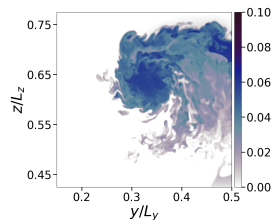
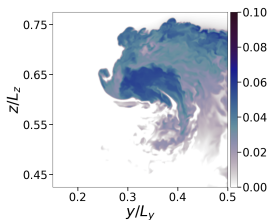
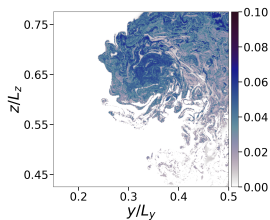


LES and more...

S. Böing
with D. Dritschel, D. Parker & A. Blyth
Universities of Leeds & St Andrews
April 9, 2018



Contents

- 1 What is MPIC?
- 2 MPIC: comparison to LES
- 3 Current plans
- 4 eCSE project: implementation in MONC
- 5 Conclusions
- 6 Some other points for LES discussions

Not LES, not boundary layers (yet)

https:

//www.videvo.net/video/cumulonimbus-clouds-timelapse/4708/

Hybrid Lagrangian-Eulerian modelling

The basic conservation principles of fluid dynamics are most naturally expressed in a Lagrangian way: e.g. mass is conserved *following* fluid “particles”.

However, certain fields are more naturally Eulerian in character, e.g. pressure. These fields are completely or largely determined by “integration”, i.e. *through inversion relations* like Poisson’s equation.

Conservation is Lagrangian. Inversion is Eulerian.

Computational methods exploiting this distinction may benefit from using a mixed, hybrid approach.

(semi)-Lagrangian modelling of the atmosphere

The idea goes back as far as **Sawyer (1963)**: “A semi-Lagrangian method for solving the **vorticity advection** equation.”

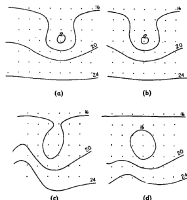


Fig. 30. Correct stream function (for initial field displaced by 4 grid-lengths), b. Computed stream function by semi-Lagrangian procedure, c. Computed stream function by Eulerian (3-3-3) scheme, d. Computed stream function by Eulerian (3-5-3) scheme.



The UK Met Office uses **Semi-Lagrangian (SL)** advection for efficiency (however conservation is challenging).

Gadian (1989): simulations using **fully Lagrangian smoothed particle hydrodynamics** for **2D** cloud studies.

Shutts and Allen (2007): fast **SL** schemes inspired by gaming.

Moist Parcel-In-Cell (MPIC)

The new “Moist Parcel-In-Cell” (MPIC) algorithm goes further by **representing the continuum by discrete “cloud parcels”**.

We use **freely-moving parcels** carrying *any number* of **attributes** (e.g. **liquid water potential temperature** θ_ℓ , **specific humidity** q , etc...)

The prototype model was developed for 3D incompressible flow (Boussinesq, no rotation):

$$\frac{D\mathbf{u}}{Dt} = -\frac{\nabla p}{\rho_0} + b\hat{\mathbf{e}}_z, \quad \frac{Db_\ell}{Dt} = 0, \quad \frac{Dq}{Dt} = 0, \quad \nabla \cdot \mathbf{u} = 0$$

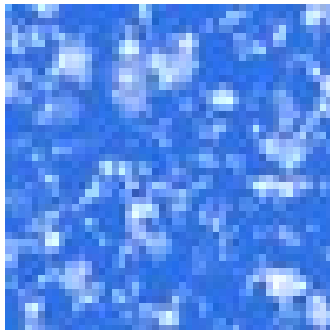
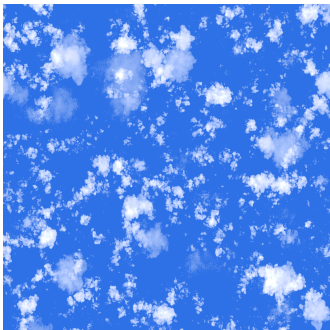
where the **total buoyancy** b is approximated by

$$b = b_\ell + \frac{gL}{c_p\theta_{\ell 0}} \max\left(0, q - q_0 e^{-\lambda z}\right).$$

Here, q_0 is a threshold **saturation humidity**, and λ is the **inverse condensation scale height**. L is the **latent heat of condensation**.

