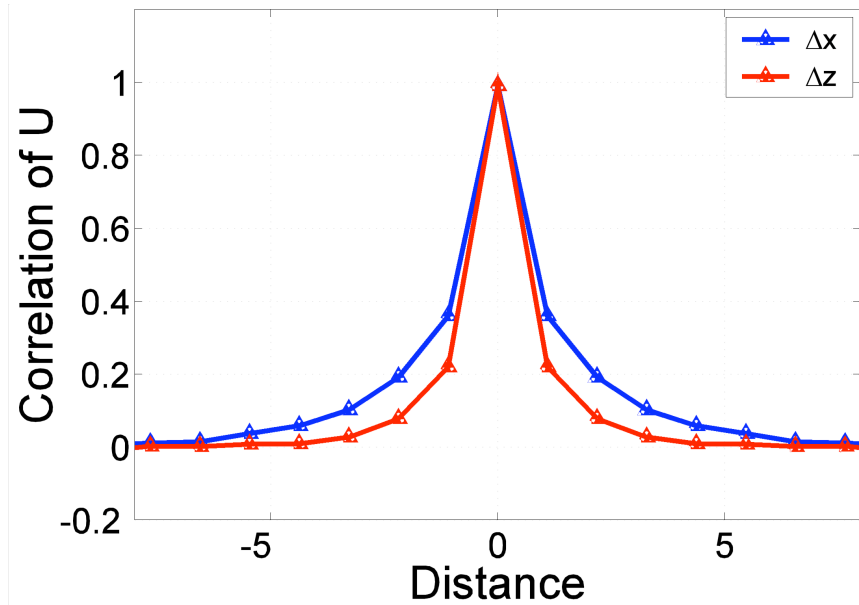
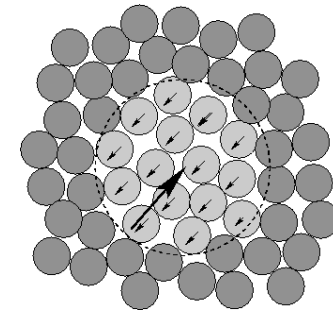
$$\alpha = \frac{V_s}{N V_p} \approx \frac{\Delta \phi}{\phi^2} \approx 10^{-2}$$

Experiment: 0.0025 DEM Simulation: 0.0024 (some spot overlap)

Direct Evidence for Spots

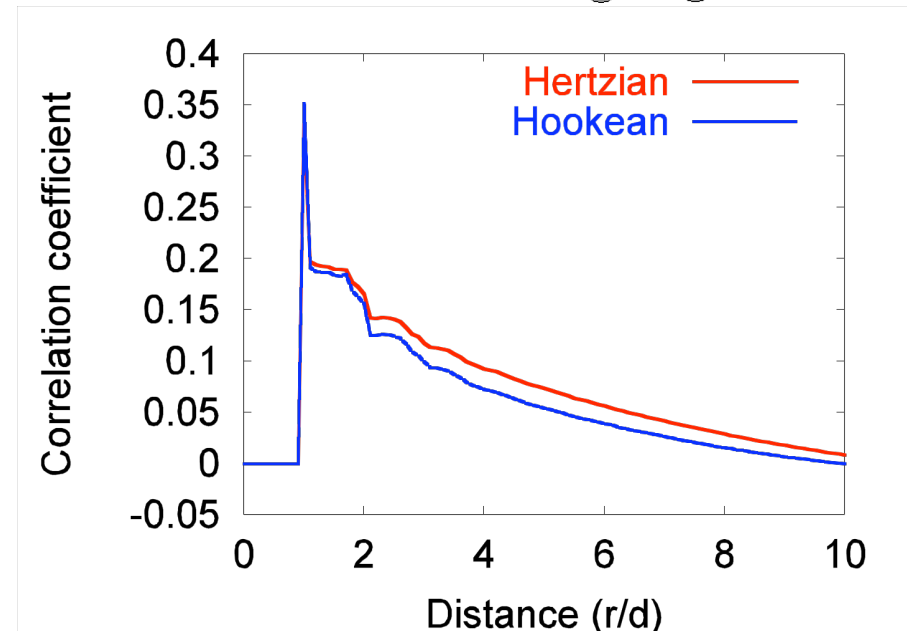
Spatial correlations in velocity fluctuations

(like “dynamic heterogeneity” in glasses)



EXPERIMENTS

- MIT Dry Fluids Lab
- 3mm glass beads, slow flow (mm/sec)
- particle tracking by digital video
- 125 frames/sec, 1024-1024 pixels
- 0.01d displacements (near wall)

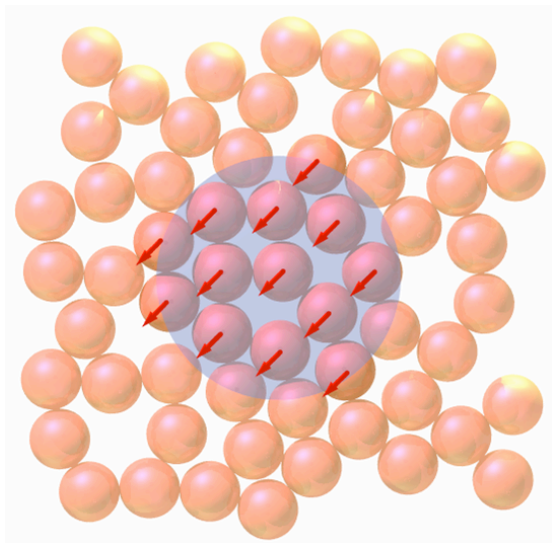


SIMULATIONS

- 3d molecular dynamics (discrete elements)
- Sandia parallel code on 32-96 processors
- Friction, Coulomb yield criterion
- Visco-elastic damping
- Hertzian or Hookean contacts

