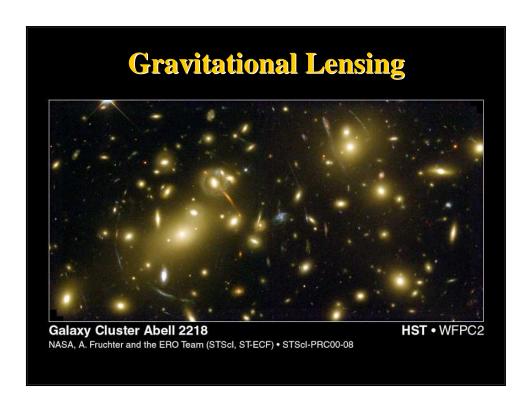
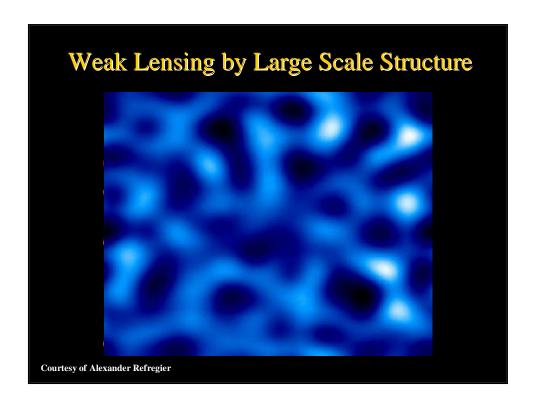


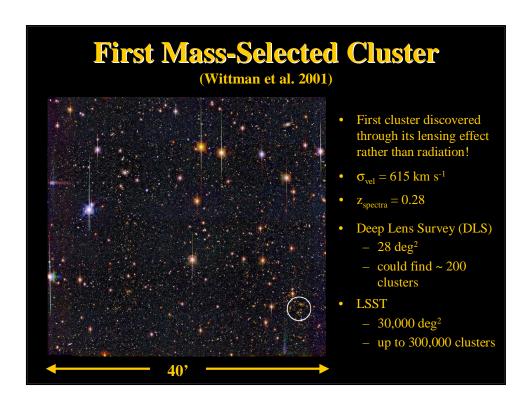


Outline

- Galaxy clusters from weak lensing
- Dark clusters?
- Cluster Tomography
- N-body simulations
- Optimal filtering
- Constraining dark energy