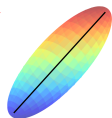
Motivation: grey zone

NWP/regional climate models now at 1-4 km resolution: turbulence poorly resolved. Large-Eddy Model resolution not affordable in medium long term.



The **liquid-water buoyancy** $b_\ell \equiv g(\theta_\ell - \theta_{\ell 0})/\theta_{\ell 0}$ where θ_ℓ is the **liquid-water potential temperature** and $\theta_{\ell 0}$ is a constant reference value.

In MPIC, each **fluid parcel** retains b_ℓ and q , *thereby exactly satisfying conservation*. Moreover, we evolve the vorticity $\omega = \nabla \times \mathbf{u}$ on parcels as ‘vortons’ (Novikov, 1983).



We use the **equivalent** form of the vorticity equation recommended in Cottet and Koumoutsakis (2001):

$$\frac{d\omega_i}{dt} = S(\mathbf{x}_i, t) \equiv (\nabla \cdot \mathbf{F}, \nabla \cdot \mathbf{G}, \nabla \cdot \mathbf{H}),$$

for each parcel $i = 1, \dots, n$, where

$$\mathbf{F} = \omega u - b \hat{e}_y \quad ; \quad \mathbf{G} = \omega v + b \hat{e}_x \quad ; \quad \mathbf{H} = \omega w.$$

We must also attach a **small volume** V_i to each parcel **in order to determine the contribution of each parcel to the fields of ω and b** represented on an underlying grid.

Interpolation: parcel \rightarrow grid communication

Tri-linear interpolation is used to transfer parcel properties to gridded values.

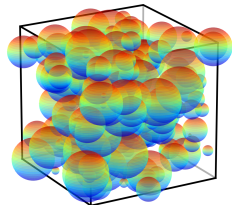
For example, the value of the buoyancy b at each grid point $\bar{\mathbf{x}} = (\bar{x}, \bar{y}, \bar{z})$ is determined from

$$b(\bar{\mathbf{x}}) = \bar{V}^{-1} \sum_{i \in \mathcal{P}} \phi(\mathbf{x}_i - \bar{\mathbf{x}}) b_i V_i \quad \text{where} \quad \bar{V} = \sum_{i \in \mathcal{P}} \phi(\mathbf{x}_i - \bar{\mathbf{x}}) V_i$$

where the **tri-linear weights** ϕ are given by

$$\phi(\mathbf{x}_i - \bar{\mathbf{x}}) = (1 - |x_i - \bar{x}|/\Delta x) (1 - |y_i - \bar{y}|/\Delta y) (1 - |z_i - \bar{z}|/\Delta z)$$

and \mathcal{P} is the set of all parcels within the 8 grid boxes surrounding $\bar{\mathbf{x}}$, while Δx , Δy and Δz are the grid lengths.



Advection: grid \rightarrow parcel communication

The parcel motion is found by solving the simple ODEs

$$\frac{d\mathbf{x}_i}{dt} = \mathbf{u}(\mathbf{x}_i, t)$$

using the gridded velocity field \mathbf{u} tri-linearly interpolated to the parcel position $\mathbf{x}_i(t)$.

The parcel velocity is given by

$$\mathbf{u}(\mathbf{x}_i, t) = \sum_{\bar{\mathbf{x}} \in \mathcal{G}} \phi(\mathbf{x}_i - \bar{\mathbf{x}}) \mathbf{u}(\bar{\mathbf{x}}, t)$$

where \mathcal{G} is the set of all grid points at the corners of the grid box containing parcel i .

Inversion: recovering the velocity field

The velocity field \mathbf{u} , needed to move the cloud parcels and to determine the vorticity source, is found by inverting $\boldsymbol{\omega}$ in a horizontally-periodic domain (in x and in y) bounded above and below by flat, free-slip boundaries at $z = L_z$ and $z = 0$.