“Multi-scale” Spot Algorithm

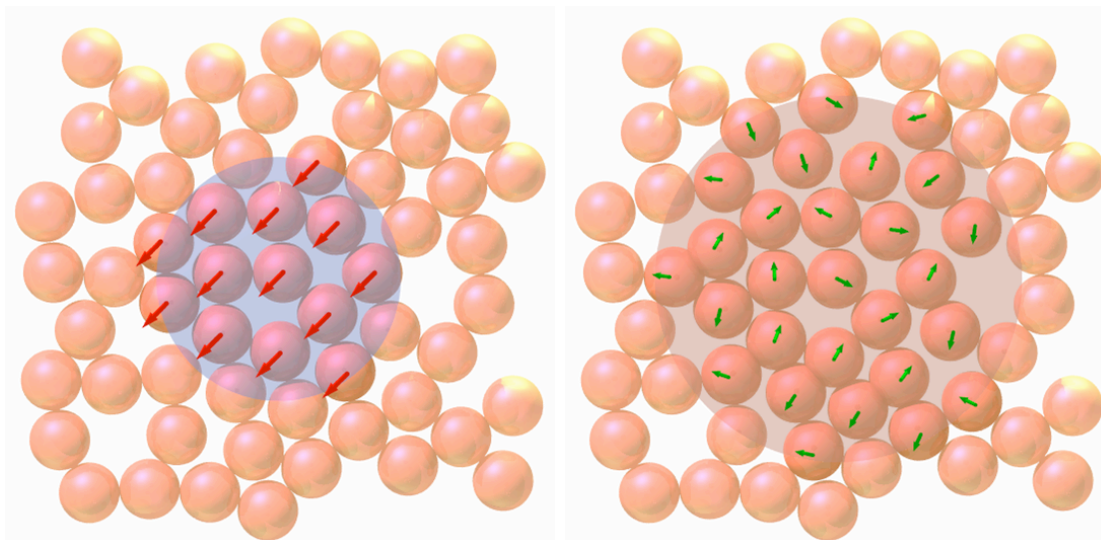
1. Simple spot-induced motion



- Apply the usual spot displacement first to all particles within range

“Multi-scale” Spot Algorithm

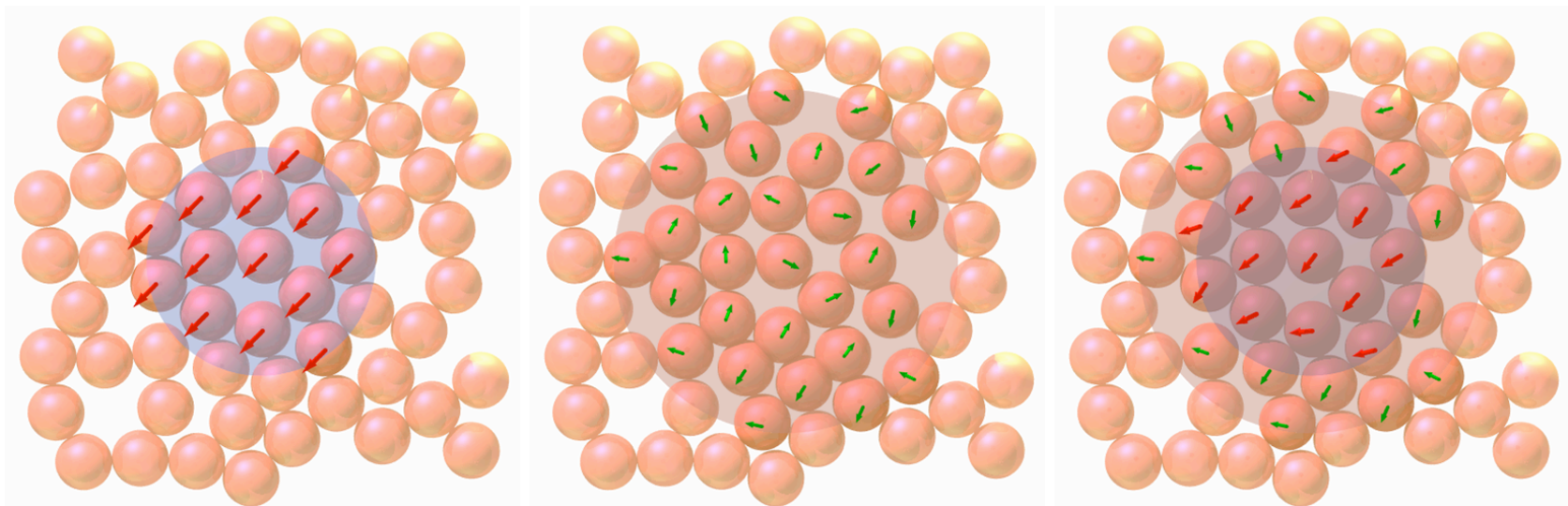
2. Relaxation by soft-core repulsion



- Apply a relaxation step to all particles within a larger radius
- All overlapping pairs of particles experience a normal repulsive displacement (soft-core elastic repulsion)
- Very simple model - no “physical” parameters, only *geometry*.