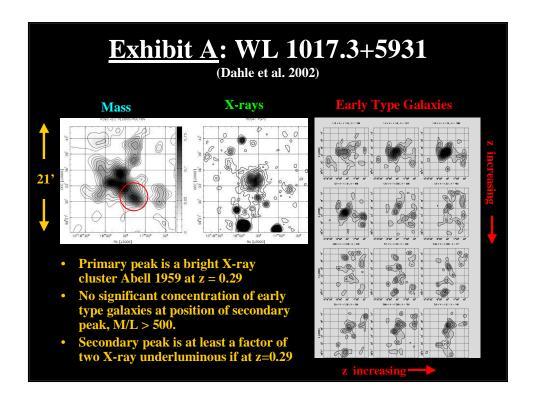


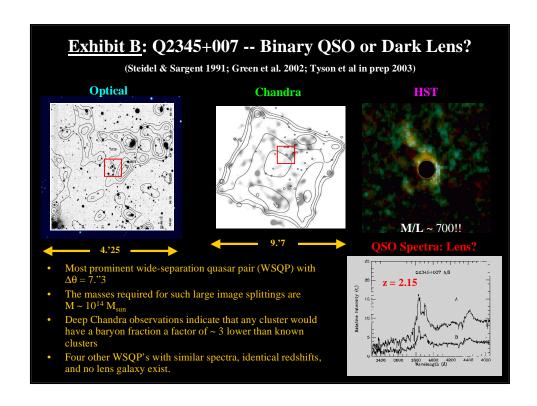


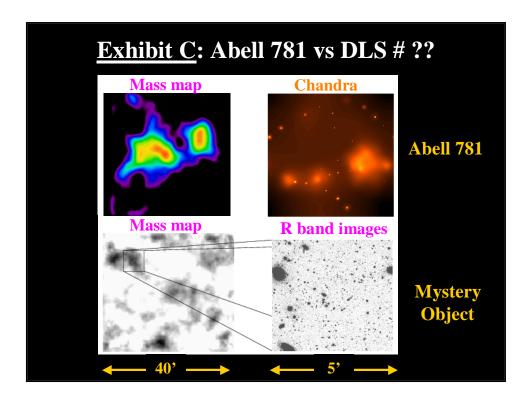


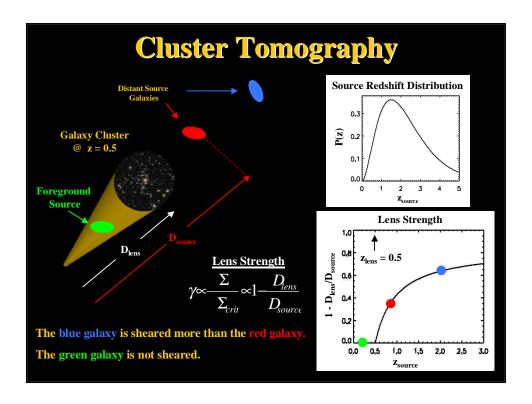
Mass-Selected Cluster Samples How can we find clusters of galaxies? Optical - X-ray Biased? Sunyaev-Zeldovich effect Weak lensing survey The first Mass-Selected cluster sample WILL: • Determine biases in other cluster samples - richness and morphology? - relaxed or merging? • Test the "fair sample" hypothesis used to determine $\Omega_{\rm m}$. Is there a class of high M/L clusters? • Number counts. Cosmological parameters with little assumption about baryons in clusters CONSTRAIN DARK ENERGY Is there a population of DARK CLUSTERS?

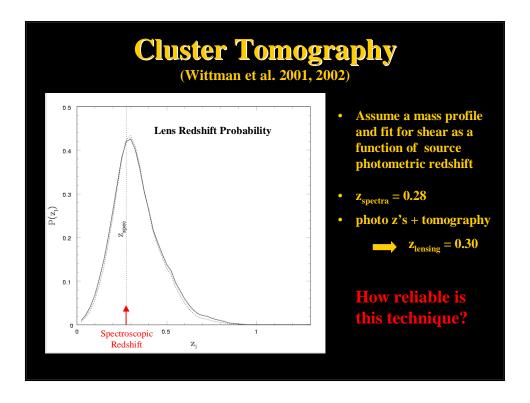
The Case For Dark Clusters (circa 2002)

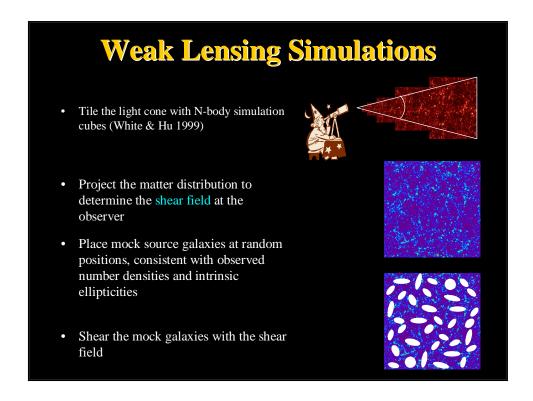








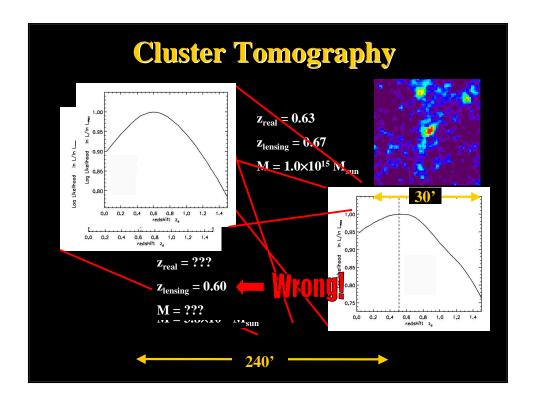


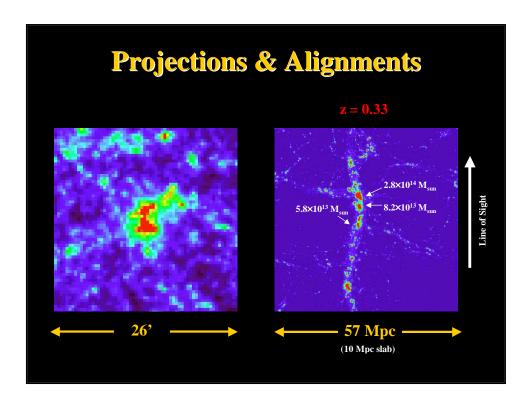


Weak Lensing Simulations Smooth the shear field with an "optimal filter" and search for peaks Apply a group finder to find collapsed halos. Detected clusters are traced back to simulations cubes for cluster statistics. Friends of Friends