To satisfy incompressibility ($\nabla \cdot \mathbf{u} = 0$), we take $\mathbf{u} = -\nabla \times \mathbf{A}$ where \mathbf{A} is a vector potential. From the definition of vorticity, we find

$$\boldsymbol{\omega} = \nabla \times \mathbf{u} = \nabla^2 \mathbf{A} - \nabla(\nabla \cdot \mathbf{A}).$$

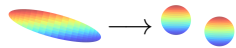
We are free to impose $\nabla \cdot \mathbf{A} = 0$, leading to

$$\boldsymbol{\omega} = \nabla^2 \mathbf{A},$$

Numerically, this is done in 'spectral space' after using Fast Fourier Transforms for accuracy and efficiency.

Parcel splitting and mixing

Splitting is controlled by prescribing the **maximum stretch** γ (default: 4) a parcel may undergo. The stretch of **each parcel** i is defined by

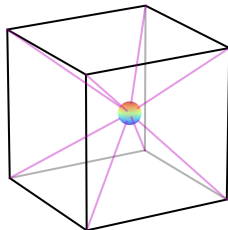

$$\gamma_i(t) = \int_{t_0}^t |\boldsymbol{\omega}_i \cdot d\boldsymbol{\omega}_i/dt|^{1/3} dt$$

where t_0 is the time since the parcel last split, or otherwise the initial time.

Parcel removal is controlled by prescribing the **minimum volume fraction** \hat{V}_{\min} (default: $1/6^3$) a parcel can have, i.e.

$$V_i/\Delta x \Delta y \Delta z \geq \hat{V}_{\min}.$$

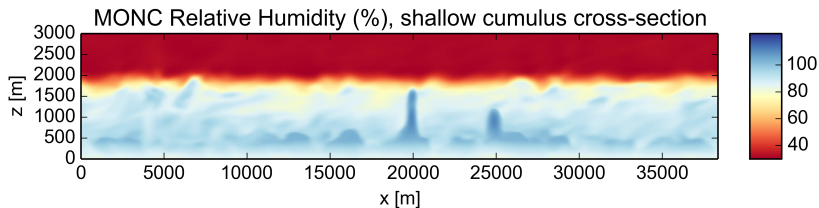
Removal: the properties of surrounding parcels are adjusted to exactly conserve total volume, mass and liquid water content.



Reference model: MONC

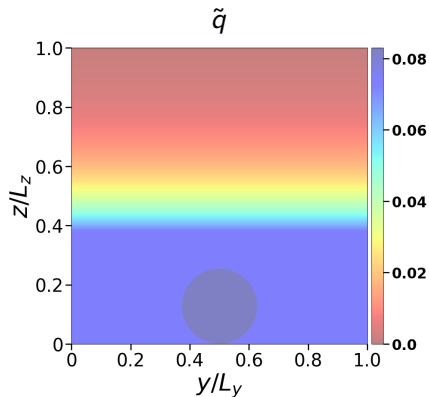
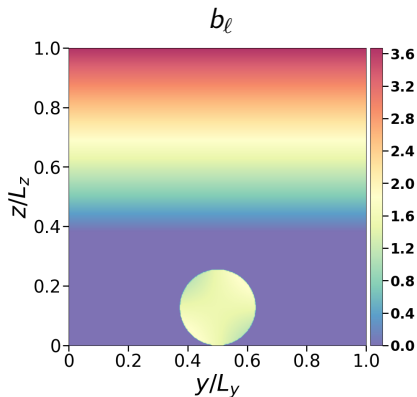
MONC: Met Office Large-Eddy Model recently **optimised** for use on **large parallel computers**.

EPCC/Met Office collaboration.



Finite difference model on staggered grid. **Smagorinsky subgrid model** using **nonlinear diffusion** to account for unresolved turbulence OR monotonical integration using TVD advection.

We start with a **spherical thermal** of **nearly uniform** b_ℓ and $\tilde{q} \equiv q/q_0$ in a **neutral layer** near the ground, with a **stratified zone** aloft. Here $x = 0$ is shown.

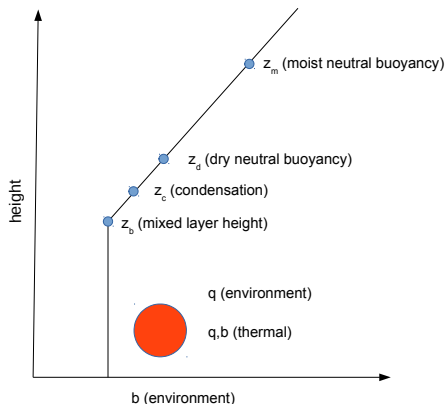


Vertical structure of the environment

The environment favours condensation (cloud formation) once the thermal rises past the lifting condensation level $z = z_c$.