“Multi-scale” Spot Algorithm

3. Net cooperative displacement



- Mean displacements are mostly determined by basic spot motion (80%), but packing constraints are also enforced
- *Can this algorithm preserve reasonable random packings?*
- *Will it preserve the simple analytical features of the model?*

Spot Model

DEM

3d Multiscale Model

Rycroft, Bazant, Landry, Grest (2005)

- Infer 3 spot parameters from DEM, as from expts:

- * radius = $2.6 d$

- * volume = $0.33 v$

- * diffusion length = $1.39 d$

- Relax particles each step with soft-core repulsion

- “Time” = number of drained particles

- Very similar results as DEM, but $>100x$ faster

- How might spot dynamics follow from mechanics in more general



Classical Mohr-Coulomb Plasticity

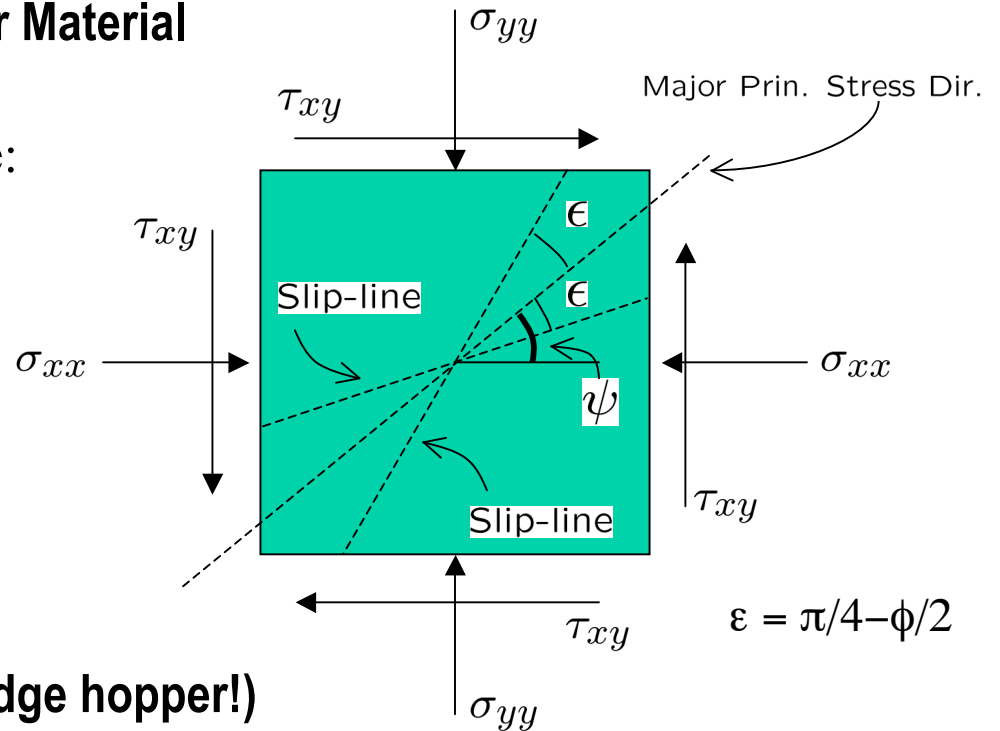
1. Theory of Static Stress in a Granular Material

Assume “incipient yield” everywhere:

$$(\tau/\sigma)_{\max} = \mu$$

μ = internal friction coefficient

ϕ = internal failure angle = $\tan^{-1}\mu$

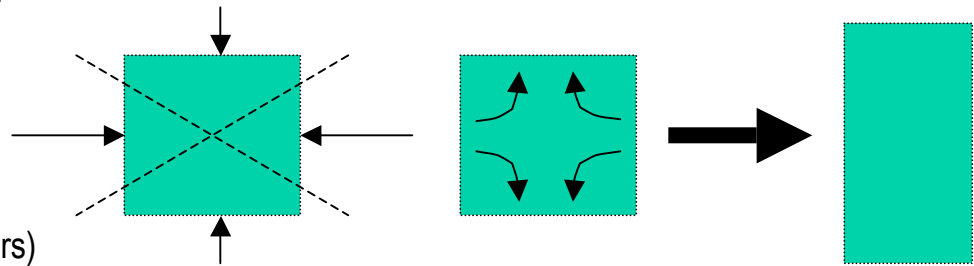


2. Theory of Plastic Flow (only in a wedge hopper!)

Levy flow rule / Principle of coaxiality:

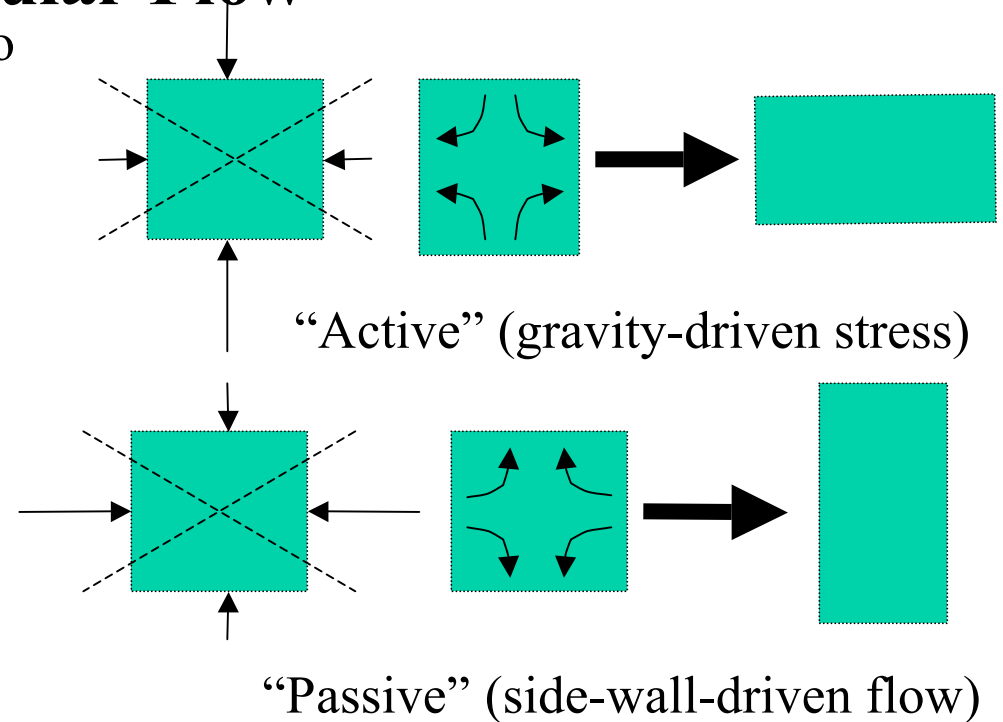
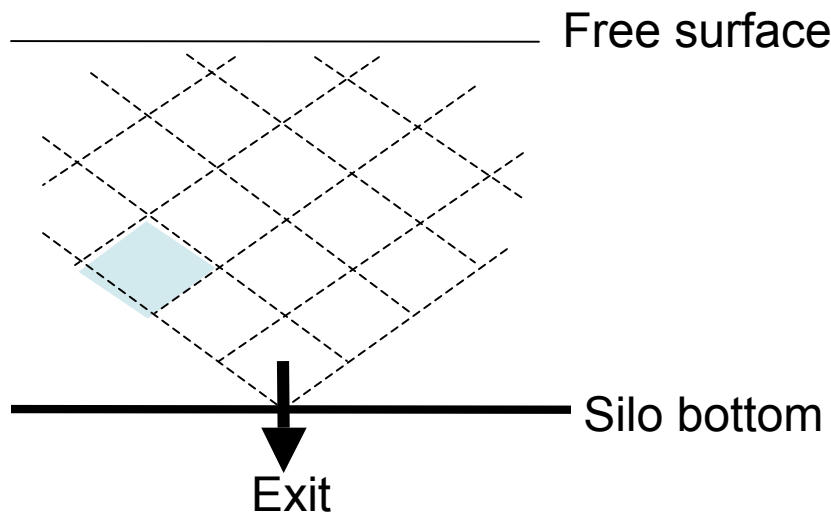
Assume equal, continuous slip along *both* incipient yield planes

(stress and strain-rate tensors have same eigenvectors)

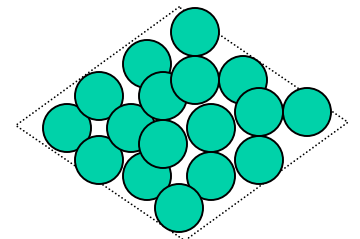


Failures of Classical Mohr-Coulomb Plasticity to Describe Granular Flow

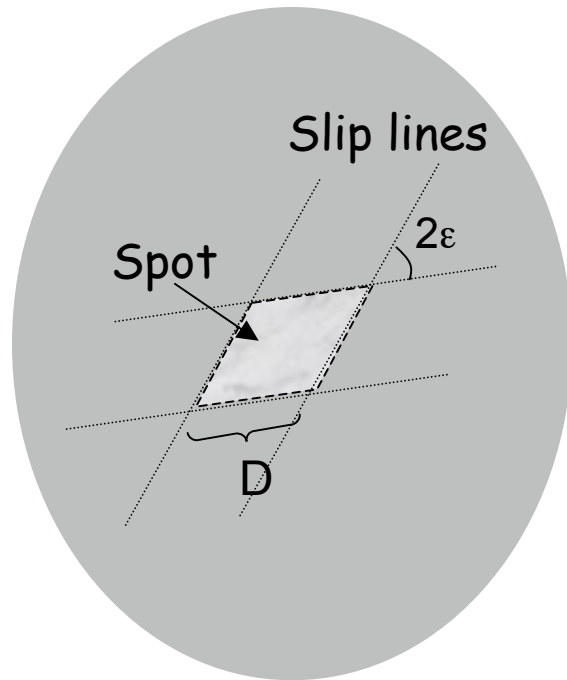
1. Stresses must change from active to passive at the onset of flow in a silo (to preserve coaxiality).



2. Walls produce complicated velocity and stress discontinuities (“shocks”) not seen in experiments with cohesionless grains.
3. No dynamic friction
4. **No discreteness and randomness** in a “continuum element”

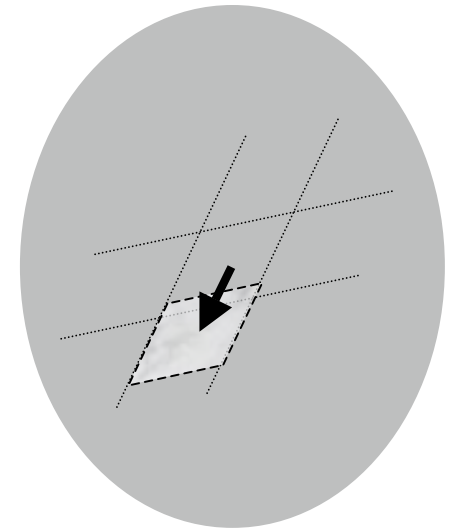
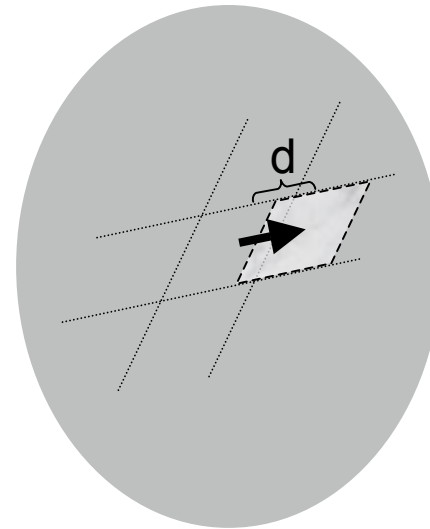