Advantages of Simulations

- Properly simulate alignments and projections, which can be severe.
- The selection function can be simulated for any cosmology, foregoing the need to acquire a "complete" sample.
- Mock observations allow us to Monte-Carlo simulate parameter estimates, for realistic error forecasts.
- Fast Particle Mesh (PM) algorithm:
 - simulate large areas of sky to accurately represent the statistics of rare events (every cluster is unique)
 - allows rapid exploration of parameter space





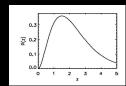
Optimal Filtering

- "Noise" in weak lensing searches for clusters requires that shear maps be smoothed
 - white noise from finite sampling and intrinsic ellipticities
 - confusion from large scale structure
 - projection effects
- For white noise a "matched filter" will optimally extract a signal of known shape
- Galaxy clusters are identified as the peaks in smoothed maps that lie above a threshold $\boldsymbol{\nu}$
- For any given threshold v define the efficiency as the ratio efficiency = $n_{clusters}$ (> V) / n_{peaks} (> V)

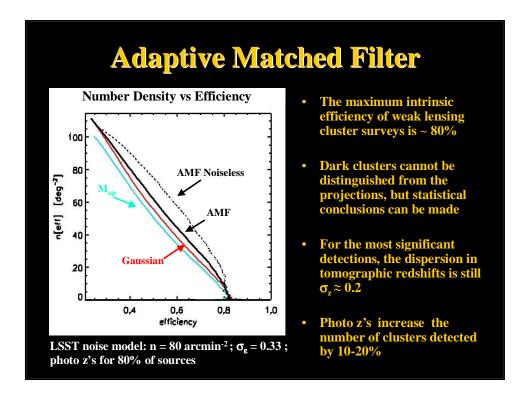
Adaptive Matched Filter

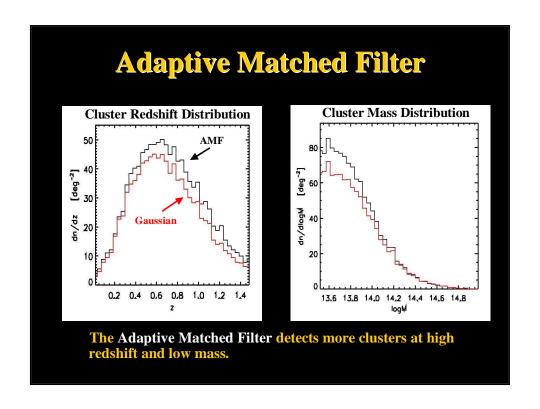
• In the absence of source redshifts, the observable is the mean shear averaged over the source redshift distribution

$$\bar{\gamma} = \int P(z) \, \gamma(z) \, dz$$



- · Two filters have been widely used on this quantity
 - Gaussian
 - Aperture Mass M_{an}(θ)
- If photometric redshifts are available for some sources, tomography and matched filtering can be combined.
- Adaptive Matched Filtering uses redshift information to optimally weight source galaxies, producing a likelihood and tomographic redshift for each line of sight





Cluster Counting Basics

- Goal: Determine cosmological parameters by comparing the observed distribution of clusters to predictions from theory/N-body simulations
- However cluster mass is not an observable. Instead we measure:
 - SZ decrement
 - X-rays (L_X or T_X)
 - Richness
 - Galaxy σ_{v}
 - Shear γ
- To interpret the observations we must know
 - M(observables,z)
 - Completeness(observables,z)