This releases additional buoyancy, increasing the vertical acceleration, and takes the thermal past its level of dry neutral buoyancy $z = z_d$.

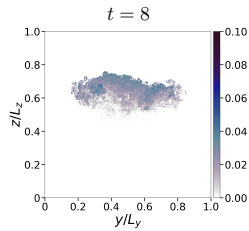
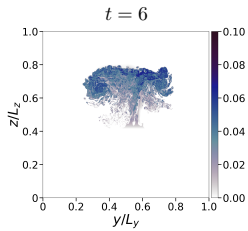
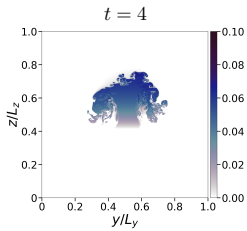
Only when the thermal encounters the level of moist neutral buoyancy $z = z_m$ (the nominal cloud top) is the upward acceleration arrested.



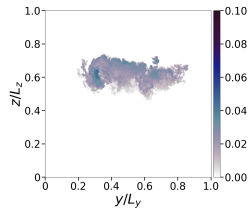
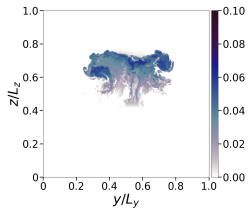
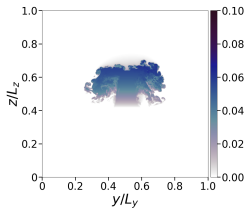
384³ MPIC and 1024³ MONC.

- 1) Evolution of liquid-water specific humidity.
- 2) Detailed zoom of liquid-water specific humidity, vorticity, vertical velocity at $t = 6$.

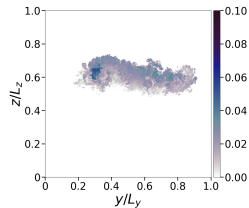
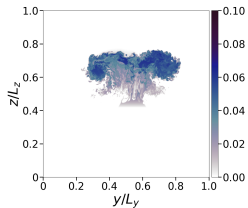
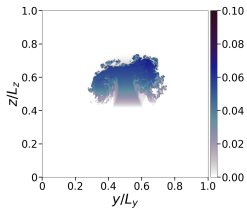
MPIC Detailed



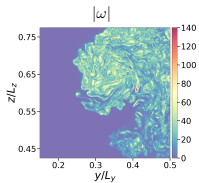
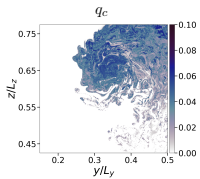
MONC Smagorinsky



MONC Implicit

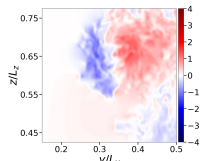
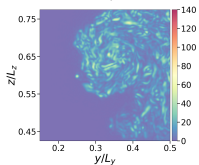
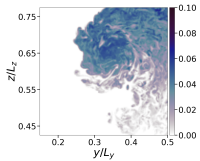


MPIC Detailed

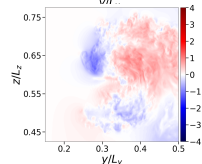
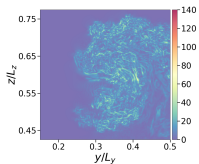
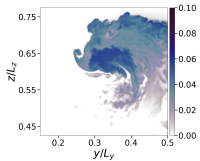


w
n/a

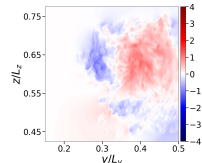
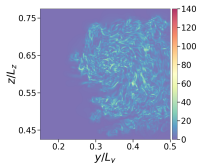
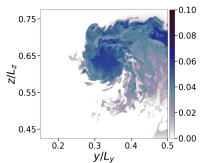
MPIC Gridded