Idea (Ken Kamrin):
Replace coaxiality with
an appropriate discrete
spot mechanism

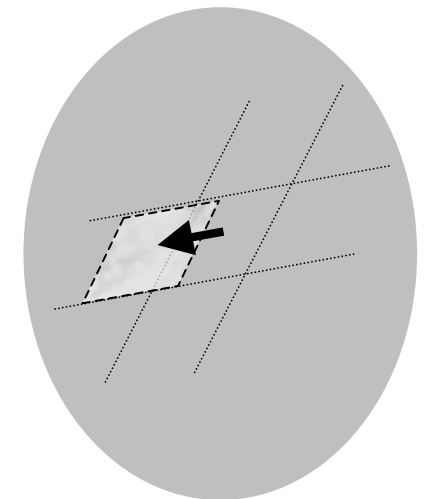
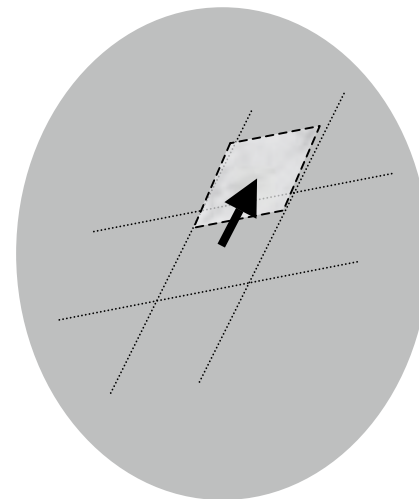


Spots random walk along
Mohr-Coloumb slip lines
(but not on a lattice)

Similar ideas in lattice models for glasses:
Bulatov and Argon (1993), Garrahan & Chandler (2004)



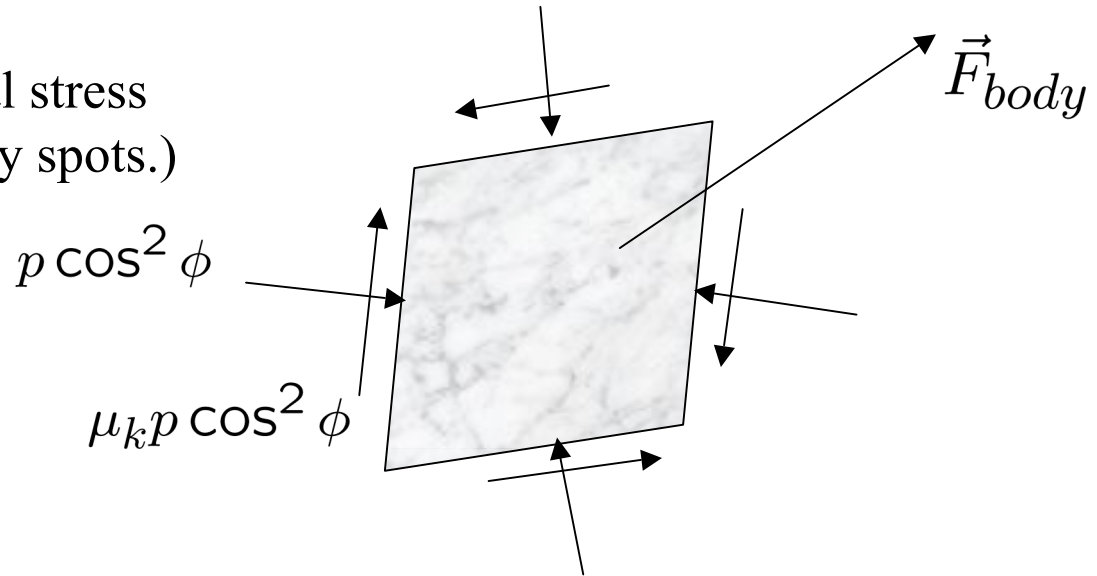
Stochastic "Flow Rule"



A Simple Theory of Spot Drift

Spot = localized failure where μ is replaced by μ_k (static to dynamic friction)

(Assume quasi-static global stress distribution is unaffected by spots.)



Net force on the particles affected by a spot

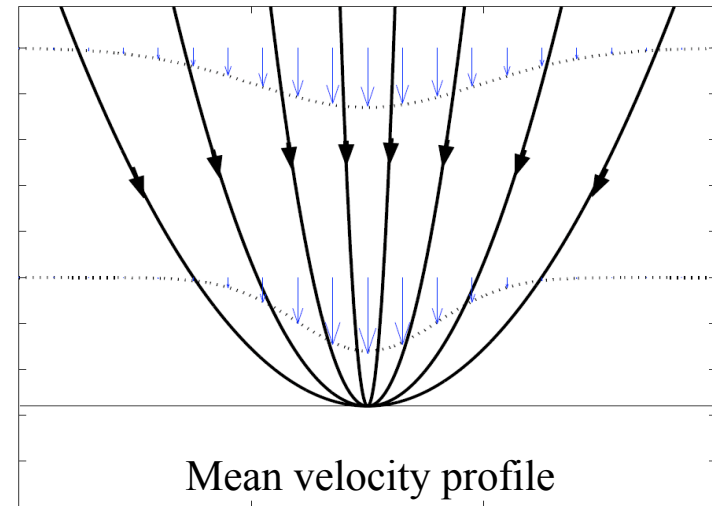
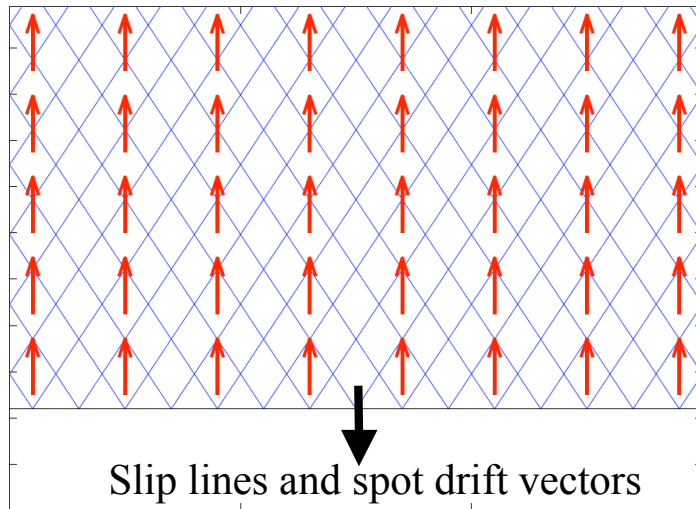
$$\vec{F}_{net} = (1 - \mu_k/\mu) (\vec{F}_{body} - \cos^2 \phi \vec{\nabla} p)$$