Cluster Counting Caveats

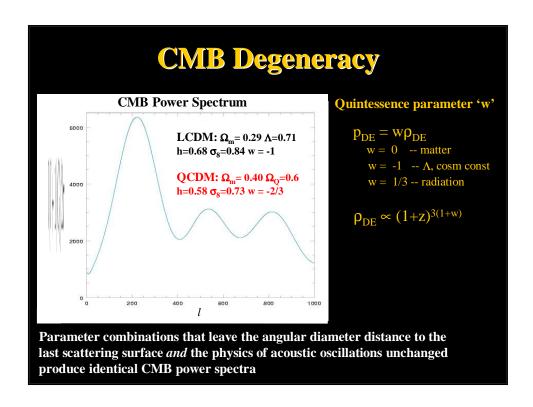
• Usually one writes

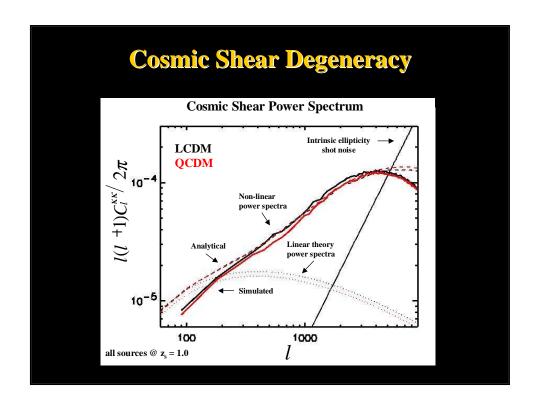
$$\frac{dN}{d\Omega dz}(w) = \frac{dV}{d\Omega dz} \int_{M_{\text{limit}}(z)}^{\infty} C(M,z) \frac{dn}{dM} (M,z \mid w) dM$$

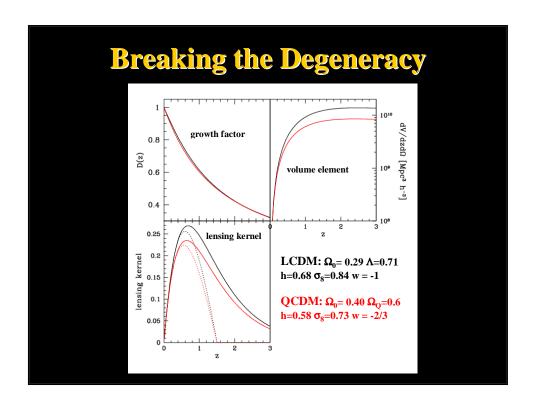
Are we learning about this number?

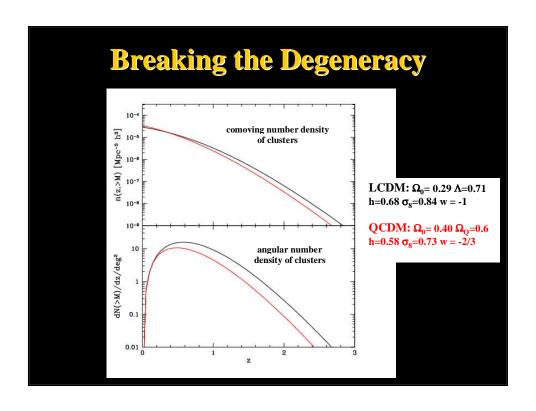
Or about these quantities?

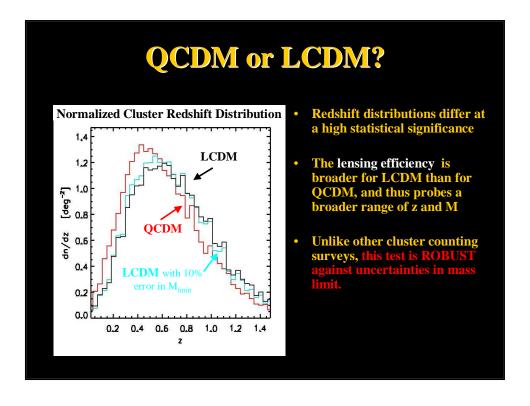
- The mass function is steep and exponentially sensitive to errors in M_{limit} (z) and uncertainty in M(observables,z). These errors mimic cosmological parameter changes!
- Until these relationships (and their scatter) can be empirically calibrated, this test relies on uncertain assumptions about baryons in clusters
- Solutions: Either determine M_{limit} (z) from your cluster survey, or devise a test that is insensitive to the limiting mass.











Conclusions

- Fast numerical simulations of weak lensing are a valuable tool to accurately predict cluster statistics over a large region of parameter space
- Using photo z's with an Adaptive Matched Filter detects up to 10-20% more clusters and recovers more clusters at high redshift and low mass.
- Even for the most significant detections, the dispersion in tomographic redshifts is still $\sigma_z{\approx}~0.2.$
- Weak lensing cluster surveys are plagued by projections --- the maximum intrinsic efficiency is ~ 80%.
- Only statistical statements about a population of dark clusters can be made from weak lensing
- The normalized redshift distribution of mass selected clusters is a powerful probe of dark energy and is insensitive to uncertainties in the mass limit.