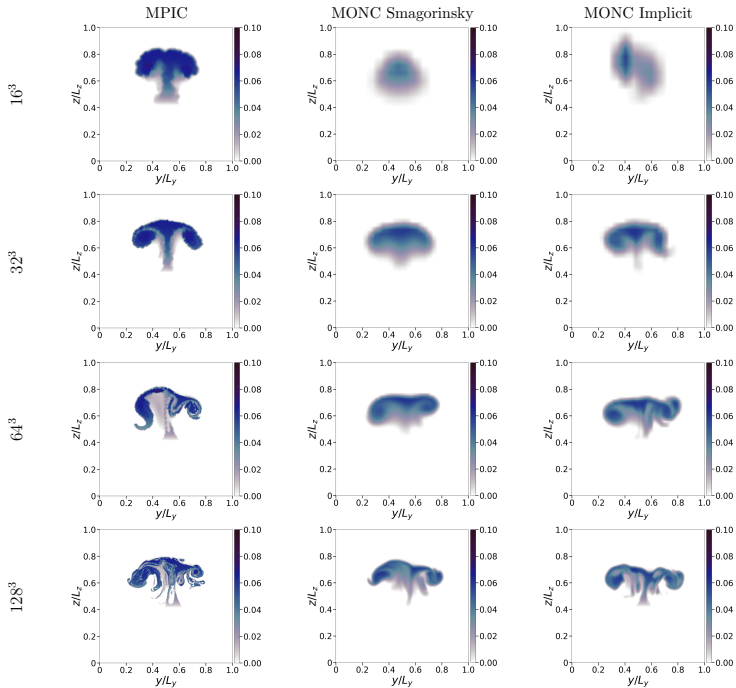
MONC Smagorinsky



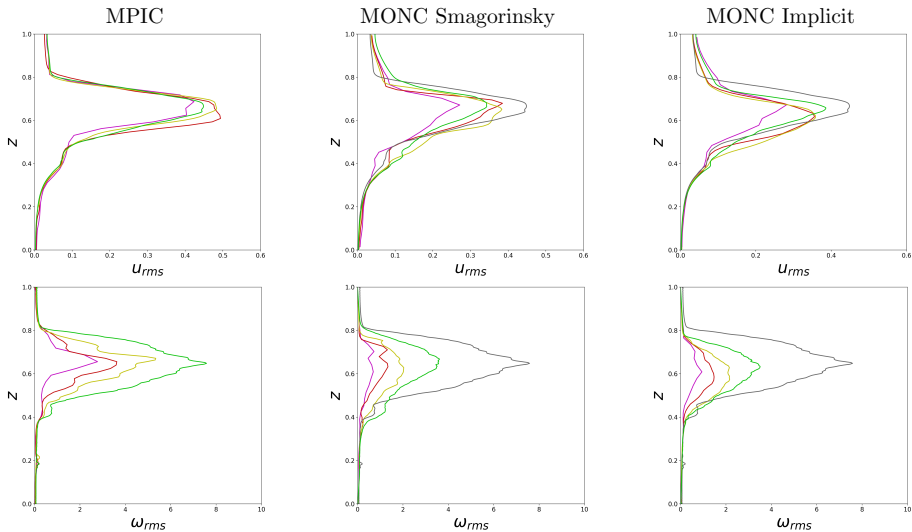
MONC Implicit



- 1) Liquid-water specific humidity at $t = 6$.
- 2) Convergence of bulk properties.



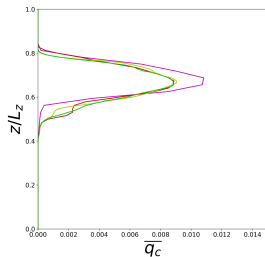
Vorticity converges slowly (influence of initial conditions?)
Much higher vorticity in MONC simulation (grey line: reference).



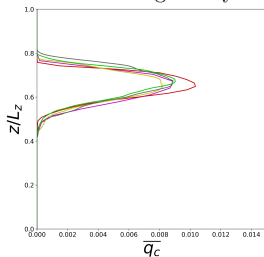
Top: liquid water at $t = 6$.

Bottom: change in total water content over the simulation.