A spot's random walk is biased by this force projected along slip lines.

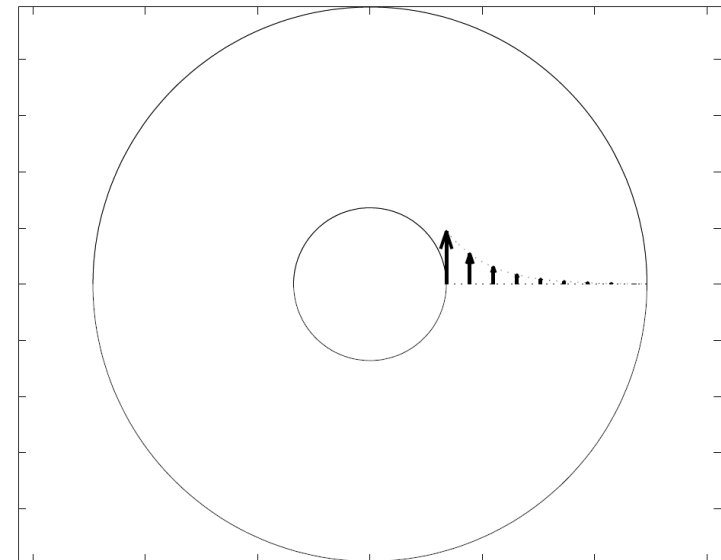
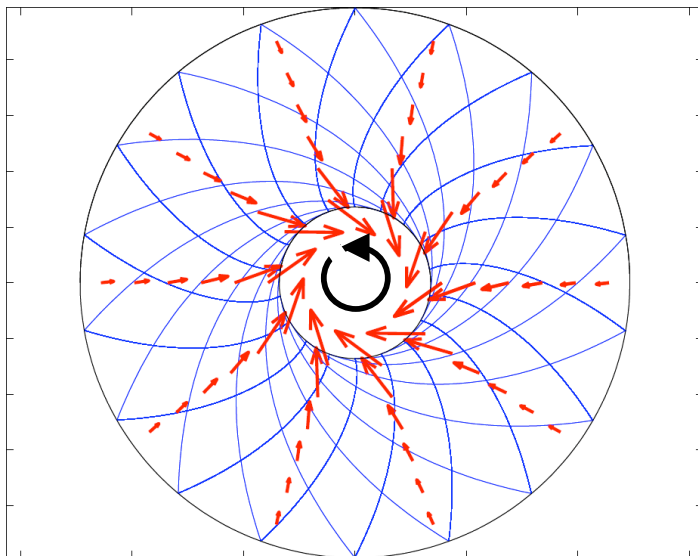
Next derive a Fokker-Planck equation for particle drift and diffusion which depends non-locally on the spot distribution in space (and time?)...

A General Theory of Dense Granular Flow?

Gravity-driven drainage from a wide quasi-2d silo: Predicts the kinematic model

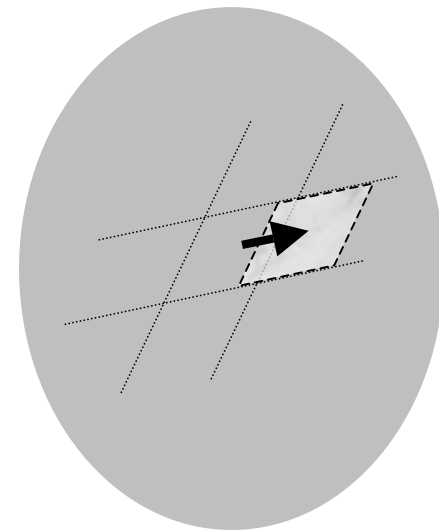
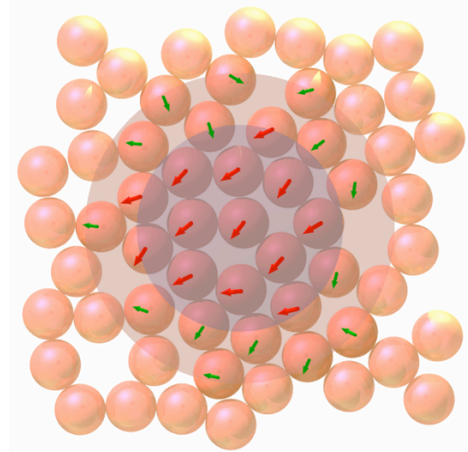


Coette cell with a rotating rough inner wall: Predicts shear localization



Conclusion

- “**Spot model**” = precise, simple mechanism for the dynamics of dense random packings
- Random walk of spots along slip lines yields “**stochastic flow rules**” for continuum plasticity
- Stochastic Mohr-Coulomb plasticity seems capable of predicting *different* granular flows
- Interactions between spots?
Extend to 3d, other materials,....?