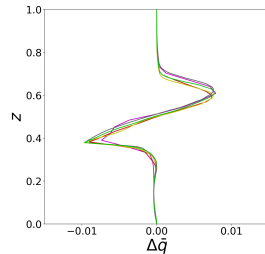
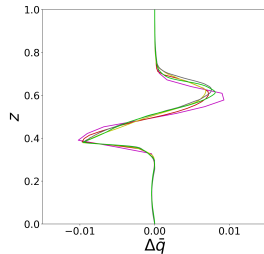
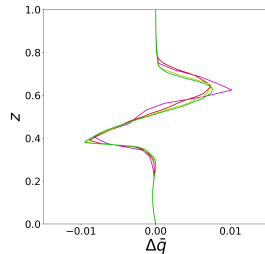
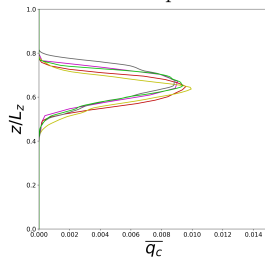
MPIC



MONC Smagorinsky

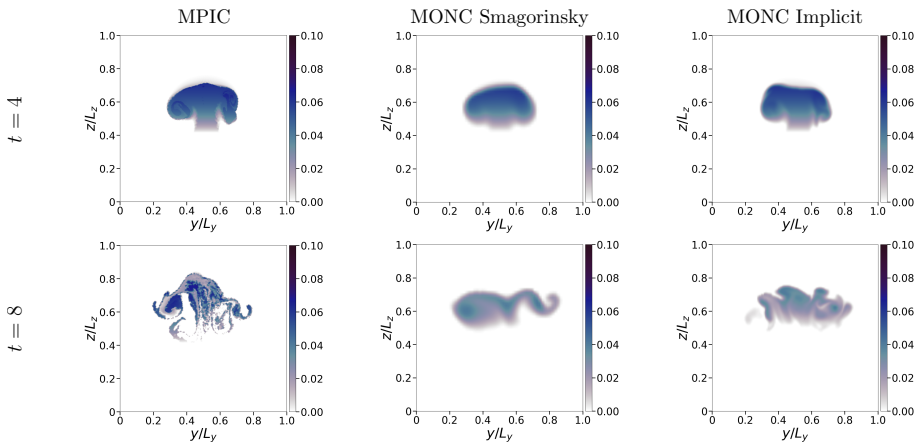


MONC Implicit



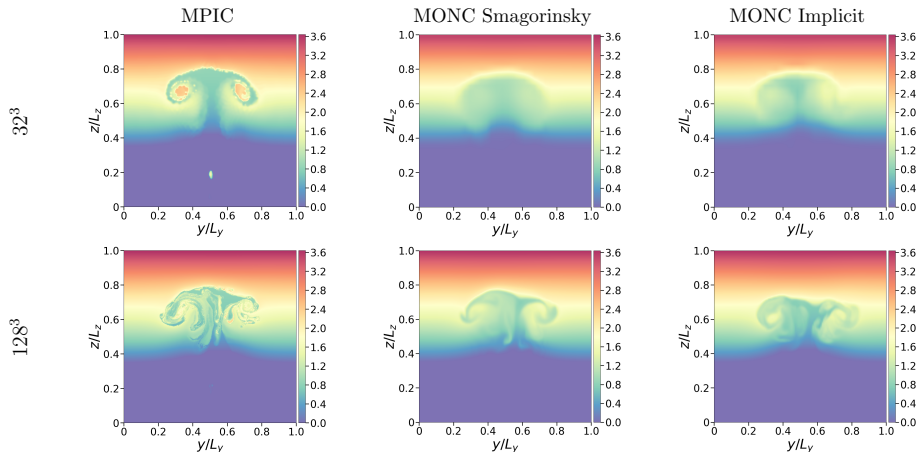
Time evolution of a marginally resolved simulation

Liquid water field: smooth in MONC, detailed in MPIC.



Time evolution of a marginally resolved simulation

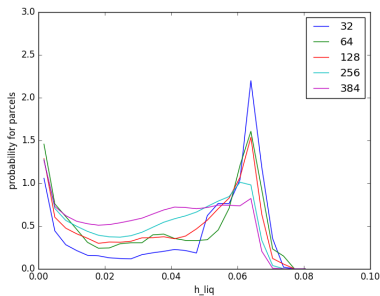
Relatively undiluted region in vortex ring at low resolution (MPIC).



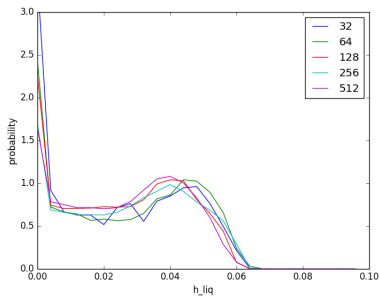
Time evolution of a marginally resolved simulation

Liquid water PDF: MONC has better convergence here.
MPIC calculated directly from parcels (this matters!)

MPIC



MONC



Is the resolved flow providing rapid enough mixing in MPIC? Do the unresolved scales play a crucial role?

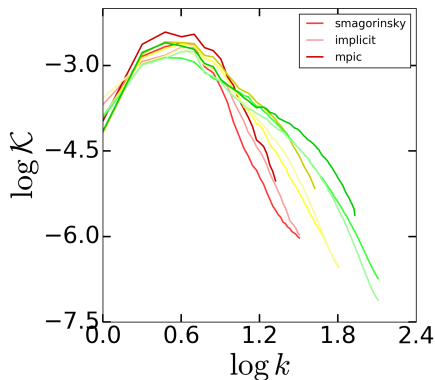
Spectra

MPIC effectively doubles resolution!

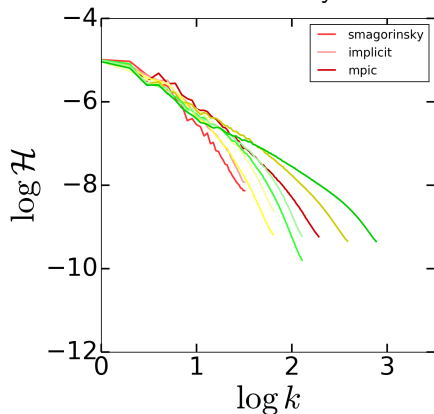
Specific humidity spectra show a lot of detail (realistic?) on fine scales

Based on 64^3 , 128^3 , 256^3 grid points.

Kinetic energy



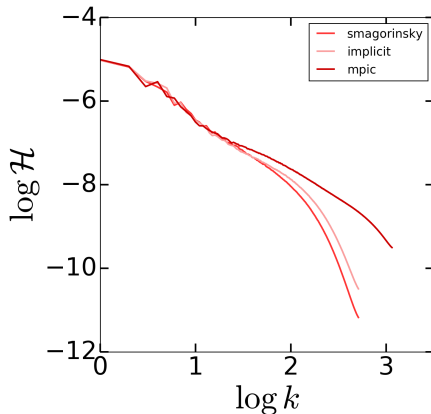
humidity



Spectra of humidity, reference simulations

384³ MPIC and 1024³ MONC.

Small scale structures undamped in MPIC.

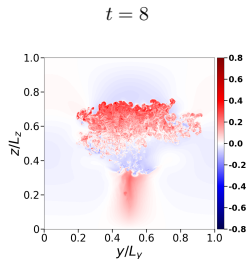
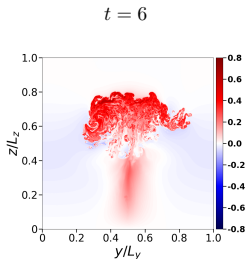
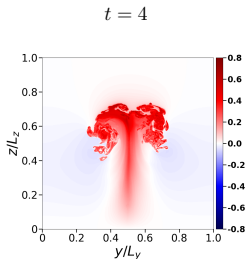


Current work: box counting and fractal dimension!

Example of Lagrangian diagnostics

Determine displacement from initial position for each parcel.

MPIC detailed



- **Massive parallelism**: project with EPCC.
- More flexible **boundary conditions**:
 - Mean wind profile.
 - Surface fluxes (heat, moisture, momentum). Vorticity damping?
 - Inhomogeneous surface values.
- Further work on **marginally resolved and subgrid-scale dynamics**.
Explicit representation of stretching, following McKiver and Dritschel (2003)? Minimize spectral filtering (first results promising)?
- Realistic **thermodynamics** and **microphysics**: proposed PhD project on prognostic droplet-size distribution, EPSRC proposal. From idealised to atmospheric model.
- Exploitation of **vorticity diagnostics** and **Lagrangian analysis** (with David Dritschel and Sam Wallace)

Parallelism

- Currently OpenMP. HPC trend to **large distributed memory systems**.
- Much more **parcel data** than **grid data**.
- Parcel data: **local communication**. Use derived types?
- Solver: requires global communication, but **efficient algorithms** exist.