For papers, movies,... <http://math.mit.edu/dryfluids>

Mohr-Coulomb Stress Equations (assuming incipient yield everywhere)

$$(1 + \sin \phi \cos 2\psi)p_x - 2p \sin \phi \sin 2\psi \psi_x + \sin \phi \sin 2\psi p_y + 2p \sin \phi \cos 2\psi \psi_y = F_x^{body}$$

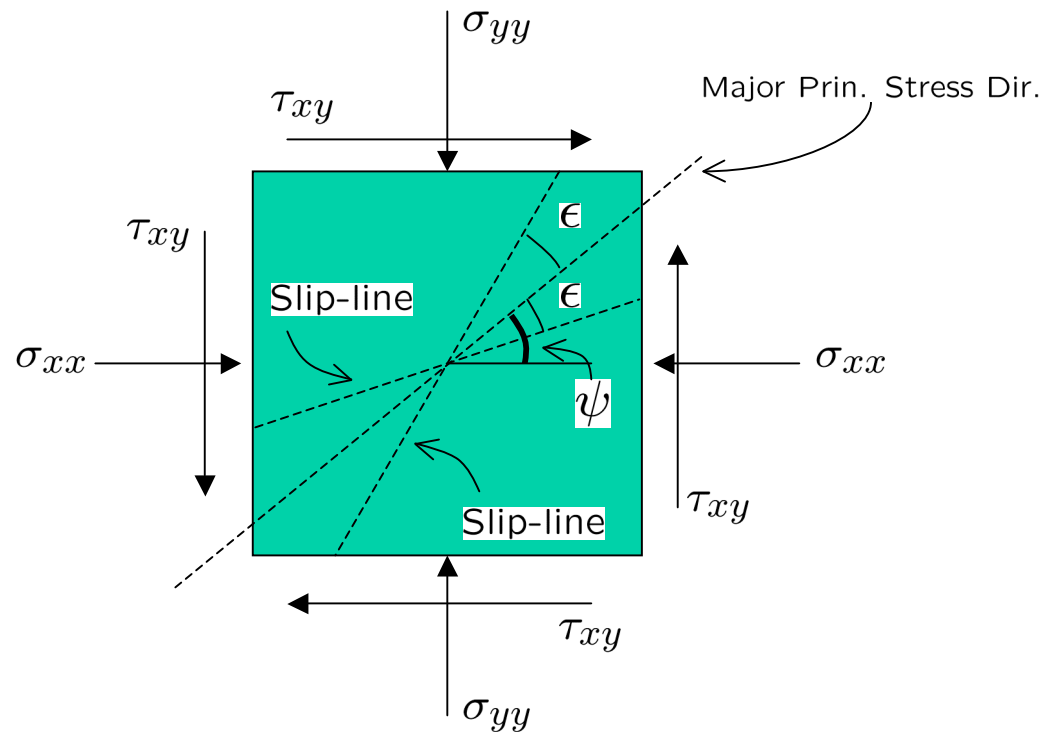
$$\sin \phi \sin 2\psi p_x + 2p \sin \phi \cos 2\psi \psi_x + (1 - \sin \phi \cos 2\psi)p_y + 2p \sin \phi \sin 2\psi \psi_y = F_y^{body}$$

Characteristics
(the slip-lines)

$$\frac{dy}{dx} = \tan(\psi - \epsilon)$$

$$\frac{dy}{dx} = \tan(\psi + \epsilon)$$

$$\epsilon = \pi/4 - \phi/2$$



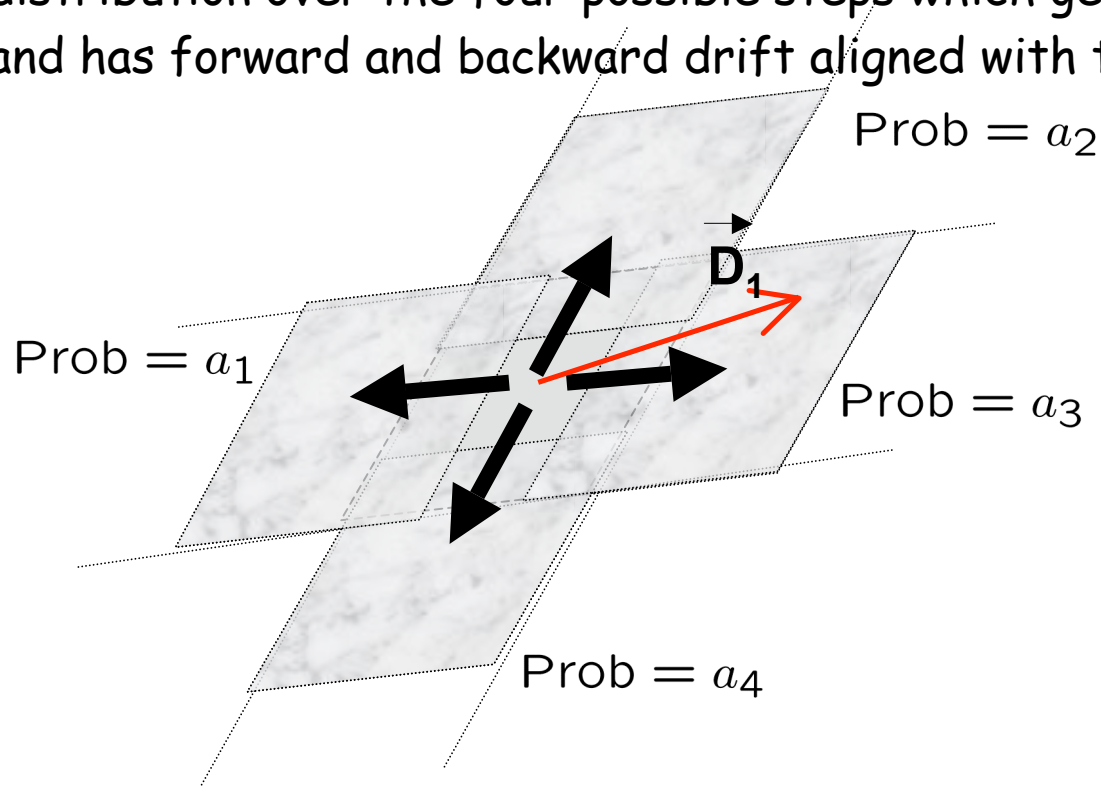
$$p = \frac{\sigma_{xx} + \sigma_{yy}}{2} = \text{Average normal stress}$$