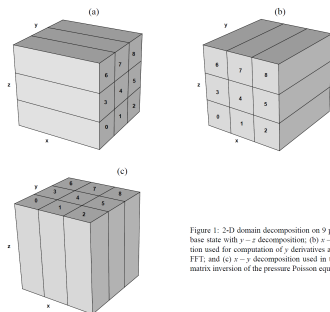


Figure 1: 2-D domain decomposition on 9 processors: (a) base state with $y-z$ decomposition; (b) $x-z$ decomposition used for computation of y derivatives and 2-D planar FFT; and (c) $x-y$ decomposition used in the tridiagonal matrix inversion of the pressure Poisson equation.

FFT Domain decompositions. Peter Sullivan, NCAR

A fully Lagrangian dynamical core for the Met Office NERC Cloud Model

St Andrews, Leeds, EPCC (Michèle Weiland, Nick Brown, Gordon Gibb)

Ideas:

- Harness **MONC's parallelism**.
- Poisson solver available. **FFT**-based solver hard to beat with limited grid data, but iterative solver also present.
- Approach: **domain decomposition**, number of parcels per subdomain will vary (simplicity versus optimal load balancing).
- **Lagrangian diagnostics** can feed back into standard MONC.
- **Component testing** using simplified code.

Objectives

- (1) Introduce the Lagrangian dynamical core into the **MONC framework**: rewrite as independent components.
- (2) Maintain the existing OpenMP in conjunction with **MPI** for the dynamical core: halo-exchanges and solver.
- (3) Introduce parcel-based **IO** in the MONC framework: MONC's IO server fully asynchronous.
- (4) **Modernise** MPIC code base: derived types, dynamic allocation.



- First use of this type of model in atmospheric community.
- Massively parallel MPIC will make it more attractive for **other problems**, e.g. ocean mixed layer, idealised convection, density-laden flows.
- MPIC approach seems very well suited to **mixed-mode** parallelism.
- **Alternative approaches** will be available for MONC community.
- Lagrangian diagnostics currently **lacking in MONC**.
- **BSD** license.



Conclusions and future work

MPIC's **parcel-based representation** of variables has several **advantages**:

- (1) it allows an *explicit* subgrid representation;
- (2) it provides a velocity field which is *undamped* by numerical diffusion all the way down to the grid scale;
- (3) it does away with the need for eddy viscosity parametrisations and, in their place, **it provides for a natural subgrid parcel mixing**;
- (4) it is *exactly conservative* — there can be no net loss or gain of any theoretically conserved attribute; and
- (5) **it dispenses with the need to have separate equations for each conserved parcel attribute** — attributes are simply labels carried by each parcel. **Moreover, this advantage increases** as more attributes are added, such as the distributions of microphysical properties, chemical composition and aerosol loading.

Conclusions and future work

Numerical tests demonstrate the **robustness** of the MPIC method as well as its ability to capture fine detail **using only modest underlying grid resolutions**.

The MPIC method is shown to **compare well** with a convection-permitting research model (MONC) run on a grid **at least twice as fine** in each coordinate direction.

Convergence of mixing in MPIC (parcel splitting and removal) **remains an issue** (i.e. for distributions of condensed water).

Many extensions are possible. An immediately viable one is to study **sub-mesoscale ocean dynamics**, particularly near the surface — no condensation is then required. This is a major topic in oceanography (**Gula, Molemaker & McWilliams, 2014**).



Discussion points: methods

Experiences with monotonically integrated LES

Boundary conditions: law of the wall, roughness, transfer of momentum

Anisotropic subgrid models (walls, stratification)

Poorly resolved LES: parametrised versus explicit dynamics

Closures: Smagorinsky, TKE, TKE+scalar variance, HOC

Time-stepping methods and advection schemes

Numerical tests

Testbeds settings: long-term LES

Experiences with topography in LES