$$\psi = -\frac{1}{2} \arctan \left(\frac{2\tau_{xy}}{\sigma_{xx} - \sigma_{yy}} \right) = \text{Angle anti-clockwise from x-axis to major principal stress direction}$$

- Spot drift opposes the net material force.
- Spots drift through slip-line field constrained only by the geometry of the slip-lines. Probability of motion along a slip-line is proportional to the component of $-F_{\text{net}}$ in that direction. Yields drift vector:

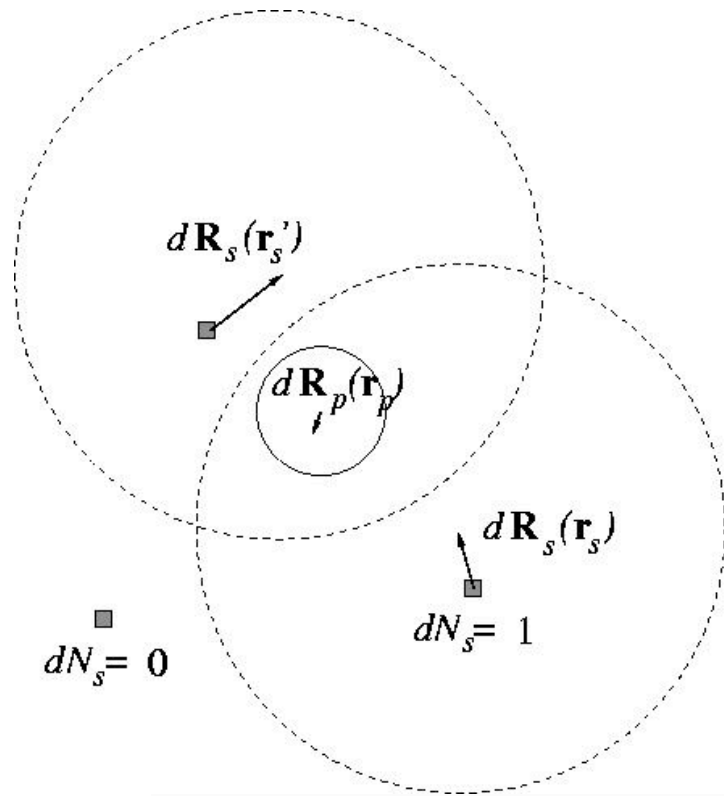
$$\vec{D}_1 = -\gamma (1 - \mu_k / \mu) \left(\mathbf{I} + \cos 2\epsilon \begin{bmatrix} \cos 2\psi & \sin 2\psi \\ \sin 2\psi & -\cos 2\psi \end{bmatrix} \right) (\vec{F}_{\text{body}} - \cos^2 \phi \vec{\nabla} p)$$

- For diffusion coefficient \underline{D}_2 , must solve for the unique probability distribution over the four possible steps which generates the drift vector and has forward and backward drift aligned with the drift direction.



$$\frac{a_1}{a_4} = \frac{a_3}{a_2}$$

A *Nonlocal* Stochastic Differential Equation for Tracer Diffusion



w = spot influence function

$$d\mathbf{R}_p(\mathbf{r}_p, t) = - \int dN_s(\mathbf{r}_s, t) w(\mathbf{r}_p, \mathbf{r}_s + d\mathbf{R}_s(\mathbf{r}_s, t)) d\mathbf{R}_s(\mathbf{r}_s, t)$$

Random Riemann sum of random variables:

$$\Delta\mathbf{R}_p(\mathbf{r}_p) = - \sum_n \sum_{j=1}^{\Delta N_s^{(n)}} w\left(\mathbf{r}_p, \mathbf{r}_s^{(n)} + \Delta\mathbf{R}_s^{(j)}(\mathbf{r}_s^{(n)})\right) \Delta\mathbf{R}_j^{(n)}(\mathbf{r}_s^{(n)})$$

A Mean-field Fokker-Planck Equation

$$\frac{\partial P_p}{\partial t} + \nabla \cdot (\mathbf{u}_p P_p) = \nabla \nabla : (\mathbf{D}_p P_p)$$

- Poisson process for spot positions
- Independent spot displacements

$$\langle dN_s \rangle = \text{Var}(dN_s) = \rho_s dV$$

Drift velocity

$$\mathbf{u}_p(\mathbf{r}_p, t) = - \int d\mathbf{r}_s w(\mathbf{r}_p, \mathbf{r}_s) [\rho_s(\mathbf{r}_s, t) \mathbf{u}_s(\mathbf{r}_s, t) - 2 \mathbf{D}_s(\mathbf{r}_s, t) \cdot \nabla \rho_s(\mathbf{r}_s, t)]$$

Diffusivity tensor

$$\mathbf{D}_p(\mathbf{r}_p, t) = \int d\mathbf{r}_s w(\mathbf{r}_p, \mathbf{r}_s)^2 \rho_s(\mathbf{r}_s, t) \mathbf{D}_s(\mathbf{r}_s, t)$$